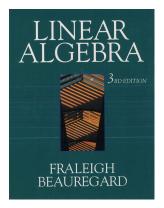
## Linear Algebra

#### Chapter 6: Orthogonality Section 6.1. Projections—Proofs of Theorems



# Table of contents

- Page 336 number 4
- Page 336 number 10
- 3 Theorem 6.1. Properties of  $W^{\perp}$
- Page 336 number 20(b)
- 5 Page 335 Example 6
- 6 Page 337 number 26
- Page 337 number 28

**Page 336 number 4.** Find the projection of [1, 2, 1] on the line with parametric equation x = 3t, y = t, z = 2t in  $\mathbb{R}^3$ .

**Solution.** A line is a translation of a one-dimensional subspace and is of the form  $\vec{x} = t\vec{d} + \vec{a}$  where  $\vec{d}$  is the direction vector and  $\vec{a}$  is a translation vector (see Section 2.5, "Lines, Planes, and Other Flats"). Here,  $\vec{d} = [3, 1, 2]$  and  $\vec{a} = [0, 0, 0]$  so, in fact, the line is not translated and so is a subspace spanned by  $\vec{d} = [3, 1, 2]$ .

**Page 336 number 4.** Find the projection of [1, 2, 1] on the line with parametric equation x = 3t, y = t, z = 2t in  $\mathbb{R}^3$ .

**Solution.** A line is a translation of a one-dimensional subspace and is of the form  $\vec{x} = t\vec{d} + \vec{a}$  where  $\vec{d}$  is the direction vector and  $\vec{a}$  is a translation vector (see Section 2.5, "Lines, Planes, and Other Flats"). Here,  $\vec{d} = [3, 1, 2]$  and  $\vec{a} = [0, 0, 0]$  so, in fact, the line is not translated and so is a subspace spanned by  $\vec{d} = [3, 1, 2]$ . So we apply the previous definition to get the projection  $\vec{p}$  of  $\vec{b} = [1, 2, 1]$  on  $\operatorname{sp}(\vec{d})$ :

$$\vec{p} = \operatorname{proj}_{\vec{d}}(\vec{b}) = \frac{\vec{b} \cdot \vec{d}}{\vec{d} \cdot \vec{d}} \vec{d} = \frac{[1, 2, 1] \cdot [3, 1, 2]}{[3, 1, 2]} [3, 1, 2]$$
$$= \frac{(1)(3) + (2)(1) + (1)(2)}{3^2 + 1^2 + 2^2} [3, 1, 2] = \frac{7}{14} [3, 1, 2] = \boxed{[3/2, 1/2, 1]}.$$

**Page 336 number 4.** Find the projection of [1, 2, 1] on the line with parametric equation x = 3t, y = t, z = 2t in  $\mathbb{R}^3$ .

**Solution.** A line is a translation of a one-dimensional subspace and is of the form  $\vec{x} = t\vec{d} + \vec{a}$  where  $\vec{d}$  is the direction vector and  $\vec{a}$  is a translation vector (see Section 2.5, "Lines, Planes, and Other Flats"). Here,  $\vec{d} = [3, 1, 2]$  and  $\vec{a} = [0, 0, 0]$  so, in fact, the line is not translated and so is a subspace spanned by  $\vec{d} = [3, 1, 2]$ . So we apply the previous definition to get the projection  $\vec{p}$  of  $\vec{b} = [1, 2, 1]$  on  $sp(\vec{d})$ :

$$\vec{p} = \operatorname{proj}_{\vec{d}}(\vec{b}) = \frac{\vec{b} \cdot \vec{d}}{\vec{d} \cdot \vec{d}} \vec{d} = \frac{[1, 2, 1] \cdot [3, 1, 2]}{[3, 1, 2] \cdot [3, 1, 2]} [3, 1, 2]$$
$$= \frac{(1)(3) + (2)(1) + (1)(2)}{3^2 + 1^2 + 2^2} [3, 1, 2] = \frac{7}{14} [3, 1, 2] = \boxed{[3/2, 1/2, 1]}.$$

# **Page 336 number 10.** Find the orthogonal complement of the plane 2x + y + 3z = 0 in $\mathbb{R}^3$ .

**Solution.** A plane is a translation of a two-dimensional space of the form  $\vec{x} = t_1 \vec{d_1} + t_2 \vec{d_2} + \vec{a}$  where  $\vec{d_1}$  and  $\vec{d_2}$  form a basis for the two-dimensional space and  $\vec{a}$  is a translation vector (see Section 2.5, "Lines, Planes, and Other Flats"). Here, we can take  $\vec{a} = \vec{0}$  so that the plane is not translated and is in fact a subspace of  $\mathbb{R}^3$ . So we just need a basis for the subspace.

**Page 336 number 10.** Find the orthogonal complement of the plane 2x + y + 3z = 0 in  $\mathbb{R}^3$ .

**Solution.** A plane is a translation of a two-dimensional space of the form  $\vec{x} = t_1 \vec{d_1} + t_2 \vec{d_2} + \vec{a}$  where  $\vec{d_1}$  and  $\vec{d_2}$  form a basis for the two-dimensional space and  $\vec{a}$  is a translation vector (see Section 2.5, "Lines, Planes, and Other Flats"). Here, we can take  $\vec{a} = \vec{0}$  so that the plane is not translated and is in fact a subspace of  $\mathbb{R}^3$ . So we just need a basis for the subspace. We pick two linearly independent vectors in the subspace, say  $\vec{d}_1 = [1, -2, 0]$  and  $\vec{d}_2 = [0, -3, 1]$  (though there are infinitely many such choices). Then using the technique described above, we take  $A = \begin{vmatrix} 1 & -2 & 0 \\ 0 & -3 & 1 \end{vmatrix}$  and find the nullspace of A by considering the system of equations  $A\vec{x} = \vec{0}$  (see Note 6.1.A):

