

SECTION 3.2

EXERCISE #33

3.2.33 Let $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ be a basis for a vector space V and let $\vec{w} = t_1 \vec{v}_1 + t_2 \vec{v}_2 + \dots + t_k \vec{v}_k$ with $t_k \neq 0$. Prove that $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_{k-1}, \vec{w}, \vec{v}_{k+1}, \dots, \vec{v}_n\}$ is a basis for V .

Proof

First, since $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is a basis then by Definition 3.6, "Basis for a Vector Space," it is a spanning set for V . Let $\vec{v} \in V$. Then $\vec{v} = r_1 \vec{v}_1 + r_2 \vec{v}_2 + \dots + r_n \vec{v}_n$ for some $r_1, r_2, \dots, r_n \in \mathbb{R}$.

$$\begin{aligned} &= (r_1 \vec{v}_1 + r_2 \vec{v}_2 + \dots + r_{k-1} \vec{v}_{k-1} + r_k \vec{v}_k + r_{k+1} \vec{v}_{k+1} \\ &\quad + \dots + r_n \vec{v}_n) \\ &= (r_1 \vec{v}_1 + r_2 \vec{v}_2 + \dots + r_{k-1} \vec{v}_{k-1} + r_k \left(\frac{\vec{w} - t_1 \vec{v}_1 - t_2 \vec{v}_2 - \dots - t_{k-1} \vec{v}_{k-1}}{t_k} \right) \\ &\quad + r_{k+1} \vec{v}_{k+1} + \dots + r_n \vec{v}_n) \quad \text{since } t_k \neq 0 \\ &= \left(r_1 - \frac{t_1}{t_k} \right) \vec{v}_1 + \left(r_2 - \frac{t_2}{t_k} \right) \vec{v}_2 + \dots + \left(r_{k-1} - \frac{t_{k-1}}{t_k} \right) \vec{v}_{k-1} + \frac{r_k}{t_k} \vec{w} \\ &\quad + r_{k+1} \vec{v}_{k+1} + \dots + r_n \vec{v}_n, \end{aligned}$$

so $\vec{v} \in \text{sp}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_{k-1}, \vec{w}, \vec{v}_{k+1}, \dots, \vec{v}_n)$ and since \vec{v} is an arbitrary vector in V then $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_{k-1}, \vec{w}, \vec{v}_{k+1}, \dots, \vec{v}_n\}$ is a spanning set.

Second, we must show linear independence of $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_{k-1}, \vec{w}, \vec{v}_{k+1}, \dots, \vec{v}_n\}$. Suppose $r_1 \vec{v}_1 + r_2 \vec{v}_2 + \dots + r_{k-1} \vec{v}_{k-1} + r_k \vec{w} + r_{k+1} \vec{v}_{k+1} + \dots + r_n \vec{v}_n = \vec{0}$.

Then $r_1 \vec{v}_1 + r_2 \vec{v}_2 + \dots + r_{k-1} \vec{v}_{k-1} + r_k (t_1 \vec{v}_1 + t_2 \vec{v}_2 + \dots + t_k \vec{v}_k) + r_{k+1} \vec{v}_{k+1} + \dots + r_n \vec{v}_n = \vec{0}$, or

SECTION 3.2
EXERCISE #33 (continued)

$$(r_1 + r_k t_1) \vec{v}_1 + (r_2 + r_k t_2) \vec{v}_2 + \dots + (r_{k-1} + r_k t_{k-1}) \vec{v}_{k-1} + r_k t_k \vec{v}_k + r_{k+1} \vec{v}_{k+1} + \dots + r_n \vec{v}_n = \vec{0}$$

Since, being a basis, $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is linearly independent (Definition 3.6) and so $r_1 + r_k t_1 = r_2 + r_k t_2 = \dots = r_{k-1} + r_k t_{k-1} = r_k t_k = r_{k+1} = \dots = r_n = 0$.
So $r_{k+1} = r_{k+2} = \dots = r_n = 0$ and, since $t_k \neq 0$,

$$r_k = 0. \text{ So } r_1 + r_k t_1 = r_1 = 0, r_2 + r_k t_2 = r_2 = 0,$$

$$\dots, r_{k-1} + r_k t_{k-1} = r_{k-1} = 0. \text{ Thus in, } r_1 = r_2 = \dots = r_n = 0.$$

So $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_{k-1}, \vec{w}, \vec{v}_{k+1}, \dots, \vec{v}_n\}$ is linearly independent.

Since $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_{k-1}, \vec{w}, \vec{v}_{k+1}, \dots, \vec{v}_n\}$ is a linearly independent spanning set in V then by Definition 3.6 it is a basis for V . ■