

## Section 2.3. Conditional Distributions and Expectations

**Note.** We now consider conditional distributions in which a random variable is assumed to assume a specific value (in the support of that random variable) and then the distribution of a second random variable is defined by taking into consideration of the value of the first random variable. This generalizes the conditional concept introduced in [1.4. Conditional Probability and Independence](#).

**Note 2.3.A/Definition.** Let  $X_1$  and  $X_2$  be discrete random variables with joint probability mass function  $p_{X_1, X_2}(x_1, x_2)$  and support  $\mathcal{S}$ . Let  $p_{X_1}(x_1)$  and  $p_{X_2}(x_2)$  be the marginal probability mass functions of  $X_1$  and  $X_2$  as defined in Section 2.1. For  $x_1$  in the support  $\mathcal{S}_{X_1}$  of  $p_{X_1}$ , we have by the definition of conditional probability (Definition 1.4.1) that

$$P(X_2 = x_2 \mid X_1 = x_1) = \frac{P(X_1 = x_1, X_2 = x_2)}{P(X_1 = x_1)} = \frac{p_{X_1, X_2}(x_1, x_2)}{p_{X_1}(x_1)}$$

for all  $x_2$  in the support  $\mathcal{S}_{X_2}$  of  $X_2$ . Denote this function as

$$p_{X_2|X_1}(x_2 \mid x_1) = \frac{p_{X_1, X_2}(x_1, x_2)}{p_{X_1}(x_1)} \text{ for } x_2 \in \mathcal{S}_{X_2}.$$

Notice that  $p_{X_2|X_1}(x_2 \mid x_1) \geq 0$  for all  $x_2 \in X_2$  and

$$\begin{aligned} \sum_{x_2 \in X_2} p_{X_2|X_1}(x_2 \mid x_1) &= \sum_{x_2 \in X_2} \frac{p_{X_1, X_2}(x_1, x_2)}{p_{X_1}(x_1)} = \frac{1}{p_{X_1}(x_1)} \sum_{x_2 \in X_2} p_{X_1, X_2}(x_1, x_2) \\ &= \frac{1}{p_{X_1}(x_1)} p_{X_1}(x_1) = 1, \end{aligned}$$

so  $p_{X_2|X_1}(x_2 \mid x_1)$  is in fact a probability mass function called the *conditional probability mass function* of  $X_2$  given  $X_1 = x_1$ . We similarly define for  $x_2 \in \mathcal{S}_{X_2}$

$$p_{X_1|X_2}(x_1 \mid x_2) = \frac{p_{X_1, X_2}(x_1, x_2)}{p_{X_2}(x_2)} \text{ for all } x_1 \in \mathcal{S}_{X_1}.$$

We may denote these functions as

$$p_{X_1|X_2}(x_1 | x_2) = p_{1|2}(x_1 | x_2) \text{ and } p_{X_2|X_1}(x_2 | x_1) = p_{2|1}(x_2, x_1).$$

**Note/Definition.** Let  $X_1$  and  $X_2$  be continuous random variables with joint probability density function  $f_{X_1, X_2}(x_1, x_2)$  and support  $\mathcal{S}$ . Let  $f_{X_1}(x_1)$  and  $f_{X_2}(x_2)$  be the marginal probability density functions as defined in Section 2.1. Motivated by the discrete case above, for  $x_1 \in X_1$  with  $f_{X_1}(x_1) > 0$  define

$$f_{X_2|X_1}(x_2 | x_1) = f_{2|1}(x_2 | x_1) = \frac{f_{X_1, X_2}(x_1, x_2)}{f_{X_1}(x_1)}.$$

We have  $f_{X_2|X_1}(x_2 | x_1)$  nonnegative and

$$\begin{aligned} \int_{-\infty}^{\infty} f_{X_2|X_1}(x_2 | x_1) dx_2 &= \int_{-\infty}^{\infty} \frac{f_{X_1, X_2}(x_1, x_2)}{f_{X_1}(x_1)} dx_2 = \frac{1}{f_{X_1}(x_1)} \int_{-\infty}^{\infty} f_{X_1, X_2}(x_1, x_2) dx_2 \\ &= \frac{1}{f_{X_1}(x_1)} f_{X_1}(x_1) = 1, \end{aligned}$$

so  $f_{X_2|X_1}(x_2 | x_1)$  is in fact a probability density function called the *conditional probability density function* of  $X_2$  given  $X_1 = x_1$ . Similarly, for  $x_2 \in X_2$  with  $f_{X_2}(x_2) > 0$  we have

$$f_{X_1|X_2}(x_1 | x_2) = f_{1|2}(x_1 | x_2) = \frac{f_{X_1, X_2}(x_1, x_2)}{f_{X_2}(x_2)}.$$

**Note.** The conditional probability that  $a < X_2 < b$  given  $X_1 = x_1$  is computed as

$$P(a < X_2 < b | X_1 = x_1) = P(a < X_2 < b | x_1) = \int_a^b f_{X_2|X_1}(x_2 | x_1) dx_2.$$

**Definition.** If  $u(X_2)$  is a function of random variable  $X_2$  then the *conditional expectation* of  $u(X_2)$  given  $X_1 = x_1$  (if it exists) is

