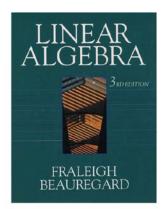
Linear Algebra

Chapter 8: Eigenvalues: Further Applications and Computations Section 8.1. Diagonalization of Quadratic Forms—Proofs of Theorems



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Page 417 Number 4(b). Find the symmetric coefficient matrix of the quadratic form $x_1^2 - 2x_2^2 + x_3^2 + 6x_4^2 - 2x_1x_4 + 6x_2x_4 - 8x_1x_3$.

Solution. From part (a) we have the upper-triangular coefficient matrix

$$U = \left[egin{array}{cccc} 1 & 0 & -8 & -2 \ 0 & -2 & 0 & 6 \ 0 & 0 & 1 & 0 \ 0 & 0 & 0 & 6 \end{array}
ight].$$

We take $a_{ij} = a_{ji} = u_{ij}/2$ for i < j to get

$$A = \left[\begin{array}{rrrr} 1 & 0 & -4 & -1 \\ 0 & -2 & 0 & 3 \\ -4 & 0 & 1 & 0 \\ -1 & 3 & 0 & 6 \end{array} \right].$$

Page 417 Number 4(a)

Page 417 Number 4(a). Find the upper-triangular coefficient matrix of the quadratic form $x_1^2 - 2x_2^2 + x_3^2 + 6x_4^2 - 2x_1x_4 + 6x_2x_4 - 8x_1x_3$.

Solution. We take the coefficient of $x_i x_i$ where $i \leq j$ as u_{ij} . All $u_{ij} = 0$ for i > j. So we have for the nonzero u_{ij} : $u_{11} = 1$, $u_{22} = -2$, $u_{33} = 1$, $u_{44} = 6$, $u_{14} = -2$, $u_{24} = 6$, $u_{13} = -8$. Hence

$$U = \left[\begin{array}{cccc} 1 & 0 & -8 & -2 \\ 0 & -2 & 0 & 6 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 6 \end{array} \right].$$

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Page 417 Number 12. Consider the quadratic form $x^2 + 2xy + y^2$. Find an orthogonal substitution that diagonalizes the quadratic form and find the diagonalized form.

Solution. For $x^2 + 2xy + y^2$, the upper-triangular coefficient matrix is $U = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$, so the symmetric coefficient matrix is $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$. We need the eigenvalues of A. so consider

$$\det(A - \lambda \mathcal{I}) = \begin{vmatrix} 1 - \lambda & 1 \\ 1 & 1 - \lambda \end{vmatrix} = (1 - \lambda)^2 - (1)^2$$
$$1 - 2\lambda + \lambda^2 - 1 = \lambda^2 - 2\lambda = \lambda(\lambda - 2).$$

so that the eigenvalues of A are $\lambda_1=0$ and $\lambda_2=2$. Now for the eigenvectors.

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Solution (continued).

 $\lambda_1 = 0$ We consider the system

$$[A - \lambda_1 \mathcal{I} \mid \vec{0}] = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \end{bmatrix} \xrightarrow{R_2 \to R_2 - R_1} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

So we need $\begin{array}{c} v_1+v_2=0 \\ 0=0 \end{array}$ or $\begin{array}{c} v_1=-v_2 \\ v_2=v_2 \end{array}$ or with $r=v_2$ as a free variable,

 $\vec{v}_1 = r \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ where $r \in \mathbb{R}$, $r \neq 0$. We need a unit eigenvector so we take

$$r=1/\sqrt{2}$$
 and $ec{v}_1=rac{1}{\sqrt{2}}\left[egin{array}{c} -1 \ 1 \end{array}
ight]=\left[egin{array}{c} -1/\sqrt{2} \ 1/\sqrt{2} \end{array}
ight].$

 $\lambda_2 = 2$ We consider the system

$$[A - \lambda_2 \mathcal{I} \mid \vec{0}] = \begin{bmatrix} -1 & 1 & 0 \\ 1 & -1 & 0 \end{bmatrix} \xrightarrow{R_1 \to R_1 + R_2} \begin{bmatrix} 0 & 0 & 0 \\ 1 & -1 & 0 \end{bmatrix}$$

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Solution (continued). The orthogonal substitution is

$$\vec{x} = \begin{bmatrix} x \\ y \end{bmatrix} = C\vec{t} = \begin{bmatrix} -1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix} \begin{bmatrix} t_1 \\ t_2 \end{bmatrix}$$
$$= \begin{bmatrix} (-1/\sqrt{2})t_1 + (1/\sqrt{2})t_2 \\ (1/\sqrt{2})t_1 + (1/\sqrt{2})t_2 \end{bmatrix}.$$

The diagonal form is then

$$\vec{x}^T A \vec{x} = \lambda_1 t_1^2 + \lambda_2 t_2^2 = 0t_1^2 + 2t_2^2 = 2t_2^2.$$

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Solution (continued).

So we need $\begin{array}{c} v_1-v_2=0 \\ 0=0 \end{array}$ or $\begin{array}{c} v_1=v_2 \\ v_2=v_2 \end{array}$ or with $s=v_2$ as a free variable,

 $ec{v}_2=s\left[egin{array}{c}1\\1\end{array}
ight]$ where $s\in\mathbb{R},\ s
eq0.$ We need a unit eigenvector so we take

 $2=1/\sqrt{2}$ and $\vec{v}_2=rac{1}{\sqrt{2}}\left[egin{array}{c}1\\1\end{array}
ight]=\left[egin{array}{c}1/\sqrt{2}\\1/\sqrt{2}\end{array}
ight]$. So we consider the orthogonal matrix

$$C = \begin{bmatrix} \vec{v}_1 & \vec{v}_2 \end{bmatrix} = \begin{bmatrix} -1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}.$$

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