Differential Geometry; Chapter IV Study Guide

The following is a *brief* list of topics covered in Chapter IV, "Metric Vector Spaces," of Dodson and Poston's *Tensor Geometry*, 2nd edition. This list is not meant to be comprehensive, but only gives a list of several important topics.

IV.1. Metrics.

Bilinear form, symmetric, anti-symmetric, non-degenerate, positive/negative definite, indefinite, metric tensor, inner product, metric vector space, inner product space, standard inner product on \mathbb{R}^n , Lorentz metric on \mathbb{R}^4 , determinant metric, length of a vector with respect to a metric tensor **G**, spacetime interval, timelike, spacelike, lightlike, lightcones, norm, Triangle Inequality, norm induced by an inner product, size of a vector, unit vector, Schwarz's Inequality (Lemma IV.1.07), orthogonal vectors, perp space (or orthogonal complement), mappings \mathbf{G}_{\downarrow} and \mathbf{G}_{\uparrow} in metric vector space (X, **G**), metric tensor and metric inner product \mathbf{G}^* induced by metric tensor and metric inner product **G**.

IV.2. Maps.

Orthogonal projection operator and resulting components of a vector, orthogonal complements in the Lorentz space \mathbb{H}^2 , orthogonal complement S^{\perp} , decomposition of \mathbf{x} as an element of subspace S and an element of subspace S^{\perp} (Lemma IV.2.04), direct sum of subspaces S and S^{\perp} , dimensions of S and S^{\perp} (Corollary IV.2.05), isometry (orthogonal operator or unitary operator), adjoint of a linear operator, self adjoint linear operator and properties (Lemma IV.2.A), \mathbf{A} is an orthogonal operator if and only if $\mathbf{A}^T \mathbf{A} = \mathbf{I}$ (Lemma IV.2.09), \mathbf{A} is orthogonal if and only it \mathbf{A}^T is orthogonal (Corollary IV.2.10).

IV.3. Coordinates.

Matrix representations of \mathbf{G}_{\downarrow} and \mathbf{G}_{\uparrow} with respect to bases β and β' (Note IV.3.B), matrix representation of \mathbf{G}^* (Note IV.3.C), orthogonal set of vectors, orthonormal set, orthonormal basis, every metric vector space has at least one orthonormal basis (Theorem IV.2.05), signature of metric \mathbf{G} , Sylvester's Law of Inertia (Corollary IV.3.10), the signature of \mathbf{G}^* equals the signature of \mathbf{G} (Corollary IV.3.12), the matrix representation relationship $[\mathbf{A}^T]^{\beta}_{\beta} = ([\mathbf{A}]^{\beta}_{\beta})^t$ where β is an orthonormal basis (Lemma IV.3.13; T represents that adjoint

of a linear operator and t represents the transpose of a matrix), entries of the matrices representing $[\mathbf{A}^T]$ and $[\mathbf{A}]^t$ with respect to an orthonormal basis (Lemma IV.3.14) and the corresponding result for self-adjoint operators (Corollary IV.3.15), orthogonal linear operators have matrix representations with orthonormal row and columns (Lemma IV.3.16).

IV.4. Diagonalizing Symmetric Operators.

Fundamental Theorem of Real Symmetric Matrices, a maximal vector for a linear operator in an inner product space (Definition IV.4.01), operator norm, symmetric linear operator, eigenvectors of **A** for eigenvalue $+||\mathbf{A}||$ or $-||\mathbf{A}||$ (Lemma IV.4.03), operator on \mathbf{x}^{\perp} induced by **A** (Lemma IV.4.04), symmetric linear operators yield orthonormal bases of eigenvectors (Theorem IV.4.05), comments about eigenvalues with respect to difference bases (Note IV.4.A), dimension of an eigenspace for a symmetric operator (Corollary IV.4.07), eigenvalues of a symmetric linear operator are real (Corollary IV.4.08), principal directions of a symmetric bilinear form, isotropic linear operator in an inner product space, orthonormal bases of eigenvectors for Lorentz space \mathbb{L}^4 (Lemma IV.4.13).