**Page 336 number 10.** Find the orthogonal complement of the plane 2x + y + 3z = 0 in  $\mathbb{R}^3$ .

**Solution.** A plane is a translation of a two-dimensional space of the form  $\vec{x} = t_1 \vec{d_1} + t_2 \vec{d_2} + \vec{a}$  where  $\vec{d_1}$  and  $\vec{d_2}$  form a basis for the two-dimensional space and  $\vec{a}$  is a translation vector (see Section 2.5, "Lines, Planes, and Other Flats"). Here, we can take  $\vec{a} = \vec{0}$  so that the plane is not translated and is in fact a subspace of  $\mathbb{R}^3$ . So we just need a basis for the subspace. We pick two linearly independent vectors in the subspace, say  $\vec{d}_1 = [1, -2, 0]$  and  $\vec{d}_2 = [0, -3, 1]$  (though there are infinitely many such choices). Then using the technique described above, we take  $A = \begin{bmatrix} 1 & -2 & 0 \\ 0 & -3 & 1 \end{bmatrix}$  and find the nullspace of A by considering the system of equations  $A\vec{x} = \vec{0}$  (see Note 6.1.A):

# Page 336 number 10 (continued)

#### Solution (continued).

$$\begin{bmatrix} A \mid \vec{0} \end{bmatrix} = \begin{bmatrix} 1 & -2 & 0 \mid 0 \\ 0 & -3 & 1 \mid 0 \end{bmatrix} \stackrel{R_1 \to R_1 - (2/3)R_2}{\frown} \begin{bmatrix} 1 & 0 & -2/3 \mid 0 \\ 0 & -3 & 1 \mid 0 \end{bmatrix}$$
$$\stackrel{R_2 \to R_2/(-3)}{\frown} \begin{bmatrix} 1 & 0 & -2/3 \mid 0 \\ 0 & 1 & -1/3 \mid 0 \end{bmatrix}.$$

So we have

or with  $x_3 = 3t$  as a free variable,  $x_1 = 2t$ ,  $x_2 = t$ , and  $x_3 = 3t$ .

()

# Page 336 number 10 (continued)

Solution (continued).

$$\begin{bmatrix} A \mid \vec{0} \end{bmatrix} = \begin{bmatrix} 1 & -2 & 0 \mid 0 \\ 0 & -3 & 1 \mid 0 \end{bmatrix} \stackrel{R_1 \to R_1 - (2/3)R_2}{\frown} \begin{bmatrix} 1 & 0 & -2/3 \mid 0 \\ 0 & -3 & 1 \mid 0 \end{bmatrix}$$
$$\stackrel{R_2 \to R_2/(-3)}{\frown} \begin{bmatrix} 1 & 0 & -2/3 \mid 0 \\ 0 & 1 & -1/3 \mid 0 \end{bmatrix}.$$

So we have

or with  $x_3 = 3t$  as a free variable,  $x_1 = 2t$ ,  $x_2 = t$ , and  $x_3 = 3t$ . So  $W^{\perp}$  is the nullspace of A:  $W^{\perp} = sp([2, 1, 3])$ .  $\Box$ 

()

# Page 336 number 10 (continued)

Solution (continued).

$$\begin{bmatrix} A \mid \vec{0} \end{bmatrix} = \begin{bmatrix} 1 & -2 & 0 \mid 0 \\ 0 & -3 & 1 \mid 0 \end{bmatrix} \stackrel{R_1 \to R_1 - (2/3)R_2}{\frown} \begin{bmatrix} 1 & 0 & -2/3 \mid 0 \\ 0 & -3 & 1 \mid 0 \end{bmatrix}$$
$$\stackrel{R_2 \to R_2/(-3)}{\frown} \begin{bmatrix} 1 & 0 & -2/3 \mid 0 \\ 0 & 1 & -1/3 \mid 0 \end{bmatrix}.$$

So we have

or with  $x_3 = 3t$  as a free variable,  $x_1 = 2t$ ,  $x_2 = t$ , and  $x_3 = 3t$ . So  $W^{\perp}$  is the nullspace of A:  $W^{\perp} = sp([2, 1, 3])$ .  $\Box$ 

#### Theorem 6.1

#### **Theorem 6.1.** Properties of $W^{\perp}$ .

The orthogonal complement  $W^{\perp}$  of a subspace W of  $\mathbb{R}^n$  has the following properties:

**Proof.** Let dim(W) = k, and let { $\vec{v_1}, \vec{v_2}, \ldots, \vec{v_k}$ } be a basis for W. Let A be the  $k \times n$  matrix having  $\vec{v_i}$  as its *i*th row vector for  $i = 1, 2, \ldots, k$ .

### Theorem 6.1

#### Theorem 6.1. Properties of $W^{\perp}$ .

The orthogonal complement  $W^{\perp}$  of a subspace W of  $\mathbb{R}^n$  has the following properties:

**Proof.** Let dim(W) = k, and let { $\vec{v_1}, \vec{v_2}, \ldots, \vec{v_k}$ } be a basis for W. Let A be the  $k \times n$  matrix having  $\vec{v_i}$  as its *i*th row vector for  $i = 1, 2, \ldots, k$ .

Property (1) follows from the fact that  $W^{\perp}$  is the nullspace of matrix A, by Note 6.1.A, and therefore is a subspace of  $\mathbb{R}^n$ .

## Theorem 6.1

#### Theorem 6.1. Properties of $W^{\perp}$ .

The orthogonal complement  $W^{\perp}$  of a subspace W of  $\mathbb{R}^{n}$  has the following properties:

**Proof.** Let dim(W) = k, and let { $\vec{v_1}, \vec{v_2}, \ldots, \vec{v_k}$ } be a basis for W. Let A be the  $k \times n$  matrix having  $\vec{v_i}$  as its *i*th row vector for  $i = 1, 2, \ldots, k$ .

Property (1) follows from the fact that  $W^{\perp}$  is the nullspace of matrix A, by Note 6.1.A, and therefore is a subspace of  $\mathbb{R}^n$ .

# Theorem 6.1 (continued 1)

Proof (continued). For Property 2, consider the rank equation of A:

 $\operatorname{rank}(A) + \operatorname{nullity}(A) = n.$ 

Since dim(W) = rank(A) and since  $W^{\perp}$  is the nullspace of A, then dim( $W^{\perp}$ ) =  $n - \dim(W)$ .

