

Modern Algebra

Chapter I. Basic Ideas of Hilbert Space Theory

I.1. Vector Spaces—Proofs of Theorems

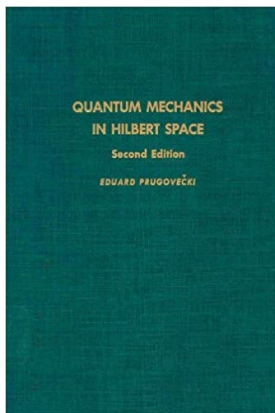


Table of contents

- 1 Theorem I.1.1
- 2 Theorem I.1.2
- 3 Theorem I.1.3
- 4 Theorem I.1.4. The Fundamental Theorem of Finite Dimensional Vector Spaces

Theorem I.1.1

Theorem I.1.1. Every vector space \mathcal{V} has only one zero vector $\mathbf{0}$, and each element f of a vector space has one and only one additive inverse $(-f)$. For any $f \in \mathcal{V}$, we have $0f = \mathbf{0}$ and $(-1)f = (-f)$.

Proof. If $\mathbf{0}_1$ and $\mathbf{0}_2$ are both zero vectors, then by Axiom 3 of Definition I.1, $f = f + \mathbf{0}_1 = f + \mathbf{0}_2$ for all $f \in \mathcal{V}$. With $f = \mathbf{0}_1$ we have $\mathbf{0}_1 = \mathbf{0}_1 + \mathbf{0}_2$ and with $f = \mathbf{0}_2$ we have $\mathbf{0}_2 = \mathbf{0}_2 + \mathbf{0}_1$, so by Axiom 1, $\mathbf{0}_1 = \mathbf{0}_1 + \mathbf{0}_2 = \mathbf{0}_2 + \mathbf{0}_1 = \mathbf{0}_2$. Therefore the additive identity vector is unique.

Theorem I.1.1

Theorem I.1.1. Every vector space \mathcal{V} has only one zero vector $\mathbf{0}$, and each element f of a vector space has one and only one additive inverse $(-f)$. For any $f \in \mathcal{V}$, we have $0f = \mathbf{0}$ and $(-1)f = (-f)$.

Proof. If $\mathbf{0}_1$ and $\mathbf{0}_2$ are both zero vectors, then by Axiom 3 of Definition I.1, $f = f + \mathbf{0}_1 = f + \mathbf{0}_2$ for all $f \in \mathcal{V}$. With $f = \mathbf{0}_1$ we have $\mathbf{0}_1 = \mathbf{0}_1 + \mathbf{0}_2$ and with $f = \mathbf{0}_2$ we have $\mathbf{0}_2 = \mathbf{0}_2 + \mathbf{0}_1$, so by Axiom 1, $\mathbf{0}_1 = \mathbf{0}_1 + \mathbf{0}_2 = \mathbf{0}_2 + \mathbf{0}_1 = \mathbf{0}_2$. Therefore the additive identity vector is unique.

Next,

$$\begin{aligned} f &= af \text{ by Axiom 7} \\ &= (1 + 0)f = 1f + 0f \text{ by Axiom 5} \\ &= f + 0f \text{ by Axiom 7} \end{aligned}$$

and so, by Axiom 3, $0f = \mathbf{0}$.

Theorem I.1.1

Theorem I.1.1. Every vector space \mathcal{V} has only one zero vector $\mathbf{0}$, and each element f of a vector space has one and only one additive inverse $(-f)$. For any $f \in \mathcal{V}$, we have $0f = \mathbf{0}$ and $(-1)f = (-f)$.

Proof. If $\mathbf{0}_1$ and $\mathbf{0}_2$ are both zero vectors, then by Axiom 3 of Definition I.1, $f = f + \mathbf{0}_1 = f + \mathbf{0}_2$ for all $f \in \mathcal{V}$. With $f = \mathbf{0}_1$ we have $\mathbf{0}_1 = \mathbf{0}_1 + \mathbf{0}_2$ and with $f = \mathbf{0}_2$ we have $\mathbf{0}_2 = \mathbf{0}_2 + \mathbf{0}_1$, so by Axiom 1, $\mathbf{0}_1 = \mathbf{0}_1 + \mathbf{0}_2 = \mathbf{0}_2 + \mathbf{0}_1 = \mathbf{0}_2$. Therefore the additive identity vector is unique.

