## Real Analysis

## Chapter V. Mappings of the Euclidean Plane

50. More Isometries and Similitudes-Proofs of Theorems


## Table of contents

(1) Theorem 50.1
(2) Theorem 50.2. The Composition of Two Reflections
(3) Theorem 50.3. A Reflection Glide is also a Glide Reflection

4 Theorem 50.4.I. Hjelmslev's Theorem
(5) Theorem 50.5

## Theorem 50.1

Theorem 50.1. Every involutory isometry of the Gauss plane $\mathbb{C}$ is either a line reflection, a half-turn, or the identity.

Proof. By Theorem 43.1, "The Main Theorem on Isometries of the Gauss Plane," there are only two types of isometries of the Gauss plane, direct and indirect isometries.

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## Theorem 50.1 (continued)

Theorem 50.1. Every involutory isometry of the Gauss plane $\mathbb{C}$ is either a line reflection, a half-turn, or the identity.

Proof (continued). For indirect isometry $M: z^{\prime}=a \bar{z}+b$ where $|a|=1$, the square of the isometry is

$$
z^{\prime}=a \overline{(a \bar{z}+b)}+b=a \bar{a} z+a \bar{b}+b=|a|^{2} z+a \bar{b}+b=z+a \bar{b}+b
$$

so this is the identity if only if $a \bar{b}+b=0$. By Theorem 49.2, "Indirect Isometries as Reflections," this means that $M$ must be a line reflection, as claimed.

## Theorem 50.2. The Composition of Two Reflections

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The composition of reflections in lines $\ell$ and $m$ result in (i) a translation if and only if the lines are parallel, or (ii) a rotation about the point of intersection if and only if the lines intersect.

Proof. Let the reflection in $\ell$ be given by $\bar{z}=a \bar{z}+b$ with $|a|=1$ and $a \bar{b}+b=0$ by Theorem 49.2. The line $\ell$ makes an angle of $\arg (a) / 2$ with the real axis. Let the reflection in $m$ be given by $z^{\prime}=c \bar{z}+d$ with $|c|=1$, $c \bar{d}+d=0$, and line $m$ makes an angle of $\arg (c) / 2$ with the real axis. The composition of the reflections is

$$
z^{\prime}=c \overline{(a \bar{z}+b)}+d=c \bar{a} z+c \bar{b}+d \in \mathscr{I}_{+} .
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Now $|c \bar{a}|=1$, so either $c \bar{a}=1$, or $|c \bar{a}|=1$ and $c \bar{a} \neq 1$.

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(i) Suppose $c \bar{a}=1$. Then the composition is $z^{\prime}=z+c \bar{b}+d$, a translation. Also, $(c \bar{a}) a=1 a$ or $c|a|^{2}=a$ or $c=a$. So $\arg (a)=\arg (c)$ and line $\ell$ and $m$ are parallel.

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## Theorem 50.2 (continued 1)

Proof (continued). Conversely, if line $\ell$ and $m$ are parallel then $\arg (a)=\arg (c)$ and, since $|a|=|c|$ then $a=c$ and so $\bar{a} c=\bar{c} c=|c|^{2}=1$ and the composition $z^{\prime}=z+c \bar{b}+d$ is a translation. So the composition is a translation if and only if the lines are parallel.
(ii) $|c \bar{a}|=1$ and $c \bar{a} \neq 1$. Then the composition $z^{\prime}=c \bar{z} z+c \bar{b}+d$ is a direct isometry which is not a translation. Then by Theorem 48.3, "The Fixed Point of a Direct Isometry," the composition is a rotation about the fixed point of the composition. The fixed point satisfies $z=c \bar{a} z+c \bar{b}+d$ or $(z-c \bar{a}) z=c \bar{b}+d$ or $z=(c \bar{b}+d) /(1-c \bar{a})$.

## Theorem 50.2 (continued 1)

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## Theorem 50.2 (continued 1)

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## Theorem 50.2 (continued 2)

Theorem 50.2. The Composition of Two Reflections.
The composition of reflections in lines $\ell$ and $m$ result in (i) a translation if and only if the lines are parallel, or (ii) a rotation about the point of intersection if and only if the lines intersect.

Proof (continued). Conversely, if $\ell$ and $m$ are not parallel then $\arg (a) \neq \arg (c)$ and $c \bar{a} \neq 1$. So the composition is a rotation about the point of intersection, as just shown.

## Theorem 50.3. A Reflection Glide is also a Glide Reflection

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A reflection in a line $\ell$ followed by a translation $T_{b}$ results in an opposite isometry without invariant points if and only if that $\ell$ is no perpendicular to the position vector $b$. An opposite isometry without fixed points is equivalent to a glide reflection, that is to a reflection in a line followed by a translation parallel to the line.