For Property 3, we have by Property 1 that  $W^{\perp}$  is a subspace of  $\mathbb{R}^n$ . By Property 2 we have

$$\dim(W^{\perp})^{\perp} = n - \dim(W^{\perp}) = n - (n - k) = k.$$

# Theorem 6.1 (continued 1)

**Proof (continued).** For Property 2, consider the rank equation of A:

 $\operatorname{rank}(A) + \operatorname{nullity}(A) = n.$ 

Since dim(W) = rank(A) and since  $W^{\perp}$  is the nullspace of A, then dim( $W^{\perp}$ ) =  $n - \dim(W)$ .

For Property 3, we have by Property 1 that  $W^{\perp}$  is a subspace of  $\mathbb{R}^n$ . By Property 2 we have

$$\dim(W^{\perp})^{\perp} = n - \dim(W^{\perp}) = n - (n - k) = k.$$

Since very vector in W is orthogonal to subspace  $W^{\perp}$  then W is a subspace of  $(W^{\perp})^{\perp}$   $((W^{\perp})^{\perp}$  is a subspace of  $\mathbb{R}^n$  by two applications of Property 1). Since W and  $(W^{\perp})^{\perp}$  have the same dimension then by Exercise 2.1.38, W must be equal to  $(W^{\perp})^{\perp}$ .

# Theorem 6.1 (continued 1)

Proof (continued). For Property 2, consider the rank equation of A:

 $\operatorname{rank}(A) + \operatorname{nullity}(A) = n.$ 

Since dim(W) = rank(A) and since  $W^{\perp}$  is the nullspace of A, then dim( $W^{\perp}$ ) =  $n - \dim(W)$ .

For Property 3, we have by Property 1 that  $W^{\perp}$  is a subspace of  $\mathbb{R}^n$ . By Property 2 we have

$$\dim(W^{\perp})^{\perp}=n-\dim(W^{\perp})=n-(n-k)=k.$$

Since very vector in W is orthogonal to subspace  $W^{\perp}$  then W is a subspace of  $(W^{\perp})^{\perp}$   $((W^{\perp})^{\perp}$  is a subspace of  $\mathbb{R}^n$  by two applications of Property 1). Since W and  $(W^{\perp})^{\perp}$  have the same dimension then by Exercise 2.1.38, W must be equal to  $(W^{\perp})^{\perp}$ .

# Theorem 6.1 (continued 2)

**Proof (continued).** For Property 4, let  $\{\vec{v}_{k+1}, \vec{v}_{k+2}, \dots, \vec{v}_n\}$  be a basis for n - k dimensional (by Property 2) subspace  $W^{\perp}$ . We now show that

$$\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\} \cup \{\vec{v}_{k+1}, \vec{v}_{k+2}, \dots, \vec{v}_n\} = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$$

is a basis for  $\mathbb{R}^n$ . Consider the linear combination

$$r_1\vec{v}_1 + r_2\vec{v}_2 + \dots + r_k\vec{v}_k + s_{k+1}\vec{v}_{k+1} + s_{k+2}\vec{v}_{k+2} + \dots + s_n\vec{v}_n = \vec{0}. \quad (*)$$

This equation implies

$$r_1\vec{v}_1 + r_2\vec{v}_2 + \dots + r_k\vec{v}_k = -s_{k+1}\vec{v}_{k+1} - s_{k+2}\vec{v}_{k+2} - \dots - s_n\vec{v}_n.$$

# Theorem 6.1 (continued 2)

**Proof (continued).** For Property 4, let  $\{\vec{v}_{k+1}, \vec{v}_{k+2}, \dots, \vec{v}_n\}$  be a basis for n - k dimensional (by Property 2) subspace  $W^{\perp}$ . We now show that

$$\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\} \cup \{\vec{v}_{k+1}, \vec{v}_{k+2}, \dots, \vec{v}_n\} = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$$

is a basis for  $\mathbb{R}^n$ . Consider the linear combination

$$r_1\vec{v}_1 + r_2\vec{v}_2 + \dots + r_k\vec{v}_k + s_{k+1}\vec{v}_{k+1} + s_{k+2}\vec{v}_{k+2} + \dots + s_n\vec{v}_n = \vec{0}. \quad (*)$$

This equation implies

$$r_1 \vec{v}_1 + r_2 \vec{v}_2 + \dots + r_k \vec{v}_k = -s_{k+1} \vec{v}_{k+1} - s_{k+2} \vec{v}_{k+2} - \dots - s_n \vec{v}_n.$$

# Theorem 6.1 (continued 3)

**Proof (continued).** Notice that the vector on the left hand side of this equation is in W and the vector on the right hand side is in  $W^{\perp}$ . But both sides of the equation represent the same vector (d'uh, it's an equation!) so both sides of the equation represent a vector in both W and  $W^{\perp}$ . So this vector must be orthogonal to itself. The only vector orthogonal to itself is  $\vec{0}$  (since  $0 = \vec{v} \cdot \vec{v} = \|\vec{v}\|^2$  implies  $\vec{v} = \vec{0}$ ). Since the vectors  $\vec{v}_1, \vec{v}_2, \ldots, \vec{v}_k$  are linearly independent and  $r_1\vec{v}_1 + r_2\vec{v}_2 + \cdots + r_k\vec{v}_k = \vec{0}$  then we must have  $r_1 = r_2 = \cdots r_k = 0$ . Similarly,  $\vec{v}_{k+1}, \vec{v}_{k+2}, \ldots, \vec{v}_n$  are linearly independent and  $s_{k+1}\vec{v}_{k+1} + s_{k+2}\vec{v}_{k+2} + \cdots + s_n\vec{v}_n = \vec{0}$  implies  $s_{k+1} = s_{k+2} = \cdots = s_n = 0$ .

