

Graph Theory

Chapter 14. Vertex Colourings

14.4. Perfect Graphs—Proofs of Theorems

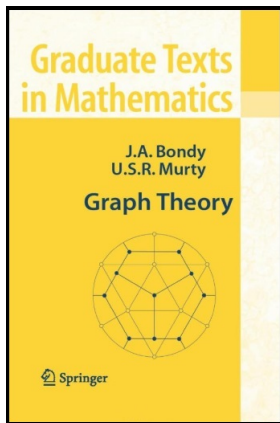


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Proposition 14.15. Let S be a stable set in a minimally imperfect graph G . Then $\omega(G - S) = \omega(G)$.

Proof. This is easy with the use of Exercise 14.4.5, which states that for S a stable set in a minimally imperfect graph G we have

$$\omega(G - S) \leq \omega(G) \leq \chi(G) - 1 \leq \chi(G - S) = \omega(G - S).$$

Since the left and right terms are the same, then the inequalities reduce to equalities. □

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Lemma 14.16

Lemma 14.16. Let G be a minimally imperfect graph with stability number α and clique number ω . Then G contains $\alpha\omega + 1$ stable sets $S_0, S_1, \dots, S_{\alpha\omega}$ and $\alpha\omega + 1$ cliques $C_0, C_1, \dots, C_{\alpha\omega}$ such that:

- each vertex of G belongs to precisely α of the stable sets S_i ,
- each clique C_j has ω vertices,
- $C_i \cap S_j = \emptyset$ for $0 \leq i \leq \alpha\omega$, and
- $|C_i \cap S_j| = 1$ for $0 \leq i < j \leq \alpha\omega$.

Proof. Let S_0 be a stable set of α vertices of G , and let $v \in S_0$ (of course $|S_0| \geq 1$). The graph $G - v$ is perfect because G is minimally imperfect (note that $G - v$ is the subgraph of G induced by $V(G) \setminus \{v\}$). So by the definition of “perfect graph” and Note 14.1.B,

$$\chi(G - v) = \omega(G - v) \leq \omega(G).$$

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Lemma 14.16 (continued 1)

Proof (continued). Since $|S_0| = \alpha$ then there are α such v in S_0 , since each family \mathcal{S}_v contains ω stable sets, then there are $\alpha\omega$ stable sets in the totality of the families $\mathcal{S}_1, \mathcal{S}_2, \dots, \mathcal{S}_\alpha$. Denote these stable sets as $S_1, S_2, \dots, S_{\alpha\omega}$. We'll see below that each S_j is nonempty when we establish the fourth claim. For each v a vertex of G where $v \in S_0$, we have that $v \in S_j$ for some unique S_j in family \mathcal{S}_w where $w \neq v$. So this v is in S_0 and all but one of $S_1, S_2, \dots, S_\alpha$; that is, v is in α of the stable sets S_j . For each v a vertex of G where $v \notin S_0$, we have that v is in some unique S_j in family \mathcal{S}_j for each $1 \leq j \leq \alpha$; that is, v is in α of the stable sets S_j . Therefore the first claim holds.

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By Proposition 14.15, the clique numbers satisfy $\omega(G - S_i) = \omega(G)$ for each $0 \leq i \leq \alpha\omega$. Therefore there is a maximum clique C_i of $G - S_i$ that is also a maximum clique of G . Each C_i has $\omega = \omega(G)$ vertices, so the second claim holds. So there is a maximum clique C_i of G that is disjoint from S_i and the third claim holds.

Lemma 14.16 (continued 1)

Proof (continued). Since $|S_0| = \alpha$ then there are α such v in S_0 , since each family \mathcal{S}_v contains ω stable sets, then there are $\alpha\omega$ stable sets in the totality of the families $\mathcal{S}_1, \mathcal{S}_2, \dots, \mathcal{S}_\alpha$. Denote these stable sets as $S_1, S_2, \dots, S_{\alpha\omega}$. We'll see below that each S_j is nonempty when we establish the fourth claim. For each v a vertex of G where $v \in S_0$, we have that $v \in S_j$ for some unique S_j in family \mathcal{S}_w where $w \neq v$. So this v is in S_0 and all but one of $\mathcal{S}_1, \mathcal{S}_2, \dots, \mathcal{S}_\alpha$; that is, v is in α of the stable sets S_j . For each v a vertex of G where $v \notin S_0$, we have that v is in some unique S_j in family \mathcal{S}_j for each $1 \leq j \leq \alpha$; that is, v is in α of the stable sets S_j . Therefore the first claim holds.

By Proposition 14.15, the clique numbers satisfy $\omega(G - S_i) = \omega(G)$ for each $0 \leq i \leq \alpha\omega$. Therefore there is a maximum clique C_i of $G - S_i$ that is also a maximum clique of G . Each C_i has $\omega = \omega(G)$ vertices, so the second claim holds. So there is a maximum clique C_i of G that is disjoint from S_i and the third claim holds.

