

## Section 1.2. Sets

**Note.** Ironically, we never formally define a set, but leave it as the intuitive idea of a “collection” of objects called “elements.” In this section we present several ideas from “naive” set theory; for a more treatment, see my online notes for [Introduction to Set Theory](#). We also define some functions on sets. Such functions will play an important role in the future. We assume a familiarity with sets of real numbers at the level of Calculus 1 where sets are described using interval notation or inequalities:

$$\{x \in \mathbb{R} \mid 1 \leq 2\} = \{x \in \mathbb{R} \mid x \in [1, 2)\}.$$

**Definition.** A set  $C$  is *countable* if it is either finite or if it has “as many elements” as there are natural numbers (that is, there is a one to one and onto function from  $C$  to  $\mathbb{N}$ ).

**Note.** Some infinite countable sets are  $\mathbb{N}$ ,  $\mathbb{Z}$ ,  $\mathbb{Q}$ , and  $\mathbb{Q} \times \mathbb{Q}$ . Surprisingly, there are uncountable sets! The interval  $(0, 1)$  is not countable (see Theorem 1-20 of my Analysis 1 notes for [1.3. The Completeness Axiom](#)).

**Definition 1.2.2.** The *complement* of an event  $A$  is the set of all elements in  $\mathcal{C}$  which are not in  $A$ , denoted  $A^c$ . That is,  $A^c = \{x \in \mathcal{C} \mid x \notin A\}$ .

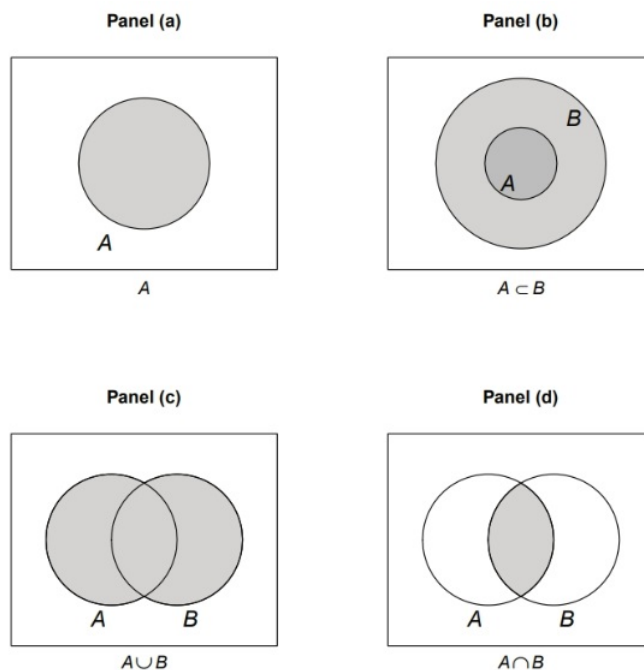
**Definition 1.2.2.** If each element of set  $A$  is also an element of set  $B$ , then set  $A$  is a *subset* of set  $B$ , denoted  $A \subset B$  or  $B \supset A$ . If  $A \subset B$  and  $B \subset A$  then sets  $A$  and  $B$  are *equal*, denoted  $A = B$ .

**Definition 1.2.3.** Let  $A$  and  $B$  be events. The *union* of  $A$  and  $B$  is the set of all elements that are in  $A$  or in  $B$  or in both  $A$  and  $B$ , denoted  $A \cup B$ .

**Definition 1.2.4.** Let  $A$  and  $B$  be events. The *intersection* of  $A$  and  $B$  is the set of all elements that are in both  $A$  and  $B$ , denoted  $A \cap B$ .

**Definition 1.2.5.** Let  $A$  and  $B$  be events. Then  $A$  and  $B$  are *disjoint* if  $A \cap B = \emptyset$ , where  $\emptyset$  denotes the empty set. If  $A$  and  $B$  are disjoint then  $A \cup B$  is called the *disjoint union*, which we denote as  $A \cup B$  (though the text does not use this notation).

