## Advanced Differential Equations

## Chapter 1. Systems of Linear Differential Equations

Section 1.8. General Linear Systems—Proofs of Theorems


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## Theorem 1.8.1

Theorem 1.8.1. If $\vec{x}(t)$ is a solution of

$$
\begin{equation*}
\vec{y}^{\prime}-A \vec{y}=\vec{e}(t) \tag{8.2}
\end{equation*}
$$

( $\vec{e}(t)$ is called a forcing term), then any solution $\vec{\Psi}(t)$ of (8.2) can be written as

$$
\vec{\Psi}(t)=\Phi(t) \vec{c}+\vec{x}(t)
$$

where $\Phi$ is a fundamental matrix for

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\begin{equation*}
\vec{y}^{\prime}-A \vec{y}=\overrightarrow{0} \tag{8.3}
\end{equation*}
$$

and $\vec{c}$ is a constant.
Proof. Let $L(\vec{y}]=\vec{y}^{\prime}=A \vec{y}$ and let $L(\vec{\psi}(t)]=\vec{e}(t)$. Then
$L[\vec{\Psi}(t)-\vec{x}(t)]=\vec{c}(t)-\vec{e}(t)=\overrightarrow{0}$. So $\vec{\psi}(t)=\vec{x}(t)$ is a solution of (8.3).
By Theorem 1.3.4, $\Psi(t)-\vec{x}(t)=\Psi(t) \vec{c}$ and so $\Psi(t)=\Psi(t) \vec{c}+\vec{x}(t)$.

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## Theorem 1.8.2

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$$
\vec{x}(t)-\Phi(t) \int_{t_{0}}^{t} \Phi^{-1}(\tau) \vec{e}(\tau) d \tau
$$

is a solution of $\vec{y}^{\prime}=\vec{e}(t)$.
Proof. Well,

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\vec{x}^{\prime}(t)=\Phi^{\prime}(t) \int_{t_{0}}^{t} \Phi^{-1}(\tau) \vec{e}(\tau) d \tau+\Phi(t) \Psi^{-1}(t) \vec{e}(t) .
$$

Now $\Phi^{\prime}(t)=A(t) \Phi(t)$ so

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\vec{x}^{\prime}=A(t) \Phi(t) \int_{t_{0}}^{t} \Phi^{-1}(\tau) \vec{e}(\tau) d \tau+\vec{e}(t)=A(t) \vec{x}(t) .
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