# Theorem 6.1 (continued 3)

**Proof (continued).** Notice that the vector on the left hand side of this equation is in W and the vector on the right hand side is in  $W^{\perp}$ . But both sides of the equation represent the same vector (d'uh, it's an equation!) so both sides of the equation represent a vector in both W and  $W^{\perp}$ . So this vector must be orthogonal to itself. The only vector orthogonal to itself is  $\vec{0}$  (since  $0 = \vec{v} \cdot \vec{v} = \|\vec{v}\|^2$  implies  $\vec{v} = \vec{0}$ ). Since the vectors  $\vec{v}_1, \vec{v}_2, \ldots, \vec{v}_k$  are linearly independent and  $r_1 \vec{v}_1 + r_2 \vec{v}_2 + \cdots + r_k \vec{v}_k = \vec{0}$  then we must have  $r_1 = r_2 = \cdots r_k = 0$ . Similarly,  $\vec{v}_{k+1}, \vec{v}_{k+2}, \ldots, \vec{v}_n$  are linearly independent and  $s_{k+1}\vec{v}_{k+1} + s_{k+2}\vec{v}_{k+2} + \dots + s_n\vec{v}_n = \vec{0}$  implies  $s_{k+1} = s_{k+2} = \dots = s_n = 0$ . From equation (\*), we see that  $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$  is a linearly independent set. Since the set contains n linearly independent vectors in  $\mathbb{R}^n$  then dim $(sp(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n)) = n$  and so by Exercise 2.1.38,  $\operatorname{sp}(\vec{v}_1, \vec{v}_2, \ldots, \vec{v}_n) = \mathbb{R}^n$  and so  $\{\vec{v}_1, \vec{v}_2, \ldots, \vec{v}_n\}$  is a basis for  $\mathbb{R}^n$ .

9 / 17

# Theorem 6.1 (continued 3)

**Proof (continued).** Notice that the vector on the left hand side of this equation is in W and the vector on the right hand side is in  $W^{\perp}$ . But both sides of the equation represent the same vector (d'uh, it's an equation!) so both sides of the equation represent a vector in both W and  $W^{\perp}$ . So this vector must be orthogonal to itself. The only vector orthogonal to itself is  $\vec{0}$  (since  $0 = \vec{v} \cdot \vec{v} = \|\vec{v}\|^2$  implies  $\vec{v} = \vec{0}$ ). Since the vectors  $\vec{v}_1, \vec{v}_2, \ldots, \vec{v}_k$  are linearly independent and  $r_1 \vec{v}_1 + r_2 \vec{v}_2 + \cdots + r_k \vec{v}_k = \vec{0}$  then we must have  $r_1 = r_2 = \cdots r_k = 0$ . Similarly,  $\vec{v}_{k+1}, \vec{v}_{k+2}, \ldots, \vec{v}_n$  are linearly independent and  $s_{k+1}\vec{v}_{k+1} + s_{k+2}\vec{v}_{k+2} + \dots + s_n\vec{v}_n = \vec{0}$  implies  $s_{k+1} = s_{k+2} = \dots = s_n = 0$ . From equation (\*), we see that  $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$  is a linearly independent set. Since the set contains *n* linearly independent vectors in  $\mathbb{R}^n$  then dim $(sp(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n)) = n$  and so by Exercise 2.1.38,  $\operatorname{sp}(\vec{v}_1, \vec{v}_2, \ldots, \vec{v}_n) = \mathbb{R}^n$  and so  $\{\vec{v}_1, \vec{v}_2, \ldots, \vec{v}_n\}$  is a basis for  $\mathbb{R}^n$ .

# Theorem 6.1 (continued 4)

**Proof (continued).** So each  $\vec{b} \in \mathbb{R}^n$  can be written as  $\vec{b} = (r_1\vec{v}_1 + r_2\vec{v}_2 + \dots + r_k\vec{v}_k) + (s_{k+1}\vec{v}_{k+1} + s_{k+2}\vec{v}_{k+2} + \dots + s_n\vec{v}_n)$ , where  $r_1\vec{v}_1 + r_2\vec{v}_2 + \dots + r_k\vec{v}_k \in W$  and  $s_{k+1}\vec{v}_{k+1} + s_{k+2}\vec{v}_{k+2} + \dots + s_n\vec{v}_n \in W^{\perp}$ , for unique  $r_1, r_2, \dots, r_k, s_{k+1}, s_{k+2}, \dots, s_n$  (by Definition 1.17, "Basis for a Subspace"). So any  $\vec{b} \in \mathbb{R}^n$  can be expressed in the form  $\vec{b} = \vec{b}_W + \vec{b}_{W^{\perp}}$ where  $\vec{b}_W \in W$  and  $\vec{b}_{W^{\perp}} \in W^{\perp}$ . Since each vector in  $\mathbb{R}^n$  is a unique linear combination of  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ , then the choice of  $\vec{b}_W$  and  $\vec{b}_{W^{\perp}}$  are unique.

# Theorem 6.1 (continued 4)

**Proof (continued).** So each  $\vec{b} \in \mathbb{R}^n$  can be written as  $\vec{b} = (r_1\vec{v}_1 + r_2\vec{v}_2 + \dots + r_k\vec{v}_k) + (s_{k+1}\vec{v}_{k+1} + s_{k+2}\vec{v}_{k+2} + \dots + s_n\vec{v}_n)$ , where  $r_1\vec{v}_1 + r_2\vec{v}_2 + \dots + r_k\vec{v}_k \in W$  and  $s_{k+1}\vec{v}_{k+1} + s_{k+2}\vec{v}_{k+2} + \dots + s_n\vec{v}_n \in W^{\perp}$ , for unique  $r_1, r_2, \dots, r_k, s_{k+1}, s_{k+2}, \dots, s_n$  (by Definition 1.17, "Basis for a Subspace"). So any  $\vec{b} \in \mathbb{R}^n$  can be expressed in the form  $\vec{b} = \vec{b}_W + \vec{b}_{W^{\perp}}$ where  $\vec{b}_W \in W$  and  $\vec{b}_{W^{\perp}} \in W^{\perp}$ . Since each vector in  $\mathbb{R}^n$  is a unique linear combination of  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ , then the choice of  $\vec{b}_W$  and  $\vec{b}_{W^{\perp}}$  are unique.

**Page 336 number 20(b).** Find the projection of  $\vec{b} = [-2, 1, 3, -5]$  on to the subspace  $W = sp(\hat{e}_1, \hat{e}_4)$  in  $\mathbb{R}^4$ .

**Solution.** We are given a basis for  $W = sp(\hat{e}_1, \hat{e}_4)$ , namely  $\{\hat{e}_1, \hat{e}_4\}$ . Certainly a basis for  $W^{\perp}$  is given by  $\{\hat{e}_2, \hat{e}_3\}$ .

**Page 336 number 20(b).** Find the projection of  $\vec{b} = [-2, 1, 3, -5]$  on to the subspace  $W = sp(\hat{e}_1, \hat{e}_4)$  in  $\mathbb{R}^4$ .

