

1.4 The First Fundamental Form

Note. Suppose M is a surface determined by $\vec{X}(u, v) \subset E^3$ and suppose $\vec{\alpha}(t)$ is a curve on M , $t \in [a, b]$. Then we can write $\vec{\alpha}(t) = \vec{X}(u(t), v(t))$ (then $(u(t), v(t))$ is a curve in \mathbb{R}^2 whose image under \vec{X} is $\vec{\alpha}$). Then

$$\vec{\alpha}'(t) = \frac{\partial \vec{X}}{\partial u} \frac{du}{dt} + \frac{\partial \vec{X}}{\partial v} \frac{dv}{dt} = u' \vec{X}_1 + v' \vec{X}_2.$$

If $s(t)$ represents the arc length along $\vec{\alpha}$ (with $s(a) = 0$) then

$$s(t) = \int_a^t \|\vec{\alpha}'(r)\| dr$$

and

$$\frac{ds}{dt} = \|\vec{\alpha}'(t)\|$$

so

$$\begin{aligned} \left(\frac{ds}{dt}\right)^2 &= \|\vec{\alpha}'(t)\|^2 = \vec{\alpha}' \cdot \vec{\alpha}' = (u' \vec{X}_1 + v' \vec{X}_2) \cdot (u' \vec{X}_1 + v' \vec{X}_2) \\ &= u'^2 (\vec{X}_1 \cdot \vec{X}_1) + 2u'v' (\vec{X}_1 \cdot \vec{X}_2) + v'^2 (\vec{X}_2 \cdot \vec{X}_2). \end{aligned}$$

Following Gauss' notation (briefly) we denote

$$E = \vec{X}_1 \cdot \vec{X}_1, \quad F = \vec{X}_1 \cdot \vec{X}_2, \quad G = \vec{X}_2 \cdot \vec{X}_2$$

and have

$$\left(\frac{ds}{dt}\right)^2 = E \left(\frac{du}{dt}\right)^2 + 2F \left(\frac{du}{dt} \frac{dv}{dt}\right) + G \left(\frac{dv}{dt}\right)^2$$

or in differential notation

$$ds^2 = E(du)^2 + 2F(du dv) + G(dv)^2.$$

Definition. Let M be a surface determined by $\vec{X}(u, v)$. The *first fundamental form* (or more commonly *metric form*) of M is $\left(\frac{ds}{dt}\right)^2$ or $(ds)^2$ as defined above.

Definition. A property of a surface which depends only on the metric form of the surface is an *intrinsic property*.

Note. The idea of an intrinsic property is that a “resident” of the surface can detect such a property without appealing to a “larger space” in which the surface is embedded. Certainly an inhabitant of a surface can measure distance within the surface.

Example 10, page 32. Consider the xy -plane described as $\vec{X}(u, v) = (u, v, 0)$ where $u \in \mathbb{R}$ and $v \in \mathbb{R}$. Then $\vec{X}_1 = (1, 0, 0)$ and $\vec{X}_2 = (0, 1, 0)$. So

$$E = \vec{X}_1 \cdot \vec{X}_1 = 1, \quad F = \vec{X}_1 \cdot \vec{X}_2 = 0, \quad G = \vec{X}_2 \cdot \vec{X}_2 = 1.$$

Then the first fundamental form is

$$\left(\frac{ds}{dt}\right)^2 = \left(\frac{du}{dt}\right)^2 + \left(\frac{dv}{dt}\right)^2$$

or, in terms of x and y :

$$\left(\frac{ds}{dt}\right)^2 = \left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2.$$

Of course, this is the “usual” expression for the differential of arclength from Calculus 2.

Definition. The *matrix of the first fundamental form* of a surface M determined by $\vec{X}(u, v)$ is

$$\begin{pmatrix} E & F \\ F & G \end{pmatrix} \equiv \begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix}$$

where E, F, G are as defined as above.

