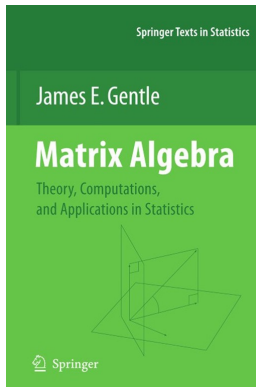


# Theory of Matrices

## Chapter 5. Matrix Transformations and Factorizations

### 5.3. Householder Transformations (Reflections)—Proofs of Theorems



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$$q = [x_1, x_2, \dots, x_{k-1}, x_k + \operatorname{sgn}(x_k)\|x\|_2, x_{k+1}, \dots, x_n]^T$$

and let  $u = q/\|q\|_2$ . Then  $H = I - 2uu^T$  maps  $x$  to  $Hx = \tilde{x}$  where all entries of  $\tilde{x}$  are 0 except for the  $k$ th entry (when  $x_k \neq 0$ ).

**Proof.** First, notice that

$$\begin{aligned} \|q\|_2^2 &= x_1^2 + x_2^2 + \dots + x_{k-1}^2 + (x_k^2 + 2x_k \operatorname{sgn}(x_k)\|x\|_2 + \operatorname{sgn}(x_k)^2\|x\|_2^2) \\ &\quad + x_{k+1}^2 + \dots + x_n^2 = \|x\|_2^2 + 2|x_k|\|x\|_2 + \|x\|_2^2 = 2\|x\|_2(\|x\|_2 + |x_k|). \end{aligned}$$

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Notice that the  $(i, j)$  entry of  $qq^T$  is

$$q_i q_j = \begin{cases} x_i x_j & \text{for } i \neq k \neq j \\ (x_k + \operatorname{sgn}(x_k)\|x\|_2)x_j & \text{for } i = k, j \neq k \\ x_i(x_k + \operatorname{sgn}(x_k)\|x\|_2) & \text{for } i \neq k, j = k \\ (x_k + \operatorname{sgn}(x_k)\|x\|_2)^2 & \text{for } i = j = k. \end{cases}$$

Let  $y_k = x_k + \operatorname{sgn}(x_k)\|x\|_2$ .

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Let  $y_k = x_k + \operatorname{sgn}(x_k)\|x\|_2$ .

## Theorem 5.3.1 (continued 1)

**Proof (continued).** Now  $qq^T =$

$$\begin{bmatrix} x_1x_1 & x_1x_2 & \cdots & x_1x_{k-1} & x_1y_k & x_1x_{k+1} & \cdots & x_1x_n \\ x_2x_1 & x_2x_2 & \cdots & x_2x_{k-1} & x_2y_k & x_2x_{k+1} & \cdots & x_2x_n \\ \vdots & \vdots & \cdots & \vdots & \vdots & \vdots & \cdots & \vdots \\ x_{k-1}x_1 & x_{k-1}x_2 & \cdots & x_{k-1}x_{k-1} & x_{k-1}y_k & x_{k-1}x_{k+1} & \cdots & x_{k-1}x_n \\ y_kx_1 & y_kx_2 & \cdots & y_kx_{k-1} & y_ky_k & y_kx_{k+1} & \cdots & y_kx_n \\ x_{k+1}x_1 & x_{k+1}x_2 & \cdots & x_{k+1}x_{k-1} & x_{k+1}y_k & x_{k+1}x_{k+1} & \cdots & x_{k+1}x_n \\ \vdots & \vdots & \cdots & \vdots & \vdots & \vdots & \cdots & \vdots \\ x_nx_1 & x_nx_2 & \cdots & x_nx_{k-1} & x_ny_k & x_nx_{k+1} & \cdots & x_nx_n \end{bmatrix}$$

...

## Theorem 5.3.1 (continued 2)

**Proof (continued).** ... and  $qq^T x =$

$$\begin{bmatrix} x_1 \sum_{\ell=1}^n x_\ell^2 - x_1 x_k^2 + x_1 y_k x_k \\ x_2 \sum_{\ell=1}^n x_\ell^2 - x_2 x_k^2 + x_2 y_k x_k \\ \vdots \\ x_{k-1} \sum_{\ell=1}^n x_\ell^2 - x_{k-1} x_k^2 + x_{k-1} y_k x_k \\ y_k \sum_{\ell=1}^n x_\ell^2 - y_k x_k^2 + y_k^2 x_k \\ x_{k+1} \sum_{\ell=1}^n x_\ell^2 - x_{k+1} x_k^2 + x_{k+1} y_k x_k \\ \vdots \\ x_n \sum_{\ell=1}^n x_\ell^2 - x_n x_k^2 + x_n y_k x_k \end{bmatrix} = \begin{bmatrix} x_1 \|x\|_2^2 - x_1 x_k (x_k - y_k) \\ x_2 \|x\|_2^2 - x_2 x_k (x_k - y_k) \\ \vdots \\ x_{k-1} \|x\|_2^2 - x_{k-1} x_k (x_k - y_k) \\ y_k \|x\|_2^2 - y_k x_k (x_k - y_k) \\ x_{k+1} \|x\|_2^2 - x_{k+1} x_k (x_k - y_k) \\ \vdots \\ x_n \|x\|_2^2 - x_n x_k (x_k - y_k) \end{bmatrix}$$

...