**Solution.** We are given a basis for  $W = sp(\hat{e}_1, \hat{e}_4)$ , namely  $\{\hat{e}_1, \hat{e}_4\}$ . Certainly a basis for  $W^{\perp}$  is given by  $\{\hat{e}_2, \hat{e}_3\}$ . So we take the ordered basis  $\{\hat{e}_1, \hat{e}_4, \hat{e}_2, \hat{e}_3\}$  of  $\mathbb{R}^4$  and we have  $\vec{b} = -2\hat{e}_1 - 5\hat{e}_4 + 1\hat{e}_2 + 3\hat{e}_3$  (and so the coordinate vector  $\vec{r}$  of  $\vec{b}$  relative to the ordered basis  $\{\hat{e}_1, \hat{e}_4, \hat{e}_2, \hat{e}_3\}$  is  $\vec{r} = [-2, -5, 1, 3]$ ).

**Page 336 number 20(b).** Find the projection of  $\vec{b} = [-2, 1, 3, -5]$  on to the subspace  $W = sp(\hat{e}_1, \hat{e}_4)$  in  $\mathbb{R}^4$ .

**Solution.** We are given a basis for  $W = sp(\hat{e}_1, \hat{e}_4)$ , namely  $\{\hat{e}_1, \hat{e}_4\}$ . Certainly a basis for  $W^{\perp}$  is given by  $\{\hat{e}_2, \hat{e}_3\}$ . So we take the ordered basis  $\{\hat{e}_1, \hat{e}_4, \hat{e}_2, \hat{e}_3\}$  of  $\mathbb{R}^4$  and we have  $\vec{b} = -2\hat{e}_1 - 5\hat{e}_4 + 1\hat{e}_2 + 3\hat{e}_3$  (and so the coordinate vector  $\vec{r}$  of  $\vec{b}$  relative to the ordered basis  $\{\hat{e}_1, \hat{e}_4, \hat{e}_2, \hat{e}_3\}$  is  $\vec{r} = [-2, -5, 1, 3]$ ). Then by the Note 6.1.B, the projection of  $\vec{b}$  on to W is

$$\vec{b}_W = \operatorname{proj}_W(\vec{b}) = r_1 \hat{e}_1 + r_2 \hat{e}_4 = -2[1, 0, 0, 0] - 5[0, 0, 0, 1] = [-2, 0, 0, -5].$$

**Page 336 number 20(b).** Find the projection of  $\vec{b} = [-2, 1, 3, -5]$  on to the subspace  $W = sp(\hat{e}_1, \hat{e}_4)$  in  $\mathbb{R}^4$ .

**Solution.** We are given a basis for  $W = sp(\hat{e}_1, \hat{e}_4)$ , namely  $\{\hat{e}_1, \hat{e}_4\}$ . Certainly a basis for  $W^{\perp}$  is given by  $\{\hat{e}_2, \hat{e}_3\}$ . So we take the ordered basis  $\{\hat{e}_1, \hat{e}_4, \hat{e}_2, \hat{e}_3\}$  of  $\mathbb{R}^4$  and we have  $\vec{b} = -2\hat{e}_1 - 5\hat{e}_4 + 1\hat{e}_2 + 3\hat{e}_3$  (and so the coordinate vector  $\vec{r}$  of  $\vec{b}$  relative to the ordered basis  $\{\hat{e}_1, \hat{e}_4, \hat{e}_2, \hat{e}_3\}$  is  $\vec{r} = [-2, -5, 1, 3]$ ). Then by the Note 6.1.B, the projection of  $\vec{b}$  on to W is

$$\vec{b}_W = \operatorname{proj}_W(\vec{b}) = r_1 \hat{e}_1 + r_2 \hat{e}_4 = -2[1, 0, 0, 0] - 5[0, 0, 0, 1] =$$
[-2,0,0,-5].

## Page 335 Example 6

**Page 335 Example 6.** Consider the inner product space  $\mathcal{P}_{[0,1]}$  of all polynomial functions defined on the interval [0,1] with inner product

$$\langle p(x), q(x) \rangle = \int_0^1 p(x)q(x) \, dx.$$

Find the projection of f(x) = x on sp(1) and then find the projection of x on sp(1)<sup> $\perp$ </sup>.

**Solution.** We follow the definition of the projection  $\vec{p}$  of  $\vec{b}$  on  $\text{sp}(\vec{a})$  in  $\mathbb{R}^n$ ,  $\vec{p} = \text{proj}_{\vec{a}}(\vec{b}) = \frac{\vec{b} \cdot \vec{a}}{\vec{a} \cdot \vec{a}} \vec{a}$ , but instead of dot products in  $\mathbb{R}^n$  we use the inner product in  $\mathcal{P}_{[0,1]}$ .

## Page 335 Example 6

**Page 335 Example 6.** Consider the inner product space  $\mathcal{P}_{[0,1]}$  of all polynomial functions defined on the interval [0,1] with inner product

$$\langle p(x), q(x) \rangle = \int_0^1 p(x)q(x) \, dx.$$

Find the projection of f(x) = x on sp(1) and then find the projection of x on sp(1)<sup> $\perp$ </sup>.

**Solution.** We follow the definition of the projection  $\vec{p}$  of  $\vec{b}$  on  $\text{sp}(\vec{a})$  in  $\mathbb{R}^n$ ,  $\vec{p} = \text{proj}_{\vec{a}}(\vec{b}) = \frac{\vec{b} \cdot \vec{a}}{\vec{a} \cdot \vec{a}} \vec{a}$ , but instead of dot products in  $\mathbb{R}^n$  we use the inner product in  $\mathcal{P}_{[0,1]}$ . So the desired projection, with  $\vec{b} = x$  and  $\vec{a} = 1$ , is

$$\frac{\langle x,1\rangle}{\langle 1,1\rangle} 1 = \frac{\int_0^1 x \cdot 1 \, dx}{\int_0^1 1 \cdot 1 \, dx} 1 = \frac{(1/2)x^2|_0^1}{x|_0^1} 1 = \boxed{\frac{1}{2}}.$$

## Page 335 Example 6

**Page 335 Example 6.** Consider the inner product space  $\mathcal{P}_{[0,1]}$  of all polynomial functions defined on the interval [0,1] with inner product

$$\langle p(x), q(x) \rangle = \int_0^1 p(x)q(x) \, dx.$$

Find the projection of f(x) = x on sp(1) and then find the projection of x on sp(1)<sup> $\perp$ </sup>.