Proof. Let the mapping be $z^{\prime}=a \bar{z}+b$. If the mapping has fixed points then, by Theorem 49.2, $a \bar{b}+b=0$. Then $a \bar{b}=-b$ and $\arg (a)+\arg (\bar{b})=\arg (-b)=\operatorname{arc}(b) \pm \pi$ so that $\arg (a)=2 \arg (b) \pm \pi$ and $\arg (a) / 2=\arg (b) \pm \pi / 2$. Since $\arg (a) / 2$ is the angle the line reflection $\ell$ makes with the real axis, so $\ell$ is perpendicular to the "position vector" $b$. So if $\ell$ is not perpendicular to the position vector $b$ then the mapping has no invariant points, as claimed.

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## Theorem 50.3 (continued 1)

Proof (continued). Conversely, if line $\ell$ is perpendicular to position vector $b$ then $\arg (a) / 2=\arg (b) \pm \pi / 2$ and we have $a \bar{b}+b=0$. So by Theorem 49.2, the mapping has fixed points. In fact, the mapping has an invariant line. Consider the line $\ell^{\prime}$ parallel to line $\ell$ and a distance $|b| / 2$ from $\ell$ in the "direction" $b$ (so that for any point $u$ on $\ell$ the point $u+b / 2$ is on line $\ell^{\prime}$ ). Consider arbitrary point $u+b / 2$ on $\ell^{\prime}$ where $u$ is on $\ell$. The reflection about line $\ell$ maps $u+b / 2$ to $u-b / 2$ and then the translation $T_{b}$ maps $u-b / 2$ to $u+b / 2$. So the mapping has line $\ell^{\prime}$ invariant.

Now suppose $z^{\prime}=a \bar{z}+b$, where $|a|=1$, is an opposite isometry without fixed points. Then by Theorem 49.2, $a b+b \neq 0$. Now $a \bar{z}+b=a(z-b / 2)+b / 2+(a \bar{b}+b) / 2$. Set $d=(a \bar{b}+b) / 2$ so that $d \neq 0$. So we have $z^{\prime}=a \bar{z}+b$ as the composition $T_{d} \circ T_{b / 2} \circ M_{a} \circ T_{b / 2}^{-1}$ since
$T_{d} \circ T_{b / 2} \circ M_{a} \circ T_{b / 2}^{-1}(z)=T_{d} \circ T_{b / 2} \circ M_{a}(z-b / 2)=T_{d} \circ T_{b / 2}(a(\overline{(z-b / 2)})$
$\square$

## Theorem 50.3 (continued 1)

Proof (continued). Conversely, if line $\ell$ is perpendicular to position vector $b$ then $\arg (a) / 2=\arg (b) \pm \pi / 2$ and we have $a \bar{b}+b=0$. So by Theorem 49.2, the mapping has fixed points. In fact, the mapping has an invariant line. Consider the line $\ell^{\prime}$ parallel to line $\ell$ and a distance $|b| / 2$ from $\ell$ in the "direction" $b$ (so that for any point $u$ on $\ell$ the point $u+b / 2$ is on line $\ell^{\prime}$ ). Consider arbitrary point $u+b / 2$ on $\ell^{\prime}$ where $u$ is on $\ell$. The reflection about line $\ell$ maps $u+b / 2$ to $u-b / 2$ and then the translation $T_{b}$ maps $u-b / 2$ to $u+b / 2$. So the mapping has line $\ell^{\prime}$ invariant.
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$$
\begin{gathered}
T_{d} \circ T_{b / 2} \circ M_{a} \circ T_{b / 2}^{-1}(z)=T_{d} \circ T_{b / 2} \circ M_{a}(z-b / 2)=T_{d} \circ T_{b / 2}(a \overline{(z-b / 2)}) \\
=T_{d}(a \overline{(z-b / 2)}+b / 2)=a \overline{(z-b / 2)}+b / 2+d=z^{\prime} .
\end{gathered}
$$

## Theorem 50.3 (continued 2)

Proof (continued). Now $T_{b / 2} \circ M_{a} \circ T_{b / 2}^{-1}$ is the canonical form for a line reflection by Theorem 49.2 where the line makes an angle $\arg (a) / 2$ with the real axis. So the mapping is a line reflection followed by a translation. We need to show that "position vector" $d$ is parallel to line $\ell$. We have, since $|a|=a \bar{a}=1$,

$$
\left(\frac{d}{\mid d}\right)^{2}-\frac{d^{2}}{d \bar{d}}=\frac{d}{\bar{d}}=\frac{a \bar{b}+b}{\bar{a} b+\bar{b}}=\frac{a(a \bar{b}+b)}{a(\bar{a} b+\bar{b})}=\frac{a(a \bar{b}+b)}{b+a \bar{b}}=a
$$

and so $2 \arg (d)=\arg \left(d^{2}\right)=\arg \left(d^{2} /|d|^{2}\right)=\arg (a)$, or $\arg (d)=\arg (a) / 2$. So position vector $d$ is parallel to line $\ell$ and the mapping is a reflection about a line $\ell$ followed by a translation parallel to line $\ell$. That is, the opposite isometry without fixed points is a glide reflection, as claimed.