Lemma 14.16 (continued 2)

Lemma 14.16. Let G be a minimally imperfect graph with stability number α and clique number ω . Then G contains $\alpha\omega + 1$ stable sets $S_0, S_1, \dots, S_{\alpha\omega}$ and $\alpha\omega + 1$ cliques $C_0, C_1, \dots, C_{\alpha\omega}$ such that:

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Proof (continued). Because each of the ω vertices of C_i lie in α of the stable sets (by the first claim), there are $\alpha\omega + 1$ stable sets (but $C_i \cap S_j = \emptyset$ for $0 \leq i \leq \alpha\omega$ by the third claim), and no two vertices of clique C_i can belong to a common stable set (since vertices of a clique are adjacent and vertices of a stable set are not adjacent), then each C_i shares exactly one point with each S_j where $i \neq j$. That is, $|C_i \cap S_j| = 1$ for $0 \leq i < j \leq \alpha\omega$, and the fourth claim holds. □

Theorem 14.14

Theorem 14.14. A graph G is perfect if and only if every induced subgraph H of G satisfies the inequality $v(H) \leq \alpha(H)\omega(H)$.

Proof. Suppose that G is a perfect graph so that $\chi(H) = \omega(H)$ for all induced subgraphs H of G . Let H be any (fixed) induced subgraph of G . Then H is $\omega(H)$ -colourable (since $\chi(H) = \omega(H)$). Since a colour class is an independent set and the largest independent set is of size α , then the number of vertices satisfies $v(H) \leq \alpha(H)\chi(H) = \alpha(H)\omega(H)$. So if G is perfect, then for every induced subgraph H of G we have $v(H) \leq \alpha(H)\omega(H)$.

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We now prove the converse (actually, the contrapositive of the converse). Suppose G is not perfect. We want to show that $v(G) \geq \alpha(G)\omega(G) + 1$. If we can show this for minimally imperfect graphs, then it will hold for all imperfect graphs. So without loss of generality, suppose G is minimally imperfect.

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Theorem 14.14 (continued 1)

Proof (continued). Consider the stable sets S_i for $0 \leq i \leq \alpha\omega$ and the cliques C_i for $0 \leq i \leq \alpha\omega$ as given for a minimally imperfect graph in Lemma 14.16. Let \mathbf{S} and \mathbf{C} be the $n \times (\alpha\omega + 1)$ incidence matrices of the families. Now the transpose of \mathbf{S} , \mathbf{S}^t , is $(\alpha\omega + 1) \times n$ and so the product $\mathbf{S}^t\mathbf{C}$ exists and is $(\alpha\omega + 1) \times (\alpha\omega + 1)$. Now the i th row of \mathbf{S}^t consists of 0's and 1's, where the k th entry is 1 if $k \in S_i$ and 0 if $k \notin S_i$. The j th column of \mathbf{C} consists of 0's and 1's where the k th entry is 1 if $k \in C_j$ and 0 if $k \notin C_j$. The (i, j) -entry of $\mathbf{S}^t\mathbf{C}$ is the inner product (or "dot product") of the i th row of \mathbf{S}^t and the j th column of \mathbf{C} . By the third claim of Lemma 14.16 we have $C_i \cap S_i = \emptyset$ for $0 \leq i \leq \alpha\omega$, so in the i th row of \mathbf{S}^t and the i th column of \mathbf{C} , if the k th entry of one of these is 1 then the k th entry of the other is 0. So the inner product is 0 and the (i, i) -entry of $\mathbf{S}^t\mathbf{C}$ is 0. By the fourth claim of Lemma 14.16 we have $|C_i \cap S_j| = 1$ for $0 \leq i < j \leq \alpha\omega$, so in the i th row of \mathbf{S}^t and the j th column of \mathbf{C} the k entry of both is 1 only once. So the inner product is 1 and the (i, j) -entry of $\mathbf{S}^t\mathbf{C}$ is 1 for $i \neq j$.

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Theorem 14.14 (continued 2)

Proof (continued). Therefore, $\mathbf{S}^t\mathbf{C} = \mathbf{J} - \mathbf{I}$ where \mathbf{J} is the $(\alpha\omega + 1) \times (\alpha\omega + 1)$ matrix of all 1's and \mathbf{I} is the $(\alpha\omega + 1) \times (\alpha\omega + 1)$ identity matrix. Now $\mathbf{J} - \mathbf{I}$ is nonsingular (i.e., invertible) because the inverse is $(1/(\alpha\omega))\mathbf{J} - \mathbf{I}$ because

