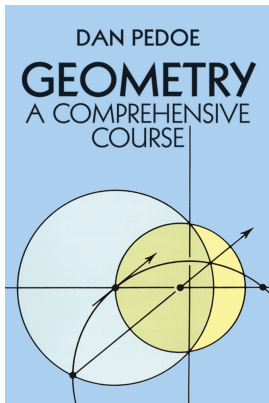


# Real Analysis

## Chapter V. Mappings of the Euclidean Plane

### 48. Groups of Translations and Rotations—Proofs of Theorems



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# Theorem 48.1. The Group of Translations

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The group  $\mathcal{T}$  of translations of the Gauss plane is transitive, and a normal subgroup of the group  $\mathcal{I}_+$  of direct isometries.

**Proof.** First, for  $T_1 : z' = z + z_1$  and  $T_2 : z' = z - z_2$ , we have  $T_2^{-1} : z' = z - z_2$  and  $T_1 \circ T_2^{-1} : z' = z - z_2 + z_1$  is a translation and so by Theorem 44.2, the set of translations is a subgroup of the direct isometries  $\mathcal{I}_+$ .

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To establish the normal subgroup claim, let  $l_1 : z' = az + b \in \mathcal{I}_+$  where  $|a| = 1$  and let  $T_d : z' = z + d \in \mathcal{T}$ . Then  $l_1^{-1} : z' = a^{-1}z + a^{-1}b$  and

$$\begin{aligned} l_1^{-1} \circ T_d \circ l_1 &= l_1^{-1} \circ T_d(az + b) = l_1^{-1}((az + b) + d) \\ &= a^{-1}((az + b) + d) - a^{-1}b = z + a^{-1}d \in \mathcal{T}. \end{aligned}$$

Since  $l_1$  is an arbitrary element of  $\mathcal{I}_+$  and  $T_d$  is an arbitrary element of  $\mathcal{T}$  then by Theorem 45.2,  $\mathcal{T}$  is a normal subgroup of  $\mathcal{I}_+$ . □

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Let  $I_1$  be the direct isometry  $z' = az + b$  where  $|a| = 1$  and  $a \neq 1$ . Then  $I_1$  has only one fixed point, given by  $w = b(1 - a)^{-1}$ , and  $I_1$  can be written in the form  $z' = a(z - w) + w$ , which shows that  $I_1$  is a rotation about  $w$ .

**Proof.** If  $w$  is a fixed point under  $I$ , then  $w = aw + b$  so that  $w = b(a - 1)^{-1}$ , as claimed. Since  $z' = az + b$  then

$$z' = az + (1 - a)w = az + w - aw = a(z - w) + w,$$

as claimed. So  $I_1$  is composed of (1) a translation of  $w$  to 0, (2) a rotation about 0 through an angle  $\arg(a)$ , and (3) a translation of 0 back to  $w$ .

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## Theorem 48.5. Rotation Groups

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The set of rotations about the point  $w$  form a group  $\mathcal{R}_w$ , and the groups  $\mathcal{R}_w$ , for all values of  $w$ , are isomorphic.

**Proof.** Let  $I_1, I_2 \in \mathcal{R}_w$ . Say the canonical forms are  $I_1 = T_w \circ R \circ T_w^{-1}$  and  $I_2 = T_w \circ R' \circ T_w^{-1}$  where  $R$  and  $R'$  are rotations about the origin 0. We have  $I_1^{-1} = T_w \circ R^{-1} \circ T_w^{-1}$ . Now the rotations about the origin form a group by Theorem 46.3, so  $R' \circ R^{-1}$  is an element of this group and hence is a rotation about the origin.

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$$I_2 \circ I_1^{-1} = (T_w \circ R' \circ T_w^{-1}) \circ (T_w \circ R^{-1} \circ T_w^{-1}) = T_w \circ (R' \circ R^{-1}) \circ T_w^{-1}$$

is a rotation about  $w$  and hence  $I_2 \circ I_1^{-1} \in \mathcal{R}_w$ . Since  $I_1$  and  $I_2$  are arbitrary elements of  $\mathcal{R}_w$  then by Theorem 44.2,  $\mathcal{R}_w$  is a subgroup of, say,  $\mathcal{I}_+$ . So  $\mathcal{R}_w$  is a group, as claimed.