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## Theorem 50.4.I. Hjelmslev's Theorem

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Suppose the points $P$ on a line are mapped by a plane isometry onto the points $P^{\prime}$ of another line. Then the midpoints of the line segments $P P^{\prime}$ either coincide or are distinct and collinear.

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Proof. First, suppose the isometry is a
direct isometry. A direct isometry is
either a translation or it is a rotation
about a fixed point (see Theorem 42.1).
If it is a translation, then it maps a given
line to a line parallel to the given line.
Let points A, B, C,\ldots. lie on a line, and
suppose they are mapped onto points
A},\mp@subsup{B}{}{\prime},\mp@subsup{C}{}{\prime},\ldots,\mathrm{ respectively, by the
translation. Then the points }\mp@subsup{A}{}{\prime},\mp@subsup{B}{}{\prime},\mp@subsup{C}{}{\prime}\mathrm{ ,
are collinear by Theorem 43.3. Also, the midpoints of the segments
A\mp@subsup{A}{}{\prime},B\mp@subsup{B}{}{\prime},C\mp@subsup{C}{}{\prime},\ldots. lie on a line (see Figure 50.4), as claimed.
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 translation. Then the points $A^{\prime}, B^{\prime}, C^{\prime}, \ldots$

Figure 50.4 are collinear by Theorem 43.3. Also, the midpoints of the segments $A A^{\prime}, B B^{\prime}, C C^{\prime}, \ldots$ lie on a line (see Figure 50.4), as claimed.

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Figure 50.4 are collinear by Theorem 43.3. Also, the midpoints of the segments $A A^{\prime}, B B^{\prime}, C C^{\prime}, \ldots$ lie on a line (see Figure 50.4), as claimed.

## Theorem 50.4.I. Hjelmslev's Theorem (continued 1)

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Proof (continued). If the direct isometry is a rotation through an angle equal to $\pi$, then the rotation is a "half-turn" and the midpoints coincide with the center of rotation. We address other rotations below.

If the isometry is indirect, then by Note 50.B it is either a reflection in a line $\ell$ (in which case the midpoints of $A A^{\prime}, B B^{\prime}, C C^{\prime} \ldots$ lie on $\ell$, or is a glide-reflection (i.e., a reflection in $\ell$ followed by a translation parallel to $\ell$ ), and again the midpoints of $A A^{\prime}, B B^{\prime}, C C^{\prime}, \ldots$ lie on $\ell$.

## Theorem 50.4.I. Hjelmslev's Theorem (continued 1)

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## Theorem 50.4.I. Hjelmslev's Theorem (continued 2)

Proof (continued). We still need to address the case of a direct isometry which is a rotation about a point through an angle other than $\pi$. We do so algebraically in such a way as to prove the result for all direct isometries (hence encompassing some of the above work already done). Let the points $A, B, C, \ldots$ be represented by the complex numbers $a, b, c, \ldots$, respectively, and let the points $A^{\prime}, B^{\prime}, C^{\prime}, \ldots$ be represented by the complex numbers $a^{\prime}, b^{\prime}, c^{\prime}, \ldots$, respectively. If $c$ is the complex number which represents any point $C$ on the line $A B$, then $c=t a+(1-t) b$ where $t$ is real and the ratio of the real numbers $1-t: t$ equals the ratio of the signed lengths of the segments $\overline{A C}: \overline{C B}$ by Theorem 3.1. Let $c^{\prime}$ be the image of $c$ under the direct isometry $z^{\prime}=p z+q$ where $|p|=1$. Then

$$
\begin{gather*}
c^{\prime}=p c+q=p(t a+(1-t) b)+q \\
=t(p a+q)+(1-t)(p b+q)=t a^{\prime}+(1-t) b^{\prime} . \tag{*}
\end{gather*}
$$

## Theorem 50.4.I. Hjelmslev's Theorem (continued 2)

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\end{gather*}
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## Theorem 50.4.I. Hjelmslev's Theorem (continued 3)

## Theorem 50.4.I. Hjelmslev's Theorem.

Suppose the points $P$ on a line are mapped by a plane isometry onto the points $P^{\prime}$ of another line. Then the midpoints of the line segments $P P^{\prime}$ either coincide or are distinct and collinear.