## Theorem 5.3.1 (continued 3)

**Proof (continued).** ... and since  $y_k = x_k + \operatorname{sgn}(x_k)\|x\|_2$  then  $x_k(x_k - y_k) = x_k(-\operatorname{sgn}(x_k)\|x\|_2) = -|x_k|\|x\|_2$  and

$$qq^T x = \begin{bmatrix} x_1\|x\|_2^2 + x_1|x_k|\|x\|_2 \\ x_2\|x\|_2^2 + x_2|x_k|\|x\|_2 \\ \vdots \\ x_{k-1}\|x\|_2^2 + x_{k-1}|x_k|\|x\|_2 \\ y_k\|x\|_2^2 + y_k|x_k|\|x\|_2 \\ x_{k+1}\|x\|_2^2 + x_{k+1}|x_k|\|x\|_2 \\ \vdots \\ x_n\|x\|_2^2 + x_n|x_k|\|x\|_2 \end{bmatrix}.$$



## Theorem 5.3.1 (continued 4)

**Proof (continued).** Since  $\|q\|_2^2 = 2\|x\|_2(\|x\|_2 + |x_k|)$  then  
 $(I - 2uu^T)x = (I - 2qq^T/\|q\|_2^2)x = (\|q\|_2^2 I - 2qq^T)x/\|q\|_2^2 =$

$$\frac{1}{\|q\|_2^2} \begin{bmatrix} 2\|x\|_2(\|x\|_2 + |x_k|)x_1 - 2x_1\|x\|_2^2 - 2x_1|x_k|\|x\|_2 \\ 2\|x\|_2(\|x\|_2 + |x_k|)x_2 - 2x_2\|x\|_2^2 - 2x_2|x_k|\|x\|_2 \\ \vdots \\ 2\|x\|_2(\|x\|_2 + |x_k|)x_{k-1} - 2x_{k-1}\|x\|_2^2 - 2x_{k-1}|x_k|\|x\|_2 \\ 2\|x\|_2(\|x\|_2 + |x_k|)x_k - 2y_k\|x\|_2^2 - 2y_k|x_k|\|x\|_2 \\ 2\|x\|_2(\|x\|_2 + |x_k|)x_{k+1} - 2x_{k+1}\|x\|_2^2 - 2x_{k+1}|x_k|\|x\|_2 \\ \vdots \\ 2\|x\|_2(\|x\|_2 + |x_k|)x_n - 2x_n\|x\|_2^2 - 2x_n|x_k|\|x\|_2 \end{bmatrix} = \dots$$

## Theorem 5.3.1 (continued 5)

**Proof (continued).** ...

$$\begin{aligned}
 &= [0, 0, \dots, 0, 2\|x\|_2(\|x\|_2 + |x_k|)x_k - 2y_k\|x\|_2^2 - 2y_k|x_k|\|x\|_2, 0, \dots, 0]^T / \|q\|_2^2 \\
 &= [0, 0, \dots, 0, 2\|x\|_2(\|x\|_2 + |x_k|)x_k - 2\|x\|_2 y_k(\|x\|_2 + |x_k|), 0, \dots, 0]^T / \|q\|_2^2 \\
 &= [0, 0, \dots, 0, 2\|x\|_2(\|x\|_2 + |x_k|)(x_k - y_k), 0, \dots, 0]^T / \|q\|_2^2 \\
 &= [0, 0, \dots, 0, 2\|x\|_2(\|x\|_2 + |x_k|)(-\operatorname{sgn}(x_k)\|x\|_2), 0, \dots, 0]^T / \|q\|_2^2 \\
 &\quad \text{since } x_k - y_k = -\operatorname{sgn}(x_k)\|x\|_2 \\
 &= \frac{[0, 0, \dots, 0, 2\|x\|_2(\|x\|_2 + |x_k|)(-\operatorname{sgn}(x_k)\|x\|_2), 0, \dots, 0]^T}{2\|x\|_2(\|x\|_2 + |x_k|)} \\
 &\quad \text{since } \|q\|_2^2 = 2\|x\|_2(\|x\|_2 + |x_k|) \\
 &= [0, 0, \dots, 0, -\operatorname{sgn}(x_k)\|x\|_2, 0, \dots, 0]^T.
 \end{aligned}$$

So the result holds. □