# Theory of Matrices

**Chapter 4. Vector/Matrix Derivatives and Integrals** 4.5. Integration and Expectation—Proofs of Theorems







**Theorem 4.5.1.** For  $A(x) = [a_{ij}(x)]$  an  $n \times n$  matrix function of scalar variable x, we have

$$\int_a^b \operatorname{tr}(A(x)) \, dx = \operatorname{tr}\left(\int_a^b A(x) \, dx\right).$$

**Proof.** Recall that  $tr(A) = tr([a_{ij}]) = \sum_{i=1}^{n} a_{ii}$ . So

$$\int_{a}^{b} \operatorname{tr}(A(x)) dx = \int_{a}^{b} \left( \sum_{i=1}^{n} a_{ii}(x) \right) dx$$
$$= \sum_{i=1}^{n} \left( \int_{a}^{b} a_{ii}(x) dx \right) \text{ by the linearity properties}$$
of definite integrals
$$= \operatorname{tr}\left( \left[ \int_{a}^{b} a_{ij}(x) \right] \right) = \operatorname{tr}\left( \int_{a}^{b} A(x) dx \right).$$

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=  $\sum_{i=1}^{n} \left( \int_{a}^{b} a_{ii}(x) dx \right)$  by the linearity properties  
of definite integrals  
=  $\operatorname{tr}\left( \left[ \int_{a}^{b} a_{ij}(x) \right] \right) = \operatorname{tr}\left( \int_{a}^{b} A(x) dx \right).$ 

#### Theorem 4.5.3. Atiken's Integral.

For  $\Sigma^{-1}$  a symmetric positive definite  $d \times d$  matrix, is a constant d-vector, and  $x \in \mathbb{R}^d$  we have

$$\int_{\mathbb{R}^d} e^{-(x-\mu)^T \Sigma^{-1}(x-\mu)/2} \, dx = (2\pi)^{d/2} (\det(\Sigma))^{1/2}$$

**Proof.** We know that  $\int_{\mathbb{R}} e^{-x^2} dx = \sqrt{2\pi}$ , based on the standard normal distribution. If we let  $y = x - \mu$  then we also have

$$\int_{\mathbb{R}} e^{-y^2} dy = \int_{\mathbb{R}} e^{-(x-\mu)^2} dx = \sqrt{2\pi}.$$

Now we make a change of variables and let  $y = x - \mu$  where  $y \in \mathbb{R}^d$ . Then as x ranges over all of  $\mathbb{R}^d$ , so does y and hence

$$\int_{\mathbb{R}^d} e^{-(x-\mu)^T \Sigma^{-1} (x-\mu)/2} \, dx = \int_{\mathbb{R}^d} e^{-y^T \Sigma^{-1} y/2} \, dy.$$

#### Theorem 4.5.3. Atiken's Integral.

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# Theorem 4.5.3 (continued 1)

### Theorem 4.5.3. Atiken's Integral.

For  $\Sigma^{-1}$  a symmetric positive definite  $d \times d$  matrix, is a constant d-vector, and  $x \in \mathbb{R}^d$  we have

**Proof (continued).** By Theorem 3.8.15(1), since  $\Sigma^{-1}$  is symmetric and positive definite, then  $P^T \Sigma^{-1} P = \mathcal{I}$  for some nonsingular P. We now make another change of variables to  $z = P^{-1}y$  (and so y = Pz). The change of variables requires that we introduce the Jacobian, as described at the beginning of the section (but now in *d*-dimensions) we need det(P). Since  $P^T \Sigma^{-1} P = \mathcal{I}$  then by Theorem 3.2.4, det( $P^T$ )det( $\Sigma^{-1}$ )det(P) = det( $\mathcal{I}$ ) = 1, and since det( $P^T$ ) = det(P) by Theorem 3.1.A and det( $\Sigma^{-1}$ ) =  $a/det(\Sigma)$  (also by Theorem 3.1.A), then  $(det(P))^2 = det(\Sigma)$  or det(P) =  $(det(\Sigma))^{1/2}$ .