Next,

$$\begin{aligned} f &= af \text{ by Axiom 7} \\ &= (1 + 0)f = 1f + 0f \text{ by Axiom 5} \\ &= f + 0f \text{ by Axiom 7} \end{aligned}$$

and so, by Axiom 3, $0f = \mathbf{0}$.

Theorem I.1.1 (continued)

Theorem I.1.1. Every vector space \mathcal{V} has only one zero vector $\mathbf{0}$, and each element f of a vector space has one and only one additive inverse $(-f)$. For any $f \in \mathcal{V}$, we have $0f = \mathbf{0}$ and $(-1)f = (-f)$.

Proof (continued). We then have

$$\begin{aligned} (-1)f + f &= (-1)f + 1f \text{ by Axiom 7} \\ &= (-1 + 1)f \text{ by Axiom 5} \\ &= 0f = \mathbf{0}, \end{aligned}$$

and so f has an additive inverse and $(-f) = (-1)f$. Now suppose $f_1 \in \mathcal{V}$ is another additive inverse of f so that $f + f_1 = \mathbf{0}$. Then

$$\begin{aligned} (-f) &= (-f) + \mathbf{0} \text{ by Axiom 3} \\ &= (-f) + (f + f_1) = ((-f) + f) + f_1 \text{ by Axiom 2} \\ &= \mathbf{0} + f_1 = f_1 \text{ by Axioms 1 and 3.} \end{aligned}$$

That is, $(-f) = f_1$ and the additive inverse of f is unique. □

Theorem I.1.1 (continued)

Theorem I.1.1. Every vector space \mathcal{V} has only one zero vector $\mathbf{0}$, and each element f of a vector space has one and only one additive inverse $(-f)$. For any $f \in \mathcal{V}$, we have $0f = \mathbf{0}$ and $(-1)f = (-f)$.

Proof (continued). We then have

$$\begin{aligned} (-1)f + f &= (-1)f + 1f \text{ by Axiom 7} \\ &= (-1 + 1)f \text{ by Axiom 5} \\ &= 0f = \mathbf{0}, \end{aligned}$$

and so f has an additive inverse and $(-f) = (-1)f$. Now suppose $f_1 \in \mathcal{V}$ is another additive inverse of f so that $f + f_1 = \mathbf{0}$. Then

$$\begin{aligned} (-f) &= (-f) + \mathbf{0} \text{ by Axiom 3} \\ &= (-f) + (f + f_1) = ((-f) + f) + f_1 \text{ by Axiom 2} \\ &= \mathbf{0} + f_1 = f_1 \text{ by Axioms 1 and 3.} \end{aligned}$$

That is, $(-f) = f_1$ and the additive inverse of f is unique. □

Theorem I.1.2

Theorem I.1.2. If the vector space \mathcal{V} is n dimensional, where $n \in \mathbb{N}$, then there is at least one set f_1, f_2, \dots, f_n of linearly independent vectors, and each vector $f \in \mathcal{V}$ can be expanded as $f = a_1 f_1 + a_2 f_2 + \dots + a_n f_n$, there the coefficients a_1, a_2, \dots, a_n are uniquely determined by f .

Proof. First, if $f = \mathbf{0}$ then we can just take $a_1 = a_2 = \dots = a_n$ (by Theorem I.1.1 and Axiom 3). For $f \neq \mathbf{0}$, the equation $cf + c_1 f_2 + c_2 f_2 + \dots + c_n f_n = \mathbf{0}$ has a solution where $c \neq 0$ because f_1, f_2, \dots, f_n are linearly independent and \mathcal{V} is dimension n (so f, f_1, f_2, \dots, f_n must be dependent, but if $c = 0$ then we would need $c_1 = c_2 = \dots = c_n = 0$).