$$\begin{aligned} (\mathbf{J} - \mathbf{I}) \left(\frac{1}{\alpha\omega} \mathbf{J} - \mathbf{I} \right) &= \frac{1}{\alpha\omega} \mathbf{J}^2 - \mathbf{J} - \frac{1}{\alpha\omega} \mathbf{J} + \mathbf{I}^2 = \frac{1}{\alpha\omega} \mathbf{J}^2 - \left(1 + \frac{1}{\alpha\omega} \right) \mathbf{J} + \mathbf{I} \\ &= \frac{1}{\alpha\omega} ((\alpha\omega + 1)\mathbf{J}) - \left(\frac{\alpha\omega + 1}{\alpha\omega} \right) \mathbf{J} + \mathbf{I} = \frac{\alpha\omega + 1}{\alpha\omega} \mathbf{J} - \frac{\alpha\omega + 1}{\alpha\omega} \mathbf{J} + \mathbf{I} = \mathbf{I}. \end{aligned}$$

This shows that $(1/(\alpha\omega))\mathbf{J} - \mathbf{I}$ is a right inverse of $\mathbf{J} - \mathbf{I}$, but since \mathbf{I} and \mathbf{J} commute, this is sufficient to establish that we have a two-sided inverse (see also “Theorem 1.11. A Commutative Property” in my Linear Algebra [MATH 2010] online notes on [Section 1.5. Inverses of Matrices, and Linear Systems](#)). Since $\mathbf{J} - \mathbf{I}$ is invertible, then it must be a full-rank $\alpha\omega + 1$ (see “Theorem 2.6. An Invertible Criteria” in my Linear Algebra online notes on [Section 2.2. The Rank of a Matrix](#)).

Theorem 14.14 (continued 2)

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$$\begin{aligned} (\mathbf{J} - \mathbf{I}) \left(\frac{1}{\alpha\omega} \mathbf{J} - \mathbf{I} \right) &= \frac{1}{\alpha\omega} \mathbf{J}^2 - \mathbf{J} - \frac{1}{\alpha\omega} \mathbf{J} + \mathbf{I}^2 = \frac{1}{\alpha\omega} \mathbf{J}^2 - \left(1 + \frac{1}{\alpha\omega} \right) \mathbf{J} + \mathbf{I} \\ &= \frac{1}{\alpha\omega} ((\alpha\omega + 1)\mathbf{J}) - \left(\frac{\alpha\omega + 1}{\alpha\omega} \right) \mathbf{J} + \mathbf{I} = \frac{\alpha\omega + 1}{\alpha\omega} \mathbf{J} - \frac{\alpha\omega + 1}{\alpha\omega} \mathbf{J} + \mathbf{I} = \mathbf{I}. \end{aligned}$$

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Theorem 14.14 (continued 3)

Theorem 14.14. A graph G is perfect if and only if every induced subgraph H of G satisfies the inequality $\nu(H) \leq \alpha(H)\omega(H)$.

Proof (continued). Recall that the rank of a matrix in the (common) dimension of the row space and the column space. In general, $\text{rank}(AB) \leq \min\{\text{rank}(A), \text{rank}(B)\}$ (see Exercises 2.2.18 and 2.2.20 in J. Fraleigh and R. Beauregard's *Linear Algebra*, 3rd Edition, Addison-Wesley (1994), or see Theorem 3.3.5 in my online notes for Theory of Matrices [MATH 5090] on [Section 3.3. Matrix Rank and the Inverse of a Full Rank Matrix](#)) so

$$\alpha\omega + 1 = \text{rank}(\mathbf{J} - \mathbf{I}) = \text{rank}(\mathbf{S}^t\mathbf{C}) \leq \min\{\text{rank}(\mathbf{S}^t), \text{rank}(\mathbf{C})\}.$$

Now the row rank equals the column rank for any matrix (see "Theorem 2.4. Row Rank Equals Column Rank" in my Linear Algebra notes on [Section 2.2. The Rank of a Matrix](#)), so we have $\text{rank}(\mathbf{S}) = \alpha\omega + 1$ and $\text{rank}(\mathbf{C}) = \alpha\omega + 1$ since the rank can't be greater than the number of rows or the number of columns.

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Now the row rank equals the column rank for any matrix (see “Theorem 2.4. Row Rank Equals Column Rank” in my Linear Algebra notes on [Section 2.2. The Rank of a Matrix](#)), so we have $\text{rank}(\mathbf{S}) = \alpha\omega + 1$ and $\text{rank}(\mathbf{C}) = \alpha\omega + 1$ since the rank can't be greater than the number of rows or the number of columns.

Theorem 14.14 (continued 4)

Theorem 14.14. A graph G is perfect if and only if every induced subgraph H of G satisfies the inequality $\nu(H) \leq \alpha(H)\omega(H)$.

Proof (continued).

Both \mathbf{S} and \mathbf{C} have n row, so the number of rows must be at least as big as the rank, hence $n \geq \alpha\omega + 1$. That is, for minimally imperfect graph G , $\nu(G) \geq \alpha(G)\omega(G) + 1$. As explained above, the general claim now holds. □