**Note.** The text illustrates the definitions above definitions with Venn diagrams as follows:



**Theorem 1.2.A.** For any sets (events)  $A$ ,  $B$ , and  $C$  we have

$$A \cap (B \cup C) = (A \cap B) \cup (A \cap C) \text{ and } A \cup (B \cap C) = (A \cup B) \cap (A \cup C).$$

These are the *distributive laws*.

**Theorem 1.2.B. De Morgan's Laws.** For any two sets (events)  $A$  and  $B$ , we have

$$(A \cap B)^c = A^c \cup B^c \text{ and } (A \cup B)^c = A^c \cap B^c.$$

**Definition.** For sets  $A_1, A_2, \dots, A_n$  define the *union* and *intersection*, respectively, as

$$A_1 \cup A_2 \cup \dots \cup A_n = \bigcup_{i=1}^n A_i = \{x \mid x \in A_i \mid \text{for some } i \in \{1, 2, \dots, n\}\},$$

$$A_1 \cap A_2 \cap \dots \cap A_n = \bigcap_{i=1}^n A_i = \{x \mid x \in A_i \mid \text{for all } i \in \{1, 2, \dots, n\}\}.$$

For a sequence of sets  $A_1, A_2, \dots$  define the *union* and *intersection*, respectively, as

$$A_1 \cup A_2 \cup \dots = \bigcup_{i=1}^{\infty} A_i = \{x \mid x \in A_i \mid \text{for some } i \in \mathbb{N}\},$$

$$A_1 \cap A_2 \cap \dots = \bigcap_{i=1}^{\infty} A_i = \{x \mid x \in A_i \mid \text{for all } i \in \mathbb{N}\}.$$

More generally, for any collection of set  $A_i$  where  $i \in I$  and  $I$  is some indexing set (finite, countable, or uncountable), define the *union* and *intersection*, respectively, as

$$\bigcup_{i \in I} A_i = \{x \mid x \in A_i \mid \text{for some } i \in I\},$$

$$\bigcap_{i \in I} A_i = \{x \mid x \in A_i \mid \text{for all } i \in I\}.$$

**Note.** De Morgan's Laws hold for finite, countable, and arbitrary unions.

**Example 1.2.4.** Suppose  $\mathcal{C}$  is the interval of real numbers  $(0, 5)$ . Define  $C_n = (1 - 1/n, 2 + 1/n)$  and  $D_n = (1/n, 3 - 1/n)$  for  $n \in \mathbb{N}$ . Then  $\cup_{n=1}^{\infty} C_n = (0, 3)$ ,  $\cap_{n=1}^{\infty} C_n = [1, 2]$ ,  $\cup_{n=1}^{\infty} D_n = (0, 3)$ , and  $\cap_{n=1}^{\infty} D_n = (1, 2)$ . This example motivates the following definition.

**Definition.** A sequence of sets  $\{A_n\}$  is *monotone nondecreasing* (also called “monotone increasing”) if  $A_n \subset A_{n+1}$  for  $n \in \mathbb{N}$ . The sequence is *monotone nonincreasing* (also called “monotone decreasing”) if  $A_n \supset A_{n+1}$  for  $n \in \mathbb{N}$ . For monotone nondecreasing sequence  $\{A_n\}$  define the *limit*  $\lim_{n \rightarrow \infty} A_n = \cup_{n=1}^{\infty} A_n$ . For monotone increasing sequence  $\{A_n\}$  define the *limit*  $\lim_{n \rightarrow \infty} A_n = \cap_{n=1}^{\infty} A_n$ .

**Definition.** A function that maps sets into the real numbers is called a *set function*.

**Example.** If  $f(x) = e^{-x^2}$  then we can define set function  $F$  on closed intervals of real numbers as  $F([a, b]) = \int_a^b e^{-x^2} dx$ .