Note. Since $\|\vec{v} \times \vec{w}\| = \|\vec{v}\|\|\vec{w}\| \sin \theta$ and $\vec{v} \cdot \vec{w} = \|\vec{v}\|\|\vec{w}\| \cos \theta$, where θ is the angle between \vec{v} and \vec{w} , then

$$\begin{aligned} \|\vec{X}_1 \times \vec{X}_2\|^2 &= \|\vec{X}_1\|^2 \|\vec{X}_2\|^2 \sin^2 \theta = \|\vec{X}_1\|^2 \|\vec{X}_2\|^2 (1 - \cos^2 \theta) \\ &= \|\vec{X}_1\|^2 \|\vec{X}_2\|^2 - (\|\vec{X}_1\| \|\vec{X}_2\| \cos \theta)^2 \\ &= (\vec{X}_1 \cdot \vec{X}_1) \cdot (\vec{X}_2 \cdot \vec{X}_2) - (\vec{X}_1 \cdot \vec{X}_2)^2 \\ &= EG - F^2 = \begin{vmatrix} E & F \\ F & G \end{vmatrix} = g. \end{aligned}$$

Hence, $\|\vec{X}_1 \times \vec{X}_2\| = \sqrt{g}$.

Note. This matrix determines dot products of tangent vectors. If $\vec{v} = a\vec{X}_1 + b\vec{X}_2$ and $\vec{w} = c\vec{X}_1 + d\vec{X}_2$ are vectors tangent to a surface M at a given point, then

$$\begin{aligned} \vec{v} \cdot \vec{w} &= (a\vec{X}_1 + b\vec{X}_2) \cdot (c\vec{X}_1 + d\vec{X}_2) = Eac + F(ad + bc) + Gbd \\ &= (a, b) \begin{pmatrix} E & F \\ F & G \end{pmatrix} \begin{pmatrix} c \\ d \end{pmatrix}. \end{aligned}$$

Notation. We now replace the parameters u and v with u^1 and u^2 . We then have

$$ds^2 = g_{11}(du^1)^2 + 2g_{12}du^1du^2 + g_{22}(du^2)^2 = \sum_{i,j} g_{ij}du^i du^j$$

where the summation is taken (throughout this chapter) over the set $\{1, 2\}$. In Chapter 3, we will sum over $\{1, 2, 3, 4\}$. If \vec{v} is a vector tangent to M at a point \vec{P} and $\vec{v} = (v^1, v^2)$ in the basis $\{\vec{X}_1, \vec{X}_2\}$ for the tangent plane at \vec{P} , then we have

$$\vec{v} = \sum_i v^i \vec{X}_i.$$

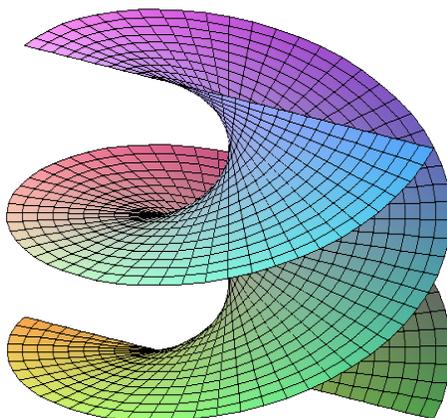
If $\vec{\alpha}(t)$ is a curve on M where $\vec{\alpha}$ is represented by $\vec{X}(u^1(t), u^2(t))$ then

$$\vec{\alpha}'(t) = u^1'(t)\vec{X}_1 + u^2'(t)\vec{X}_2 = \sum_i u^{i'}\vec{X}_i.$$

Notation. We denote the ij entry of $(g_{ij})^{-1}$ as g^{ij} . Therefore $(g_{ij})(g^{ij}) = \mathcal{I}$ and $\sum_j g_{ij}g^{jk} = \delta_i^k$ (the ik entry of \mathcal{I}) where

$$\delta_i^k = \begin{cases} 1 & \text{if } i = k \\ 0 & \text{if } i \neq k. \end{cases}$$

Example (Exercise 1.4.3(c)). For the surface $\vec{X}(u, v) = (u \cos v, u \sin v, bv)$ (the helicoid of Example 9), compute the matrix (g_{ij}) , its determinate g , the inverse matrix (g^{ij}) and the unit normal vector \vec{U} .



