

## Section 1.8. General Linear Systems

**Note.** In this section we find solutions to nonhomogeneous linear systems of equations.

**Theorem 1.8.1.** If  $\vec{x}(t)$  is a solution of

$$\vec{y}' - A\vec{y} = \vec{e}(t) \quad (8.2)$$

( $\vec{e}(t)$  is called a *forcing term*), then any solution  $\vec{\Psi}(t)$  of (8.2) can be written as

$$\vec{\Psi}(t) = \Phi(t)\vec{c} + \vec{x}(t)$$

where  $\Phi$  is a fundamental matrix for

$$\vec{y}' - A\vec{y} = \vec{0} \quad (8.3)$$

and  $\vec{c}$  is a constant.

**Theorem 1.8.2.**

$$\vec{x}(t) - \Phi(t) \int_{t_0}^t \Phi^{-1}(\tau)\vec{e}(\tau) d\tau$$

is a solution of  $\vec{y}' = \vec{e}(t)$ .

**Note.** Theorem 1.8.2 can be modified to give solutions of IVPs, as follows.

**Theorem 1.8.3. Variation of Constants.**

Let  $\Phi(t)$  be a fundamental matrix for  $\vec{x}' = A(t)\vec{x}$ . Then the solution of

$$\begin{cases} \vec{y}' = A(t)\vec{y} + \vec{e}(t) \\ \vec{y}(t_0) = \vec{\eta} \end{cases}$$

is

$$\vec{y}(t) = \Phi(t)\Phi^{-1}(t_0)\vec{\eta} + \int_{t_0}^t \Phi(t)\Phi^{-1}(s)\vec{e}(s) ds.$$

**Example.** Page 68 Number 1(a). Solve  $\vec{x}' = \begin{bmatrix} 1 & 2 \\ 0 & 2 \end{bmatrix} \vec{x} + \begin{bmatrix} 0 \\ t \end{bmatrix}$ .

**Partial Solution.** We have  $\det(A - \lambda I) = (1 - \lambda)(2 - \lambda)$  and so the eigenvalues are

$\lambda_1 = 1$  and  $\lambda_2 = 2$ . We find that we have eigenvectors  $\vec{c}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\vec{c}_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ .

So  $\Phi(t) = \begin{bmatrix} e^t & 2e^{2t} \\ 0 & e^{2t} \end{bmatrix}$  and  $\Phi^{-1}(t) = e^{-3t} \begin{bmatrix} e^{2t} & -2e^{2t} \\ 0 & e^t \end{bmatrix} = \begin{bmatrix} e^{-1} & -2e^{-t} \\ 0 & e^{-2t} \end{bmatrix}$ . So we

have

$$\vec{x}(t) = \Phi(t) \int_0^t \Phi^{-1}(\tau)\vec{e}(\tau) d\tau = \begin{bmatrix} e^t & 2e^{2t} \\ 0 & e^{2t} \end{bmatrix} \int_0^t \begin{bmatrix} e^{-\tau} & -2e^{-\tau} \\ 0 & e^{-2\tau} \end{bmatrix} \begin{bmatrix} 0 \\ \tau \end{bmatrix} d\tau.$$

We can now find the general solution using Theorem 1.8.3.

*Revised: 4/14/2019*