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## Theorem 48.5 (continued)

**Proof (continued).** Now consider groups  $\mathcal{R}_w$  and  $\mathcal{R}_0$  (rotation about the origin). Define  $\beta : \mathcal{R}_0 \rightarrow \mathcal{R}_w$  as  $\beta(R) = T_w \circ R \circ T_w^{-1}$ . Since  $\beta : \mathcal{R}_0 \rightarrow \mathcal{R}_w$  as  $\beta(R) = T_w \circ R \circ T_w^{-1}$ . Since  $R$  can range over all rotations about 0, the  $\beta(R)$  ranges over all rotations about  $w$ . That is,  $\beta$  is onto. Clearly,  $\beta$  is one to one. Now for  $R, R' \in \mathcal{R}_0$  we have

$$\beta(R \circ R') = T_w \circ (R \circ R') \circ T_w^{-1} = (T_w \circ R \circ T_w^{-1}) \circ (T_w \circ R' \circ T_w^{-1}) = \beta(R) \circ \beta(R')$$

and so  $\beta$  is a group isomorphism. So  $\mathcal{R}_w \cong \mathcal{R}_0$ . Since this holds for any point  $w$ , for  $w_1, w_2 \in \mathbb{C}$  we have  $\mathcal{R}_{w_1} \cong \mathcal{R}_0$  and  $\mathcal{R}_{w_2} \cong \mathcal{R}_0$  and so  $\mathcal{R}_{w_1} \cong \mathcal{R}_{w_2}$  (group isomorphisms is an equivalence relation by Exercise 45.1). □

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## Corollary 48.5

**Corollary 48.5.** The rotation groups  $\mathcal{R}_w$  form a complete set of conjugate subgroups of  $\mathcal{R}_0$  within the group of all isometries  $\mathcal{I}$  of the Gauss plane  $\mathbb{C}$ . That is,

$$\{\mathcal{R}_w \mid w \in \mathbb{C}\} = \{I \circ \mathcal{R}_0 \circ I^{-1} \mid I \in \mathcal{I}\}.$$

**Proof.** Every element of  $\mathcal{R}_w$  has a canonical form  $T_w \circ R \circ T_w^{-1}$  for some  $R \in \mathcal{R}_0$  (and conversely  $T_w \circ R \circ T_w^{-1}$  is a rotation about  $w$  for any  $R \in \mathcal{R}_0$ ) so  $\mathcal{R}_w = T_w \mathcal{R}_0 T_w^{-1}$  and all  $\mathcal{R}_w$  are conjugates of  $\mathcal{R}_0$ .

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We now need to show that  $I_1 \mathcal{R}_0 I_1^{-1}$  and  $I_2 \mathcal{R}_0 I_2^{-1}$  are rotation groups  $\mathcal{R}_w$  for some  $w$ , where  $I_1 \in \mathcal{I}_+$  and  $I_2 \in \mathcal{I}_2$ . Let  $I_1 : z' = az + b$  where  $|a| = 1$  be a direct isometry and let  $R : z' = kz$  where  $|k| = 1$  be a rotation about the origin. We have

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## Corollary 48.5 (continued)

**Proof.** ... whereas

$$T_b \circ R \circ T_b^{-1}(z) = T_b \circ R(z-b) = T_b(k(z-b)) = k(z-b) + b = kz - kb + b$$

and so  $l_1 \circ R \circ l_1^{-1} = T_b \circ R \circ T_b^{-1} \in \mathcal{R}_b$ . So  $l_1 \mathcal{R}_0 l_1^{-1} = \mathcal{R}_b$ .

Let  $l_2 : z' = c\bar{z} + d$  where  $|c| = 1$  be an indirect isometry and let  $R : z' = kz$ , where  $|k| = 1$ , be a rotation about the origin. We have

$$\begin{aligned} l_2 \circ R \circ l_2^{-1}(z) &= l_2 \circ R(\overline{c^{-1}z} - \overline{c^{-1}d}) = l_2(k(\overline{c^{-1}z} - \overline{c^{-1}d})) \\ &= \overline{c(k(\overline{c^{-1}z} - \overline{c^{-1}d}))} + d = \overline{c(\bar{k}(c^{-1}z c^{-1}d))} + d = \bar{k}z - \bar{k}d + d \end{aligned}$$

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So the set of all conjugate subgroups  $\mathcal{R}_0$  in group  $\mathcal{I}$  is equal to the set of all rotation groups  $\{\mathcal{R}_w \mid w \in \mathbb{C}\}$ , as claimed.  $\square$

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