From Wikipedia's page

https://commons.wikimedia.org/wiki/File:Helicoid_JD.png

Solution. Well

$$\begin{aligned}\vec{X}_1 &= \frac{\partial \vec{X}}{\partial u} = (\cos v, \sin v, 0) \\ \vec{X}_2 &= \frac{\partial \vec{X}}{\partial v} = (-u \sin v, u \cos v, b)\end{aligned}$$

and so

$$\begin{aligned}g_{11} &= \vec{X}_1 \cdot \vec{X}_1 = \cos^2 v + \sin^2 v + 0 = 1 \\ g_{22} &= \vec{X}_2 \cdot \vec{X}_2 = u^2 \sin^2 v + u^2 \cos^2 v + b^2 = u^2 + b^2 \\ g_{12} &= \vec{X}_1 \cdot \vec{X}_2 = -u \cos v \sin v + u \cos v \sin v + 0 = 0 = g_{21}.\end{aligned}$$

Therefore

$$G = \begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & u^2 + b^2 \end{pmatrix}$$

and $g = \det(g_{ij}) = u^2 + b^2$. Then

$$\begin{aligned}G^{-1} &= \begin{pmatrix} g^{11} & g^{12} \\ g^{21} & g^{22} \end{pmatrix} = \frac{1}{g} \begin{pmatrix} g_{22} & -g_{12} \\ -g_{21} & g_{11} \end{pmatrix} \\ &= \frac{1}{u^2 + b^2} \begin{pmatrix} u^2 + b^2 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & \frac{1}{u^2 + b^2} \end{pmatrix}.\end{aligned}$$

Now the unit normal vector is $\vec{U} = \frac{\vec{X}_1 \times \vec{X}_2}{\|\vec{X}_1 \times \vec{X}_2\|}$ and

$$\vec{X}_1 \times \vec{X}_2 = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \cos v & \sin v & 0 \\ -u \sin v & u \cos v & b \end{vmatrix}$$

$$= (b \sin v, -b \cos v, u \cos^2 v + u \sin^2 v) = (b \sin v, -b \cos v, u).$$

Now

$$\|\vec{X}_1 \times \vec{X}_2\| = \sqrt{b^2 \sin^2 v + b^2 \cos^2 v + u^2} = \sqrt{b^2 + u^2}.$$

Therefore

$$\vec{U} = \left(\frac{b \sin v}{\sqrt{b^2 + u^2}}, \frac{-b \cos v}{\sqrt{b^2 + u^2}}, \frac{u}{\sqrt{b^2 + u^2}} \right).$$

Definition. Suppose Ω is a closed subset of the u^1u^2 -plane and that $\vec{X} : \Omega \rightarrow E^3$ is smooth (i.e. has continuous first partials), is one-to-one and regular (i.e. \vec{X}_1 and \vec{X}_2 are linearly independent) on the interior of Ω . Then the *area* of the surface $\vec{X}(\Omega)$ is

$$A = \int \int_{\Omega} \|\vec{X}_1 \times \vec{X}_2\| du^1 du^2 = \int \int_{\Omega} \sqrt{g} du^1 du^2.$$

(See page 37 of the text for motivation of this definition.)