**Solution.** We follow the definition of the projection  $\vec{p}$  of  $\vec{b}$  on  $\text{sp}(\vec{a})$  in  $\mathbb{R}^n$ ,  $\vec{p} = \text{proj}_{\vec{a}}(\vec{b}) = \frac{\vec{b} \cdot \vec{a}}{\vec{a} \cdot \vec{a}} \vec{a}$ , but instead of dot products in  $\mathbb{R}^n$  we use the inner product in  $\mathcal{P}_{[0,1]}$ . So the desired projection, with  $\vec{b} = x$  and  $\vec{a} = 1$ , is

$$\frac{\langle x,1\rangle}{\langle 1,1\rangle} 1 = \frac{\int_0^1 x \cdot 1 \, dx}{\int_0^1 1 \cdot 1 \, dx} 1 = \frac{(1/2)x^2|_0^1}{x|_0^1} 1 = \boxed{\frac{1}{2}}.$$

# Page 335 Example 6 (continued)

**Page 335 Example 6.** Consider the inner product space  $\mathcal{P}_{[0,1]}$  of all polynomial functions defined on the interval [0,1] with inner product

$$\langle p(x), q(x) \rangle = \int_0^1 p(x)q(x) \, dx.$$

Find the projection of f(x) = x on sp(1) and then find the projection of x on sp(1)<sup> $\perp$ </sup>.

**Solution (continued).** Notice that with W = sp(1) then we have from Definition 6.2 that  $\vec{b} = \vec{b}_W + \vec{b}_{W^{\perp}}$  and we can find  $\vec{b}_{W^{\perp}}$  (where  $W^{\perp} = sp(1)^{\perp}$ ) as  $\vec{b}_{W^{\perp}} = \vec{b} - \vec{b}_W = x - 1/2$ .  $\Box$ 

#### **Page 337 number 26.** Let A be an $m \times n$ matrix.

- (a) Prove that the set W of row vectors  $\vec{x}$  in  $\mathbb{R}^m$  such that  $\vec{x}A = \vec{0}$  is a subspace of  $\mathbb{R}^m$ .
- (b) Prove that the subspace W in part (a) and the column space of A are orthogonal complements in  $\mathbb{R}^m$ .

**Proof.** (a) We use definition 1.16, "Subspace of  $\mathbb{R}^{n}$ ." Let  $W = \{\vec{x} \in \mathbb{R}^{m} \mid \vec{x}A = \vec{0}\}$ . We must check W for closure under vector addition and scalar multiplication. Let  $\vec{x}_1, \vec{x}_2 \in W$  and let r be a scalar.

#### **Page 337 number 26.** Let A be an $m \times n$ matrix.

- (a) Prove that the set W of row vectors  $\vec{x}$  in  $\mathbb{R}^m$  such that  $\vec{x}A = \vec{0}$  is a subspace of  $\mathbb{R}^m$ .
- (b) Prove that the subspace W in part (a) and the column space of A are orthogonal complements in  $\mathbb{R}^m$ .

**Proof.** (a) We use definition 1.16, "Subspace of  $\mathbb{R}^n$ ." Let  $W = \{\vec{x} \in \mathbb{R}^m \mid \vec{x}A = \vec{0}\}$ . We must check W for closure under vector addition and scalar multiplication. Let  $\vec{x}_1, \vec{x}_2 \in W$  and let r be a scalar. Then:

$$(\vec{x}_1 + \vec{x}_2)A = \vec{x}_1A + \vec{x}_2A$$
 by Theorem 1.3.A(10),

"Distribution Laws of Matrix Multiplication"

(here we treat 
$$\vec{x}$$
 as a matrix)

=  $\vec{0} + \vec{0}$  since  $\vec{x_1}, \vec{v_2} \in W$ 

= 0

#### **Page 337 number 26.** Let A be an $m \times n$ matrix.

- (a) Prove that the set W of row vectors  $\vec{x}$  in  $\mathbb{R}^m$  such that  $\vec{x}A = \vec{0}$  is a subspace of  $\mathbb{R}^m$ .
- (b) Prove that the subspace W in part (a) and the column space of A are orthogonal complements in  $\mathbb{R}^m$ .

**Proof.** (a) We use definition 1.16, "Subspace of  $\mathbb{R}^n$ ." Let  $W = \{\vec{x} \in \mathbb{R}^m \mid \vec{x}A = \vec{0}\}$ . We must check W for closure under vector addition and scalar multiplication. Let  $\vec{x}_1, \vec{x}_2 \in W$  and let r be a scalar. Then:

$$\begin{array}{rcl} (\vec{x}_1 + \vec{x}_2)A &=& \vec{x}_1A + \vec{x}_2A \text{ by Theorem 1.3.A(10),} \\ && \text{``Distribution Laws of Matrix Multiplication'} \\ && (\text{here we treat } \vec{x} \text{ as a matrix}) \\ &=& \vec{0} + \vec{0} \text{ since } \vec{x}_1, \vec{v}_2 \in W \\ &=& \vec{0}, \end{array}$$

#### Proof (continued). ... and

$$(r\vec{x_1})A = r(\vec{x_1}A)$$
 by Theorem 1.3.A(7), "Scalars Pull Through"  
=  $r\vec{0}$  since  $\vec{x_1} \in W$   
=  $\vec{0}$ .

So both  $\vec{x_1} + \vec{x_2} \in W$  and  $r\vec{x_1} \in W$ . That is, W is closed under vector addition and scalar multiplication. By Definition 1.16, W is a subspace of  $\mathbb{R}^m$ .

#### Proof (continued). ... and

$$(r\vec{x_1})A = r(\vec{x_1}A)$$
 by Theorem 1.3.A(7), "Scalars Pull Through"  
=  $r\vec{0}$  since  $\vec{x_1} \in W$   
=  $\vec{0}$ .

So both  $\vec{x_1} + \vec{x_2} \in W$  and  $r\vec{x_1} \in W$ . That is, W is closed under vector addition and scalar multiplication. By Definition 1.16, W is a subspace of  $\mathbb{R}^m$ .