**Note.** We will often deal with definite integrals. For  $A \subset \mathbb{R}$  and  $f$  a real valued function, we denote the integral of  $f$  over  $A$  as  $\int_A f(x) dx$ , though we may have legitimate concerns about the integral existing (or being finite). If  $A \subset \mathbb{R} \times \mathbb{R} = \mathbb{R}^2$  then we denote an integral of  $g : \mathbb{R}^2 \rightarrow \mathbb{R}$  as  $\int \int_A g(x, y) dx dy$ .

**Example 1.2.7.** Let  $\mathcal{C} = \mathbb{N}$  and let  $A \subset \mathcal{C}$ . Define the set function

$$Q(A) = \sum_{n \in A} \left(\frac{2}{3}\right)^n.$$

Then

$$Q(\mathcal{C}) = \sum_{n \in \mathbb{N}} \left(\frac{2}{3}\right)^n = \sum_{i=0}^{\infty} \left(\frac{2}{3}\right)^n = \frac{1}{1 - 2/3} = 3.$$

Let  $B$  be the set of off positive integers. Then

$$Q(B) = \sum_{n \in B} \left(\frac{2}{3}\right)^n = \sum_{i=0} \left(\frac{2}{3}\right)^{2n+1} = \frac{2}{3} \sum_{i=0}^{\infty} \left(\frac{4}{9}\right)^n = \frac{2}{3} \frac{1}{1 - 4/9} = \frac{6}{5}. \quad \square$$

**Example 1.2.9.** Let  $\mathcal{C} = \mathbb{R}^n$ . for  $A \subset \mathcal{C}$  define the set function  $Q(A) = \int \int \cdots \int_A dx_1 dx_2 \cdots dx_n$ , provided the integral exists (notice this is an integral of the function 1 so we expect the quantity  $Q(A)$  to be the  $n$ -dimensional volume of  $A$ ). Let

$$A = \{(x_1, x_2, \dots, x_n) \mid - \leq x_1 \leq x_2 \text{ and } 0 \leq x_i \leq 1 \text{ for } i \in \{2, 3, 4, \dots, n\}\}.$$

Then

$$\begin{aligned} Q(A) &= \int_0^1 \int_0^1 \cdots \int_0^1 \int_0^{x_2} dx_1 dx_2 \cdots dx_n = (1) \int_0^1 \left( \int_0^{x_2} dx_1 \right) dx_2 \\ &= \int_0^1 (x_1|_{x_1=0}^{x_1=x_2}) dx_2 = \int_0^1 (x_2 - 0) dx_2 = \frac{1}{2} x_2^2|_{x_2=0}^{x_2=1} = \frac{1}{2}. \end{aligned}$$

If  $B = \{(x_1, x_2, \dots, x_n) \mid 0 \leq x_1 \leq x_2 \leq \cdots \leq x_n \leq 1\}$  then

$$\begin{aligned} Q(B) &= \int_0^1 \int_0^{x_n} \cdots \int_0^{x_3} \int_0^{x_2} dx_1 dx_2 \cdots dx_{n-1} dx_n \\ &= \int_0^1 \int_0^{x_n} \cdots \int_0^{x_3} (x_1|_{x_1=0}^{x_1=x_2}) dx_2 \cdots dx_{n-1} dx_n \end{aligned}$$

$$\begin{aligned} &= \int_0^1 \int_0^{x_n} \cdots \int_0^{x_3} x_2 dx_2 \cdots dx_{n-1} dx_n \\ &= \int_0^1 \int_0^{x_n} \cdots \int_0^{x_4} \frac{1}{2} x_3^2 dx_3 \cdots dx_{n-1} dx_n \\ &= \int_0^1 \int_0^{x_n} \cdots \int_0^{x_5} \frac{1}{(1)(2)(3)} x_4^3 dx_4 \cdots dx_{n-1} dx_n \\ &= \cdots = \int_0^1 \frac{1}{(n-1)!} x_n^{n-1} dx_n = \frac{1}{n!} x_n^n \Big|_{x_n=0}^{x_n=1} = \frac{1}{n!}. \end{aligned}$$

□

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