Example (Exercise 1.4.6). (a) Show that the area A of the surface of revolution $\vec{X}(u, v) = (f(u) \cos v, f(u) \sin v, g(u))$ where $u \in [a, b]$ and $v \in [0, 2\pi]$ is given by

$$A = 2\pi \int_a^b |f(u)| \sqrt{f'(u)^2 + g'(u)^2} du.$$

(b) Show that the area of the surface obtained by revolving the graph $y = f(x)$ for $x \in [a, b]$ about the x -axis is given by

$$A = 2\pi \int_a^b |f(x)| \sqrt{1 + f'(x)^2} dx.$$

Solution. (a) Consider the surface area of the surface of revolution $\vec{X}(u, v) = (f(u) \cos v, f(u) \sin v, g(u))$. We have (from Exercise 1.4.5)

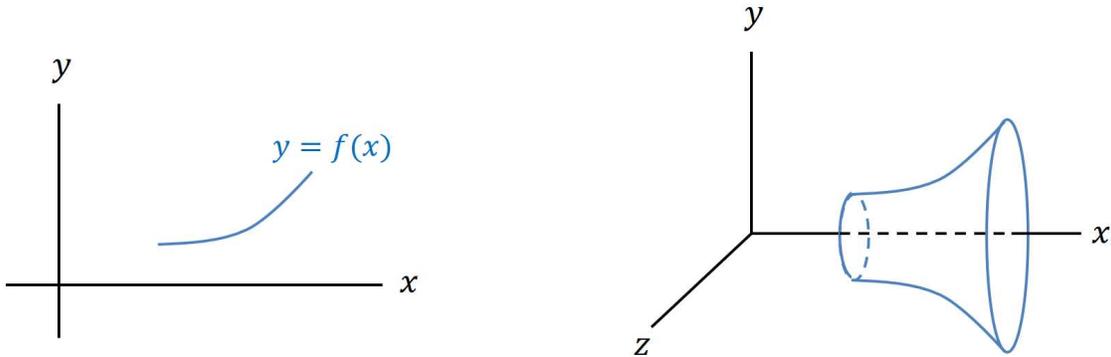
$$\|\vec{X}_1 \times \vec{X}_2\| = |f(u)| \sqrt{f'(u)^2 + g'(u)^2}$$

and so

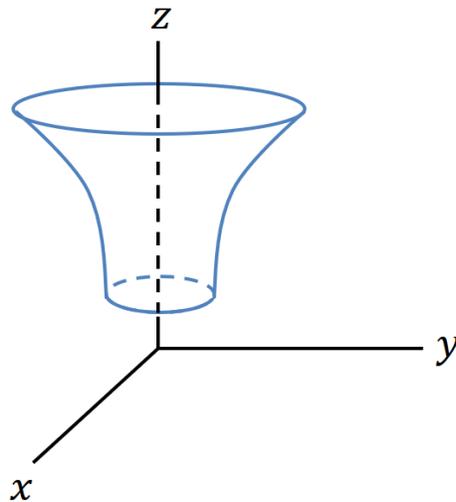
$$A = \int \int_{\Omega} \|\vec{X}_1 \times \vec{X}_2\| du dv \quad (\text{see page 37})$$

$$\begin{aligned}
 &= \int_a^b \int_0^{2\pi} |f(u)| \sqrt{f'(u)^2 + g'(u)^2} \, dv \, du \\
 &= 2\pi \int_a^b |f(u)| \sqrt{f'(u)^2 + g'(u)^2} \, du.
 \end{aligned}$$

(b) If $y = f(x)$, $x \in [a, b]$ where $a \geq 0$ is revolved about the x -axis, then we have:



This is equivalent to taking $\vec{X}(u, v) = (f(u), 0, u)$ (that is, the curve $x = f(z)$ in the xz -plane) and revolving it about the z -axis):



Then by Exercise 1.3.1, the surface is $\vec{X}(u, v) = (f(u) \cos v, f(u) \sin v, u)$. So by

part (a), the surface area is

$$A = 2\pi \int_a^b |f(u)|\sqrt{f'(u)^2 + 1} du = 2\pi \int_a^b |f(x)|\sqrt{1 + f'(x)^2} dx.$$

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