# Theorem 4.5.3 (continued 1)

### Theorem 4.5.3. Atiken's Integral.

For  $\Sigma^{-1}$  a symmetric positive definite  $d \times d$  matrix, is a constant d-vector, and  $x \in \mathbb{R}^d$  we have

**Proof (continued).** By Theorem 3.8.15(1), since  $\Sigma^{-1}$  is symmetric and positive definite, then  $P^T \Sigma^{-1} P = \mathcal{I}$  for some nonsingular P. We now make another change of variables to  $z = P^{-1}y$  (and so y = Pz). The change of variables requires that we introduce the Jacobian, as described at the beginning of the section (but now in *d*-dimensions) we need det(P). Since  $P^T \Sigma^{-1} P = \mathcal{I}$  then by Theorem 3.2.4,  $\det(P^T)\det(\Sigma^{-1})\det(P) = \det(\mathcal{I}) = 1$ , and since  $\det(P^T) = \det(P)$  by Theorem 3.1.A and  $\det(\Sigma^{-1}) = a/\det(\Sigma)$  (also by Theorem 3.1.A), then  $(\det(P))^2 = \det(\Sigma)$  or  $\det(P) = (\det(\Sigma))^{1/2}$ .

Theorem 4.5.3 (continued 2)

### Proof (continued). So

. . .

$$\int_{\mathbb{R}^d} e^{-y^T \Sigma^{-1} y/2} dt = \int_{\mathbb{R}^d} e^{-(Pz)^T \Sigma^{-1} (Pz)/2} (\det(\Sigma))^{1/2} dz$$

$$= \int_{\mathbb{R}^d} e^{-z^T (P^T \Sigma^{-1} P) z/2} (\det(\Sigma))^{1/2} dz$$

$$= \int_{\mathbb{R}^d} e^{z^T z/2} (\det(\Sigma))^{1/2} dz \text{ since } P^T \Sigma^{-1} P = \mathcal{I}$$

$$= (\det(\Sigma))^{1/2} \int_{\mathbb{R}^d} e^{-|z|^2/2} dz$$

$$= (\det(\Sigma))^{1/2} \int_{\mathbb{R}^d} e^{-(z_1^2 + z_2^2 + \dots + z_d^2)/2} dz$$
where vector z has components  $z_i$ 

Theorem 4.5.3 (continued 3)

#### Theorem 4.5.3. Atiken's Integral.

For  $\Sigma^{-1}$  a symmetric positive definite  $d \times d$  matrix, is a constant d-vector, and  $x \in \mathbb{R}^d$  we have

$$\int_{\mathbb{R}^d} e^{-(x-\mu)^T \Sigma^{-1}(x-\mu)/2} \, dx = (2\pi)^{d/2} (\det(\Sigma))^{1/2}.$$

Proof (continued). ...

$$\int_{\mathbb{R}^d} e^{-(x-\mu)^T \Sigma^{-1} (x-\mu)/2} \, dx = \int_{\mathbb{R}^d} e^{-y^T \Sigma^{-1} y/2} \, dy$$

$$= (\det(\Sigma))^{1/2} \int_{\mathbb{R}} \int_{\mathbb{R}} \cdots \int_{\mathbb{R}} e^{-z_1^2} e^{-z_2^2} \cdots e^{-z_d^2} dz_1 dz_2 \cdots dz_d$$

$$= (\det(\Sigma))^{1/2} \int_{\mathbb{R}} e^{-z_1^2} dz_1 \int_{\mathbb{R}} e^{-z_2^2} dz_2 \cdots \int_{\mathbb{R}} e^{-z_d^2} dz_d$$

$$= (\det(\Sigma))^{1/2} ((2\pi)^{1/2})^d \text{ as described above}$$
$$= (2\pi)^{d/2} (\det(\Sigma))^{1/2}. \quad \Box$$