(b) Let A be an  $m \times n$  matrix. Prove that the subspace W in part (a) and the column space of A are orthogonal complements in  $\mathbb{R}^m$ .

#### Proof (continued). ... and

$$(r\vec{x_1})A = r(\vec{x_1}A)$$
 by Theorem 1.3.A(7), "Scalars Pull Through"  
=  $r\vec{0}$  since  $\vec{x_1} \in W$   
=  $\vec{0}$ .

So both  $\vec{x_1} + \vec{x_2} \in W$  and  $r\vec{x_1} \in W$ . That is, W is closed under vector addition and scalar multiplication. By Definition 1.16, W is a subspace of  $\mathbb{R}^m$ .

(b) Let A be an  $m \times n$  matrix. Prove that the subspace W in part (a) and the column space of A are orthogonal complements in  $\mathbb{R}^m$ .

**Proof.** Recall that by Definition 1.8, "Matrix Product," the (i, j) entry of the matrix product AB is the dot product of the *i*th row of A with the *j*th column of B.

#### Proof (continued). ... and

$$(r\vec{x_1})A = r(\vec{x_1}A)$$
 by Theorem 1.3.A(7), "Scalars Pull Through"  
=  $r\vec{0}$  since  $\vec{x_1} \in W$   
=  $\vec{0}$ .

So both  $\vec{x_1} + \vec{x_2} \in W$  and  $r\vec{x_1} \in W$ . That is, W is closed under vector addition and scalar multiplication. By Definition 1.16, W is a subspace of  $\mathbb{R}^m$ .

(b) Let A be an  $m \times n$  matrix. Prove that the subspace W in part (a) and the column space of A are orthogonal complements in  $\mathbb{R}^m$ .

**Proof.** Recall that by Definition 1.8, "Matrix Product," the (i, j) entry of the matrix product AB is the dot product of the *i*th row of A with the *j*th column of B.

**Proof (continued).** So for  $\vec{x} \in W$  (here we treat row vector  $\vec{x} \in \mathbb{R}^m$  as a  $1 \times m$  matrix) we have that  $\vec{x}A$  is a  $1 \times n$  matrix (or a row vector in  $\mathbb{R}^n$ ) and for  $\vec{x} \in W$  we have  $\vec{x}A = \vec{0} \in \mathbb{R}^n$ . So the *j*th entry of  $\vec{x}A = \vec{0}$  is the dot product of  $\vec{x}$  with the *j*th column of A and, since  $\vec{x}A = \vec{0}$ , this dot product must be 0 for each i = 1, 2, ..., n. So by Definition 1.7, "Perpendicular or Orthogonal Vectors," each  $\vec{x} \in W$  is orthogonal to each column of A. Also, by definition, W contain all vectors  $\vec{x}$  in  $\mathbb{R}^m$  which satisfy  $\vec{x}A = \vec{0}$  (i.e., all vectors  $\vec{x}$  in  $\mathbb{R}^m$  which are perpendicular to all columns of A). The column space of A is the span of the columns of A and since  $\vec{x} \in W$  is orthogonal to each column of A then  $\vec{x}$  is orthogonal to each vector which is in the span of the columns of A.

**Proof (continued).** So for  $\vec{x} \in W$  (here we treat row vector  $\vec{x} \in \mathbb{R}^m$  as a  $1 \times m$  matrix) we have that  $\vec{x}A$  is a  $1 \times n$  matrix (or a row vector in  $\mathbb{R}^n$ ) and for  $\vec{x} \in W$  we have  $\vec{x}A = \vec{0} \in \mathbb{R}^n$ . So the *j*th entry of  $\vec{x}A = \vec{0}$  is the dot product of  $\vec{x}$  with the *j*th column of A and, since  $\vec{x}A = \vec{0}$ , this dot product must be 0 for each j = 1, 2, ..., n. So by Definition 1.7, "Perpendicular or Orthogonal Vectors," each  $\vec{x} \in W$  is orthogonal to each column of A. Also, by definition, W contain all vectors  $\vec{x}$  in  $\mathbb{R}^m$  which satisfy  $\vec{x}A = \vec{0}$  (i.e., all vectors  $\vec{x}$  in  $\mathbb{R}^m$  which are perpendicular to all columns of A). The column space of A is the span of the columns of Aand since  $\vec{x} \in W$  is orthogonal to each column of A then  $\vec{x}$  is orthogonal to each vector which is in the span of the columns of A. Conversely, any vector  $\vec{x}$  in the orthogonal complement of the column space of A must be orthogonal to all linear combinations of the columns of A; in particular such  $\vec{x}$  must by orthogonal to each column of A and hence such  $\vec{x}$  is in W. So the orthogonal complement of the column space of A is W.

**Proof (continued).** So for  $\vec{x} \in W$  (here we treat row vector  $\vec{x} \in \mathbb{R}^m$  as a  $1 \times m$  matrix) we have that  $\vec{x}A$  is a  $1 \times n$  matrix (or a row vector in  $\mathbb{R}^n$ ) and for  $\vec{x} \in W$  we have  $\vec{x}A = \vec{0} \in \mathbb{R}^n$ . So the *j*th entry of  $\vec{x}A = \vec{0}$  is the dot product of  $\vec{x}$  with the *j*th column of A and, since  $\vec{x}A = \vec{0}$ , this dot product must be 0 for each j = 1, 2, ..., n. So by Definition 1.7, "Perpendicular or Orthogonal Vectors," each  $\vec{x} \in W$  is orthogonal to each column of A. Also, by definition, W contain all vectors  $\vec{x}$  in  $\mathbb{R}^m$  which satisfy  $\vec{x}A = \vec{0}$  (i.e., all vectors  $\vec{x}$  in  $\mathbb{R}^m$  which are perpendicular to all columns of A). The column space of A is the span of the columns of Aand since  $\vec{x} \in W$  is orthogonal to each column of A then  $\vec{x}$  is orthogonal to each vector which is in the span of the columns of A. Conversely, any vector  $\vec{x}$  in the orthogonal complement of the column space of A must be orthogonal to all linear combinations of the columns of A; in particular such  $\vec{x}$  must by orthogonal to each column of A and hence such  $\vec{x}$  is in W. So the orthogonal complement of the column space of A is W.