Theorem I.1.2

Theorem I.1.2. If the vector space \mathcal{V} is n dimensional, where $n \in \mathbb{N}$, then there is at least one set f_1, f_2, \dots, f_n of linearly independent vectors, and each vector $f \in \mathcal{V}$ can be expanded as $f = a_1 f_1 + a_2 f_2 + \dots + a_n f_n$, there the coefficients a_1, a_2, \dots, a_n are uniquely determined by f .

Proof. First, if $f = \mathbf{0}$ then we can just take $a_1 = a_2 = \dots = a_n$ (by Theorem I.1.1 and Axiom 3). For $f \neq \mathbf{0}$, the equation $cf + c_1 f_2 + c_2 f_2 + \dots + c_n f_n = \mathbf{0}$ has a solution where $c \neq 0$ because f_1, f_2, \dots, f_n are linearly independent and \mathcal{V} is dimension n (so f, f_1, f_2, \dots, f_n must be dependent, but if $c = 0$ then we would need $c_1 = c_2 = \dots = c_n = 0$). So we get

$$f = \frac{-c_1}{c} f_1 + \frac{-c_2}{c} f_2 + \dots + \frac{-c_n}{c} f_n,$$

and so scalars a_1, a_2, \dots, a_n exist as claimed.

Theorem I.1.2

Theorem I.1.2. If the vector space \mathcal{V} is n dimensional, where $n \in \mathbb{N}$, then there is at least one set f_1, f_2, \dots, f_n of linearly independent vectors, and each vector $f \in \mathcal{V}$ can be expanded as $f = a_1 f_1 + a_2 f_2 + \dots + a_n f_n$, there the coefficients a_1, a_2, \dots, a_n are uniquely determined by f .

Proof. First, if $f = \mathbf{0}$ then we can just take $a_1 = a_2 = \dots = a_n$ (by Theorem I.1.1 and Axiom 3). For $f \neq \mathbf{0}$, the equation $cf + c_1 f_2 + c_2 f_2 + \dots + c_n f_n = \mathbf{0}$ has a solution where $c \neq 0$ because f_1, f_2, \dots, f_n are linearly independent and \mathcal{V} is dimension n (so f, f_1, f_2, \dots, f_n must be dependent, but if $c = 0$ then we would need $c_1 = c_2 = \dots = c_n = 0$). So we get

$$f = \frac{-c_1}{c} f_1 + \frac{-c_2}{c} f_2 + \dots + \frac{-c_n}{c} f_n,$$

and so scalars a_1, a_2, \dots, a_n exist as claimed.

Theorem I.1.2 (continued)

Theorem I.1.2. If the vector space \mathcal{V} is n dimensional, where $n \in \mathbb{N}$, then there is at least one set f_1, f_2, \dots, f_n of linearly independent vectors, and each vector $f \in \mathcal{V}$ can be expanded as $f = a_1 f_1 + a_2 f_2 + \dots + a_n f_n$, where the coefficients a_1, a_2, \dots, a_n are uniquely determined by f .

Proof (continued). If we also have $f = b_1 f_1 + b_2 f_2 + \dots + b_n f_n$, then

$$\begin{aligned} 0 &= f - f = (a_1 f_1 + a_2 f_2 + \dots + a_n f_n) - (b_1 f_1 + b_2 f_2 + \dots + b_n f_n) \\ &= (a_1 - b_1) f_1 + (a_2 - b_2) f_2 + \dots + (a_n - b_n) f_n \end{aligned}$$

by Axiom 1 and Axiom 5. But since f_1, f_2, \dots, f_n are linearly independent then (by Definition I.1.2), $a_1 - b_1 = 0$, $a_2 - b_2 = 0$, \dots , $a_n - b_n = 0$ and so $a_1 = b_1$, $a_2 = b_2$, \dots , $a_n = b_n$. That is, the choice of coefficients a_1, a_2, \dots, a_n is unique, as claimed. □

Theorem I.1.2 (continued)

Theorem I.1.2. If the vector space \mathcal{V} is n dimensional, where $n \in \mathbb{N}$, then there is at least one set f_1, f_2, \dots, f_n of linearly independent vectors, and each vector $f \in \mathcal{V}$ can be expanded as $f = a_1 f_1 + a_2 f_2 + \dots + a_n f_n$, where the coefficients a_1, a_2, \dots, a_n are uniquely determined by f .

