2.1 Inertial Frames of Reference

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**Definition.** A frame of reference is a system of spatial coordinates and possibly

a temporal coordinate. A frame of reference in which the Law of Inertia holds is

an inertial frame or inertial system. An observer at rest (i.e., with zero velocity)

in such a system is an *inertial observer*.

**Note.** The main idea of an inertial observer in an inertial frame is that the observer

experiences no acceleration (and therefore no net force). If S is an inertial frame

and S' is a frame (i.e. coordinate system) moving uniformly relative to S, then S'

is itself an inertial frame (see Exercise II-1). Frames S and S' are equivalent in the

sense that there is no mechanical experiment that can be conducted to determine

whether either frame is at rest or in uniform motion (that is, there is **no preferred** 

frame). This is called the Galilean (or classical) Principle of Relativity.

Special relativity deals with the observations of phenomena by inertial

observers and with the comparison of observations of inertial observers in equivalent

frames (i.e., NO ACCELERATION!). General relativity takes into consideration

the effects of acceleration (and therefore gravitation) on observations.

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