**Page 337 number 28.** Let *W* be a subspace of  $\mathbb{R}^n$  with orthogonal complement  $W^{\perp}$ . Writing  $\vec{a} = \vec{a}_W + \vec{a}_{W^{\perp}}$ , as in Theorem 6.1, prove that  $\|\vec{a}\| = \sqrt{\|\vec{a}_W\|^2 + \|\vec{a}_{W^{\perp}}\|^2}$ .

**Solution.** By Note 1.2.A,  $\|\vec{a}\|^2 = \vec{a} \cdot \vec{a}$ , so we have

**Page 337 number 28.** Let *W* be a subspace of  $\mathbb{R}^n$  with orthogonal complement  $W^{\perp}$ . Writing  $\vec{a} = \vec{a}_W + \vec{a}_{W^{\perp}}$ , as in Theorem 6.1, prove that  $\|\vec{a}\| = \sqrt{\|\vec{a}_W\|^2 + \|\vec{a}_{W^{\perp}}\|^2}$ .

**Solution.** By Note 1.2.A,  $\|\vec{a}\|^2 = \vec{a} \cdot \vec{a}$ , so we have

$$\begin{split} \|\vec{a}\|^{2} &= (\vec{a}_{W} + \vec{a}_{W^{\perp}}) \cdot (\vec{a}_{W} + \vec{a}_{W^{\perp}}) \\ &= \vec{a}_{W} \cdot \vec{a}_{W} + \vec{a}_{W} \cdot \vec{a}_{W^{\perp}} + \vec{a}_{W^{\perp}} \cdot \vec{a}_{W} + \vec{a}_{W^{\perp}} \cdot \vec{a}_{W^{\perp}} \\ & \text{by Theorem 1.3, "Properties of Dot Products"} \\ &= \|\vec{a}_{W}\|^{2} + \vec{a}_{W} \cdot \vec{a}_{W^{\perp}} + \vec{a}_{W^{\perp}} \cdot \vec{a}_{W} + \|\vec{a}_{W^{\perp}}\|^{2} \text{ by Note 1.2.A} \\ &= \|\vec{a}_{W}\|^{2} + 0 + 0 + \|\vec{a}_{W^{\perp}}\|^{2} \text{ since } \vec{a}_{W} \text{ and } \vec{a}_{W^{\perp}} \text{ are orthogonal.} \end{split}$$

**Page 337 number 28.** Let *W* be a subspace of  $\mathbb{R}^n$  with orthogonal complement  $W^{\perp}$ . Writing  $\vec{a} = \vec{a}_W + \vec{a}_{W^{\perp}}$ , as in Theorem 6.1, prove that  $\|\vec{a}\| = \sqrt{\|\vec{a}_W\|^2 + \|\vec{a}_{W^{\perp}}\|^2}$ .

**Solution.** By Note 1.2.A,  $\|\vec{a}\|^2 = \vec{a} \cdot \vec{a}$ , so we have

$$\begin{split} \|\vec{a}\|^2 &= (\vec{a}_W + \vec{a}_{W^{\perp}}) \cdot (\vec{a}_W + \vec{a}_{W^{\perp}}) \\ &= \vec{a}_W \cdot \vec{a}_W + \vec{a}_W \cdot \vec{a}_{W^{\perp}} + \vec{a}_{W^{\perp}} \cdot \vec{a}_W + \vec{a}_{W^{\perp}} \cdot \vec{a}_{W^{\perp}} \\ & \text{by Theorem 1.3, "Properties of Dot Products"} \\ &= \|\vec{a}_W\|^2 + \vec{a}_W \cdot \vec{a}_{W^{\perp}} + \vec{a}_{W^{\perp}} \cdot \vec{a}_W + \|\vec{a}_{W^{\perp}}\|^2 \text{ by Note 1.2.A} \\ &= \|\vec{a}_W\|^2 + 0 + 0 + \|\vec{a}_{W^{\perp}}\|^2 \text{ since } \vec{a}_W \text{ and } \vec{a}_{W^{\perp}} \text{ are orthogonal.} \end{split}$$

Not taking square roots (and observing that  $\|\vec{a}\|$  is nonnegative) gives  $\|\vec{a}\| = \sqrt{\|\vec{a}_W\|^2 + \|\vec{a}_{W^{\perp}}\|^2}$ .

**Page 337 number 28.** Let *W* be a subspace of  $\mathbb{R}^n$  with orthogonal complement  $W^{\perp}$ . Writing  $\vec{a} = \vec{a}_W + \vec{a}_{W^{\perp}}$ , as in Theorem 6.1, prove that  $\|\vec{a}\| = \sqrt{\|\vec{a}_W\|^2 + \|\vec{a}_{W^{\perp}}\|^2}$ .

**Solution.** By Note 1.2.A,  $\|\vec{a}\|^2 = \vec{a} \cdot \vec{a}$ , so we have

$$\begin{split} \|\vec{a}\|^2 &= (\vec{a}_W + \vec{a}_{W^{\perp}}) \cdot (\vec{a}_W + \vec{a}_{W^{\perp}}) \\ &= \vec{a}_W \cdot \vec{a}_W + \vec{a}_W \cdot \vec{a}_{W^{\perp}} + \vec{a}_{W^{\perp}} \cdot \vec{a}_W + \vec{a}_{W^{\perp}} \cdot \vec{a}_{W^{\perp}} \\ & \text{by Theorem 1.3, "Properties of Dot Products"} \\ &= \|\vec{a}_W\|^2 + \vec{a}_W \cdot \vec{a}_{W^{\perp}} + \vec{a}_{W^{\perp}} \cdot \vec{a}_W + \|\vec{a}_{W^{\perp}}\|^2 \text{ by Note 1.2.A} \\ &= \|\vec{a}_W\|^2 + 0 + 0 + \|\vec{a}_{W^{\perp}}\|^2 \text{ since } \vec{a}_W \text{ and } \vec{a}_{W^{\perp}} \text{ are orthogonal.} \end{split}$$

Not taking square roots (and observing that  $\|\vec{a}\|$  is nonnegative) gives  $\|\vec{a}\| = \sqrt{\|\vec{a}_W\|^2 + \|\vec{a}_{W^{\perp}}\|^2}$ .