Proof (continued). If we also have $f = b_1 f_1 + b_2 f_2 + \dots + b_n f_n$, then

$$\begin{aligned} 0 &= f - f = (a_1 f_1 + a_2 f_2 + \dots + a_n f_n) - (b_1 f_1 + b_2 f_2 + \dots + b_n f_n) \\ &= (a_1 - b_1) f_1 + (a_2 - b_2) f_2 + \dots + (a_n - b_n) f_n \end{aligned}$$

by Axiom 1 and Axiom 5. But since f_1, f_2, \dots, f_n are linearly independent then (by Definition I.1.2), $a_1 - b_1 = 0$, $a_2 - b_2 = 0$, \dots , $a_n - b_n = 0$ and so $a_1 = b_1$, $a_2 = b_2$, \dots , $a_n = b_n$. That is, the choice of coefficients a_1, a_2, \dots, a_n is unique, as claimed. □

Theorem I.1.3

Theorem I.1.3. If the set $\{g_1, g_2, \dots, g_n\}$ is a basis of n -dimensional vector space \mathcal{V} (where $n \in \mathbb{N}$), then $m = n$. That is, all bases of an n -dimensional vector space are of the same size n .

Proof. Since \mathcal{V} is n -dimensional, there are n linearly independent vectors f_1, f_2, \dots, f_n . Since $\{g_1, g_2, \dots, g_n\}$ is a basis, then

$$f_1 = a_{11}g_1 + a_{21}g_2 + \cdots + a_{m1}g_m$$

$$f_2 = a_{12}g_1 + a_{22}g_2 + \cdots + a_{m2}g_m$$

$$\vdots$$

$$f_n = a_{1n}g_1 + a_{2n}g_2 + \cdots + a_{mn}g_m.$$

Theorem I.1.3

Theorem I.1.3. If the set $\{g_1, g_2, \dots, g_n\}$ is a basis of n -dimensional vector space \mathcal{V} (where $n \in \mathbb{N}$), then $m = n$. That is, all bases of an n -dimensional vector space are of the same size n .

Proof. Since \mathcal{V} is n -dimensional, there are n linearly independent vectors f_1, f_2, \dots, f_n . Since $\{g_1, g_2, \dots, g_n\}$ is a basis, then

$$f_1 = a_{11}g_1 + a_{21}g_2 + \cdots + a_{m1}g_m$$

$$f_2 = a_{12}g_1 + a_{22}g_2 + \cdots + a_{m2}g_m$$

$$\vdots$$

$$f_n = a_{1n}g_1 + a_{2n}g_2 + \cdots + a_{mn}g_m.$$

So if $x_1f_1 + x_2f_2 + \cdots + x_nf_n = \mathbf{0}$ then substituting for f_1, f_2, \dots, f_n we get

$$x_1f_1 + x_2f_2 + \cdots + x_nf_n = (a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n)g_1$$

$$+ (a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n)g_2 + \cdots + (a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n)g_m = \mathbf{0}.$$

Theorem I.1.3

Theorem I.1.3. If the set $\{g_1, g_2, \dots, g_n\}$ is a basis of n -dimensional vector space \mathcal{V} (where $n \in \mathbb{N}$), then $m = n$. That is, all bases of an n -dimensional vector space are of the same size n .

