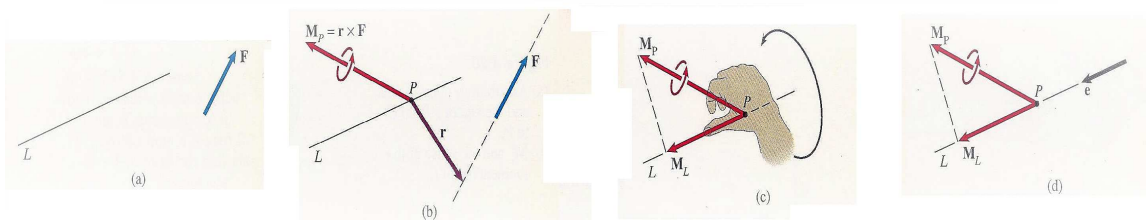


## Section 4.3. Moment of a Force About a Line

**Definition.** The moment of  $\vec{F}$  about a line  $L$  is the component of  $\vec{M}_P$  parallel to  $L$  (where  $P$  is an arbitrary point on  $L$ ; see Figure 4.18, page 153). If  $\hat{e}$  is a unit vector along  $L$ , then the moment about  $L$  is

$$\vec{M}_L = (\hat{e} \cdot \vec{M}_P)\hat{e} = (\hat{e} \cdot \vec{r} \times \vec{F})\hat{e}$$

where  $\vec{r}$  is a vector from  $L$  to the line of action of  $\vec{F}$ .



**Figure 4.18.** (a) The line  $L$  and force  $\mathbf{F}$ . (b)  $\mathbf{M}_P$  is the moment of  $\mathbf{F}$  about any point  $P$  on  $L$ .  
 (c) The component  $\mathbf{M}_L$  is the moment of  $\mathbf{F}$  about  $L$ . (d) The unit vector  $\mathbf{e}$  along  $L$ .

**Note.** If  $\hat{e} \cdot \vec{M}_P$  is positive,  $\vec{M}_L$  points in the direction of  $\hat{e}$ , and if  $\hat{e} \cdot \vec{M}_P$  is negative,  $\vec{M}_L$  points in the direction opposite to  $\hat{e}$ .

**Note.** The product  $\hat{e} \cdot \vec{r} \times \vec{F}$  is called a *scalar triple product* (or “mixed triple product”) and can be calculated as

$$\hat{e} \cdot \vec{r} \times \vec{F} = \begin{vmatrix} e_x & e_y & e_z \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}.$$

**Example.** Page 164 Number 4.106.

*Revised: 9/26/2018*