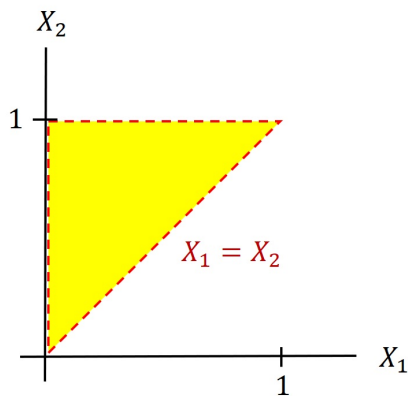
$$E[u(X_2) | X_1 = x_1] = E[u(X_2) | x_1] = \int_{-\infty}^{\infty} u(x_2) f_{X_2|X_1}(x_2 | x_1) dx_2.$$

If it exists then  $E[X_2 | x_1]$  is the *conditional mean* of the conditional distribution of  $X_2$  given  $X_1 = x_1$ . If it exists then  $E[(x_2 - E[X_2 | x_1])^2 | x_1] = \text{Var}(X_2 | x_1)$  is the *conditional variance* of the conditional distribution of  $X_2$  given  $X_1 = x_1$ . We can similarly define these quantities for  $X_1$  given  $X_2 = x_2$ .

**Example 2.3.1.** Let  $X_1$  and  $X_2$  be continuous random variables with joint probability density function

$$f(x_1, x_2) = \begin{cases} 2 & \text{for } 0 < x_1 < x_2 < 1 \\ 0 & \text{elsewhere.} \end{cases}$$

The support of  $f(x_1, x_2)$  is:



The marginal probability density functions are

$$f_{X_1}(x_1) = \int_{-\infty}^{\infty} f(x_1, x_2) dx_2 = \int_{x_2=x_1}^{x_2=1} dx_2 = 2(1 - x_1) \text{ for } 0 < x_1 < 1,$$

$$f_{X_2}(x_2) = \int_{-\infty}^{\infty} f(x_1, x_2) dx_1 = \int_{x_1=0}^{x_1=x_2} 2 dx_1 = 2x_2 \text{ for } 0 < x_2 < 1$$

and each is 0 elsewhere. The conditional probability density function of  $X_1$  given  $X_2 = x_2$  for  $0 < x_2 < 1$  is

$$f_{X_1|X_2}(x_1 | x_2) = \frac{f_{X_1, X_2}(x_1, x_2)}{f_{X_2}(x_2)} = \frac{2}{2x_2} = \frac{1}{x_2}.$$

The conditional mean of  $X_1$  given  $X_2 = x_2$  is

$$\begin{aligned} E[X_1 | x_2] &= \int_{-\infty}^{\infty} x_1 f_{X_1|X_2}(x_1 | x_2) dx_1 = \int_0^{x_2} x_1 \frac{1}{x_2} dx_1 \\ &= \frac{1}{x_2} \left( \frac{1}{2}(x_2)^2 - \frac{1}{2}(0)^2 \right) = \frac{x_2}{2} \text{ for } 0 < x_2 < 1, \end{aligned}$$

so the conditional variance of  $X_1$  given  $X_2$  is

$$\begin{aligned} \text{Var}(X_1 | x_2) &= E[(X_1 - E[X_1 | x_1])^2] = \int_{-\infty}^{\infty} \left( x_1 - \frac{x_2}{2} \right)^2 f_{X_1, X_2}(x_1 | x_2) dx_1 \\ &= \int_0^{x_1} \left( x_1 - \frac{x_2}{2} \right)^2 \left( \frac{1}{x_2} \right) dx_1 = \int_0^{x_2} \frac{x_1^2 - x_1 x_2 + x_2^2/4}{x_2} dx_1 \\ &= \frac{1}{x_2} \left( \frac{1}{3}x_2^3 - \frac{1}{2}x_2^3 + \frac{1}{4}x_2^3 \right) = \frac{x_2^2}{12} \text{ for } 0 < x_2 < 1. \end{aligned}$$

Also,

$$\begin{aligned} P\left(0 < X_1 < \frac{1}{2} \mid X_2 = \frac{3}{4}\right) &= \int_0^{1/2} f_{X_1, X_2}\left(x_1 \mid \frac{3}{4}\right) dx_1 \\ &= \int_0^{1/2} \frac{1}{3/4} dx_1 = \frac{4}{3} \left( \frac{1}{2} - 0 \right) = \frac{2}{3}. \end{aligned}$$

(We can use the marginal distribution  $f_{X_1}(x_1)$  to find that  $P(0 < X_1 < 1/2) = 3/4$ , so the value of  $X_2$  affects probabilities of the value of  $X_1$ .)

**Note.** In the previous example, we have  $P(X_2 = 3/4) = 0$  since  $X_2$  is a continuous, so in computing  $P(0 < X_1 < 1/2 | X_2 = 3/4)$  we have **conditioned on a probability 0 event**, and yet the conditional probability is still defined!

**Theorem 2.3.1.** Let  $(X_1, X_2)$  be a random vector such that the variance of  $X_2$  is finite. Then

(a)  $E[E[X_2 | X_1]] = E[X_2]$ , and

(b)  $\text{Var}([E[X_2 | X_1]) \leq \text{Var}(X_2)$ .

**Note.** The book comments (see page 115) that, since the mean of both  $X_2$  and  $E[X_2 | X_1]$  is  $\mu_2$ , if we wish to approximate  $\mu_2$  then because  $\text{Var}(X_2) \geq \text{Var}(E[X_2 | X_1])$  then we can put more “reliance” on estimates of  $E[X_1 | X_2]$  to guess the unknown  $\mu_2$ .

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