Proof (continued). Next, suppose that real numbers $k$ and $k^{\prime}$ satisfy $k+k^{\prime}=1$. Then by ( $*$ ) we have

$$
\begin{gather*}
k^{\prime} c+k c^{\prime}=k^{\prime}(t a+(1-t) b)+k\left(t a^{\prime}+(1-t) b^{\prime}\right) \\
=t\left(k^{\prime} a+k a^{\prime}\right)+(1-t)\left(k b^{\prime}+k^{\prime} b\right) . \tag{**}
\end{gather*}
$$

Suppose $k$ and $k^{\prime}$ are now fixed. If $k^{\prime} a+k a^{\prime} \neq k^{\prime} b+k b^{\prime}$, then the points $k^{\prime} c+k c^{\prime}$ "move" on a line as $t$ varies and are distinct for distinct values of $t$, as claimed.

## Theorem 50.4.I. Hjelmslev's Theorem (continued 4)

Proof (continued). If $k^{\prime} a+k a^{\prime}=k^{\prime} b+k b^{\prime}$ then by $(* *)$ we have $k^{\prime} c+k c^{\prime}=k^{\prime} a+k a^{\prime}=k^{\prime} b+k b^{\prime}$. Then all the points which divide the segment $C C^{\prime}$ in the ratio $k: k^{\prime}$ coincide. In terms of $a, b, a^{\prime}, b^{\prime}$ this implies that $k^{\prime}(a-b)=-k\left(a^{\prime}-b^{\prime}\right)$. So if $A$ and $B$ are any two points on the one line, and $A^{\prime}$ and $B^{\prime}$ are the images of $A$ and $B$ on the other line, then we have for these fixed values of $k$ and $k^{\prime}$ that $k^{\prime} \overrightarrow{A B}=-k \overrightarrow{A^{\prime} B^{\prime}}$. In this case the line containing points $A$ and $B$ is parallel to the line containing points $A^{\prime}$ and $B^{\prime}$ (we are using the difference of two complex numbers as a direction vector of a line here).

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The computations are similar for an indirect isometry, based on the fact that the conjugate of a real number (such as $t, 1-t, k$ ad $k^{\prime}$ ) is the number itself.

## Theorem 50.4.I. Hjelmslev's Theorem (continued 4)

Proof (continued). If $k^{\prime} a+k a^{\prime}=k^{\prime} b+k b^{\prime}$ then by $(* *)$ we have $k^{\prime} c+k c^{\prime}=k^{\prime} a+k a^{\prime}=k^{\prime} b+k b^{\prime}$. Then all the points which divide the segment $C C^{\prime}$ in the ratio $k: k^{\prime}$ coincide. In terms of $a, b, a^{\prime}, b^{\prime}$ this implies that $k^{\prime}(a-b)=-k\left(a^{\prime}-b^{\prime}\right)$. So if $A$ and $B$ are any two points on the one line, and $A^{\prime}$ and $B^{\prime}$ are the images of $A$ and $B$ on the other line, then we have for these fixed values of $k$ and $k^{\prime}$ that $k^{\prime} \overrightarrow{A B}=-k \overrightarrow{A^{\prime} B^{\prime}}$. In this case the line containing points $A$ and $B$ is parallel to the line containing points $A^{\prime}$ and $B^{\prime}$ (we are using the difference of two complex numbers as a direction vector of a line here). Since $k^{\prime}(a-b)=-k\left(a^{\prime}-b^{\prime}\right)$ and we are dealing with an isometry (so that $\left.|a-b|=\left|a^{\prime}-b^{\prime}\right|\right)$, then we must have $k=k^{\prime}=1 / 2$ and since $k^{\prime} a+k a^{\prime}=k^{\prime} b+k b^{\prime}\left(\right.$ or $\left.\left(a+a^{\prime}\right) / 2=\left(b+b^{\prime}\right) / 2\right)$ then the midpoints coincide, as claimed.

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## Theorem 50.5.

Theorem 50.5. A proper direct similitude $z^{\prime}=a z+b$, where $|a| \neq 1$, has a unique fixed point. A proper indirect similitude $z^{\prime}=c \bar{z}+d$, where $|c| \neq 1$, has a unique fixed point.

Proof. If $w$ is a fixed point of $z^{\prime}=a z+b$, then $w=a w+b$ or $w(1-a)=b$. Since $a \neq 1$, then there is a unique value of $w$, namely $w=b /(1-a)$.

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If $w$ is a fixed point of $z^{\prime}=c \bar{z}+d$, then $w=c \bar{w}+d$ or, conjugating both sides of this equation, $\bar{w}=\bar{c} w+\bar{d}$. Now replacing $\bar{w}$ with $\bar{c} w+\bar{d}$ in this last equation, we have $w=c(\bar{c} w+\bar{d})+d$. Then $w(1-c \bar{c})=c \bar{d}+d$ or $w\left(1-|c|^{2}\right)=c \bar{d}+d$. Since $|c| \neq 1$ then there is a unique value of $w$, namely $w=(c \bar{d}+d) /\left(1-|c|^{2}\right)$.

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