Proof. Since \mathcal{V} is n -dimensional, there are n linearly independent vectors f_1, f_2, \dots, f_n . Since $\{g_1, g_2, \dots, g_n\}$ is a basis, then

$$f_1 = a_{11}g_1 + a_{21}g_2 + \cdots + a_{m1}g_m$$

$$f_2 = a_{12}g_1 + a_{22}g_2 + \cdots + a_{m2}g_m$$

$$\vdots$$

$$f_n = a_{1n}g_1 + a_{2n}g_2 + \cdots + a_{mn}g_m.$$

So if $x_1f_1 + x_2f_2 + \cdots + x_nf_n = \mathbf{0}$ then substituting for f_1, f_2, \dots, f_n we get

$$x_1f_1 + x_2f_2 + \cdots + x_nf_n = (a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n)g_1$$

$$+ (a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n)g_2 + \cdots + (a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n)g_m = \mathbf{0}.$$

Theorem I.1.3 (continued)

Proof (continued). Since g_1, g_2, \dots, g_m are linearly independent, then x_1, x_2, \dots, x_n satisfy the homogeneous system of equations

$$\begin{aligned} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n &= 0 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n &= 0 \\ &\vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n &= 0, \end{aligned}$$

and conversely any solution to this system of equations yields $x_1f_1 + x_2f_2 + \cdots + x_nf_n = \mathbf{0}$. But since f_1, f_2, \dots, f_n are linearly independent then the only solution to the system of equations is the trivial solution $x_1 = x_2 = \cdots = x_n = 0$. Finally, we have $m \leq n$ since \mathcal{V} is n -dimensional and g_1, g_2, \dots, g_m are linearly independent (see Definition I.1.2). Since the homogeneous system of equations only has the trivial solution, then by Lemma I.1.A above, $n \leq m$. Therefore $m = n$, as claimed. \square

Theorem I.1.3 (continued)

Proof (continued). Since g_1, g_2, \dots, g_m are linearly independent, then x_1, x_2, \dots, x_n satisfy the homogeneous system of equations

$$\begin{aligned} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n &= 0 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n &= 0 \\ &\vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n &= 0, \end{aligned}$$

and conversely any solution to this system of equations yields $x_1f_1 + x_2f_2 + \cdots + x_nf_n = \mathbf{0}$. But since f_1, f_2, \dots, f_n are linearly independent then the only solution to the system of equations is the trivial solution $x_1 = x_2 = \cdots = x_n = 0$. Finally, we have $m \leq n$ since \mathcal{V} is n -dimensional and g_1, g_2, \dots, g_m are linearly independent (see Definition I.1.2). Since the homogeneous system of equations only has the trivial solution, then by Lemma I.1.A above, $n \leq m$. Therefore $m = n$, as claimed. \square

Theorem 1.1.4

Theorem 1.1.4. The Fundamental Theorem of Finite Dimensional Vector Spaces.

All complex (real) n -dimensional ($n \in \mathbb{N}$) vector spaces are isomorphic to the vector space \mathbb{C}^n (or \mathbb{R}^n in the case of real vector spaces).

Proof. Let \mathcal{V} be an n -dimensional complex vector space. By Theorem 1.1.2, there is a basis consisting of n vectors, f_1, f_2, \dots, f_n , and each given $f \in \mathcal{V}$ can be expanded as $f = a_1 f_1 + a_2 f_2 + \dots + a_n f_n$ for unique $a_1, a_2, \dots, a_n \in \mathbb{C}$. So we define a mapping of \mathcal{V} to \mathbb{C}^n as $f \mapsto \alpha_f = [a_1, a_2, \dots, a_n]^T \in \mathbb{C}^n$ / Notice that this mapping is one to one (by the uniqueness of the a_i 's) and onto.

Theorem 1.1.4

Theorem 1.1.4. The Fundamental Theorem of Finite Dimensional Vector Spaces.

All complex (real) n -dimensional ($n \in \mathbb{N}$) vector spaces are isomorphic to the vector space \mathbb{C}^n (or \mathbb{R}^n in the case of real vector spaces).

Proof. Let \mathcal{V} be an n -dimensional complex vector space. By Theorem 1.1.2, there is a basis consisting of n vectors, f_1, f_2, \dots, f_n , and each given $f \in \mathcal{V}$ can be expanded as $f = a_1 f_1 + a_2 f_2 + \dots + a_n f_n$ for unique $a_1, a_2, \dots, a_n \in \mathbb{C}$. So we define a mapping of \mathcal{V} to \mathbb{C}^n as $f \mapsto \alpha_f = [a_1, a_2, \dots, a_n]^T \in \mathbb{C}^n$ / Notice that this mapping is one to one (by the uniqueness of the a_i 's) and onto. Now for $f, g \in \mathcal{V}$ with $f = a_1 f_1 + a_2 f_2 + \dots + a_n f_n$ and $g = b_1 f_1 + b_2 f_2 + \dots + b_n f_n$ we have

$$f + g = (a_1 + b_1)f_1 + (a_2 + b_2)f_2 + \dots + (a_n + b_n)f_n \mapsto \dots$$

Theorem 1.1.4

Theorem 1.1.4. The Fundamental Theorem of Finite Dimensional Vector Spaces.

All complex (real) n -dimensional ($n \in \mathbb{N}$) vector spaces are isomorphic to the vector space \mathbb{C}^n (or \mathbb{R}^n in the case of real vector spaces).

Proof. Let \mathcal{V} be an n -dimensional complex vector space. By Theorem 1.1.2, there is a basis consisting of n vectors, f_1, f_2, \dots, f_n , and each given $f \in \mathcal{V}$ can be expanded as $f = a_1 f_1 + a_2 f_2 + \dots + a_n f_n$ for unique $a_1, a_2, \dots, a_n \in \mathbb{C}$. So we define a mapping of \mathcal{V} to \mathbb{C}^n as $f \mapsto \alpha_f = [a_1, a_2, \dots, a_n]^T \in \mathbb{C}^n$ / Notice that this mapping is one to one (by the uniqueness of the a_i 's) and onto. Now for $f, g \in \mathcal{V}$ with $f = a_1 f_1 + a_2 f_2 + \dots + a_n f_n$ and $g = b_1 f_1 + b_2 f_2 + \dots + b_n f_n$ we have

$$f + g = (a_1 + b_1)f_1 + (a_2 + b_2)f_2 + \dots + (a_n + b_n)f_n \mapsto \dots$$

Theorem 1.1.4 (continued)

Proof (continued).

$$\cdots \begin{bmatrix} a_1 + b_1 \\ a_2 + b_2 \\ \vdots \\ a_n + b_n \end{bmatrix} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} + \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

and for scalar $a \in \mathbb{C}$,

$$af = (aa_1)f_1 + (aa_2)f_2 + \cdots + (aa_n)f_n \mapsto \begin{bmatrix} aa_1 \\ aa_2 \\ \vdots \\ aa_n \end{bmatrix} = a \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix},$$

and so the mapping is an isomorphism. Hence, \mathcal{V} is isomorphic to \mathbb{C}^n .

Replacing field \mathbb{C} with field \mathbb{R} , we see that real n -dimensional vector space is isomorphic to \mathbb{R}^n and, more generally, n -dimensional vector space \mathcal{V} over field F is isomorphic to F^n . □

Theorem 1.1.4 (continued)

Proof (continued).

$$\cdots \begin{bmatrix} a_1 + b_1 \\ a_2 + b_2 \\ \vdots \\ a_n + b_n \end{bmatrix} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} + \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

and for scalar $a \in \mathbb{C}$,

$$af = (aa_1)f_1 + (aa_2)f_2 + \cdots + (aa_n)f_n \mapsto \begin{bmatrix} aa_1 \\ aa_2 \\ \vdots \\ aa_n \end{bmatrix} = a \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix},$$

and so the mapping is an isomorphism. Hence, \mathcal{V} is isomorphic to \mathbb{C}^n .

Replacing field \mathbb{C} with field \mathbb{R} , we see that real n -dimensional vector space is isomorphic to \mathbb{R}^n and, more generally, n -dimensional vector space \mathcal{V} over field F is isomorphic to F^n . □