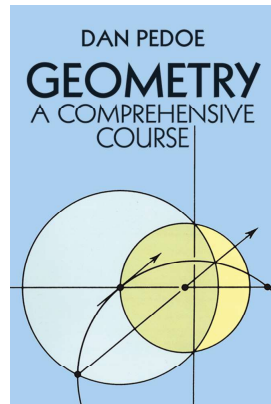


# Real Analysis

## Chapter VI. Mappings of the Inversive Plane

### 55. $M$ -Transformations—Proofs of Theorems



## Theorem 55.2

**Theorem 55.2.** Let  $X$  and  $A$  be two points of  $\Omega$  and let  $\xi$  and  $\alpha$  be directions through  $X$  and  $A$ , respectively. Then there is a unique  $M$ -transformation which maps  $X$  on  $A$ , and maps the direction  $\xi$  onto the direction  $\alpha$ .

**Proof.** First, by Exercise 55.1 there is exactly one circle orthogonal to  $\omega$  that passes through point  $X$  and has vector  $\xi$  as its direction vector at  $X$  (Pedoe describes the direction-condition in terms of tangency to the [Euclidean] straight line determined by vector  $\xi$ .) Denote this circle as  $\mathcal{C}_X$ , and let  $X_1$  and  $X_2$  be the points of intersection of  $\mathcal{C}_X$  and  $\omega$ . Similarly, let  $\mathcal{C}_A$  be the unique circle through point  $A$  with direction  $\alpha$  at  $A$  and orthogonal to  $\omega$ . Let  $A_1$  and  $A_2$  be the points of intersection of  $\mathcal{C}_X$  with  $\omega$ . Since Möbius transformations preserve angles of intersection by Theorem 54.3, and an  $M$ -transformation maps  $\omega$  onto itself, circle orthogonal to  $\omega$  are mapped onto circles orthogonal to  $\omega$ .

## Theorem 55.2 (continued 1)

**Proof (continued).** Now any  $M$ -transformation which maps point  $A$  and vector  $\xi$  onto point  $A$  and vector  $\alpha$ , must map  $\mathcal{C}_X$  onto  $\mathcal{C}_A$  since  $\mathcal{C}_X$  is mapped onto a circle through  $A$  with direction  $\alpha$  at  $A$  and orthogonal to  $\omega$ , and there is only one such circle (by Exercise 55.1), namely  $\mathcal{C}_A$ .

Next label the points of intersection of  $\mathcal{C}_X$  and  $\mathcal{C}_A$  with  $\omega$ , such that the direction  $\xi$  of  $\mathcal{C}_X$  is that of  $X_1$  towards  $X_2$  and such that the direction  $\alpha$  of  $\mathcal{C}_A$  is that of  $A_1$  towards  $A_2$  (direction can be put on a line or circle by giving it parametrically; this is also how tangent vectors such as  $\xi$  and  $\alpha$  can be determined by taking derivatives with respect to the parameter). The  $M$ -transformation must map  $X_1$  to  $A_1$ , map  $X_2$  to  $A_2$ , and map  $X$  to  $A$  (again, this follows from a parametric presentation of the circle and tangent vectors). By Theorem 53.2, three points and their images uniquely determine a Möbius transformation. We just need to show that this unique Möbius transformation is in fact an  $M$ -transformation.

## Theorem 55.2 (continued 2)

**Theorem 55.2.** Let  $X$  and  $A$  be two points of  $\Omega$  and let  $\xi$  and  $\alpha$  be directions through  $X$  and  $A$ , respectively. Then there is a unique  $M$ -transformation which maps  $X$  on  $A$ , and maps the direction  $\xi$  onto the direction  $\alpha$ .

**Proof (continued).** Now the Möbius transformation maps the circle through  $X_1$  and  $X_2$  which is orthogonal to  $\mathcal{C}_X$  (namely, circle  $\omega$ ) must be mapped to the circle through  $A_1$  and  $A_2$  which is orthogonal to  $\mathcal{C}_A$  (also circle  $\omega$ ; the preservation of orthogonality is given by Theorem 54.3). That is,  $\omega$  is mapped to  $\omega$  by the Möbius transformation. Since the interior point  $X$  of  $\Omega$  is mapped to the interior point  $A$  of  $\Omega$ , then the interior of  $\omega$  is mapped to the interior of  $\omega$ ; that is, the unique Möbius transformation is an  $M$ -transformation, as needed.  $\square$

## Corollary 55.A

**Corollary 55.A.** Let  $\mathcal{C}_A$  be a circle through point  $A$  of  $\Omega$  to  $\omega$ , and let  $\mathcal{C}_B$  be a circle through a point  $B$  of  $\Omega$  orthogonal to  $\omega$ . Then there exist just two  $M$ -transformations which map  $A$  on  $B$  and  $\mathcal{C}_A$  on  $\mathcal{C}_B$ .

**Proof.** For a given direction tangent to  $\mathcal{C}_A$  at point  $A$  and a given tangent to  $\mathcal{C}_B$  at point  $B$  there is, by Theorem 55.2, a unique  $M$ -transformation mapping  $A$  to  $X$  and mapping  $\mathcal{C}_A$  to  $\mathcal{C}_B$ . Since there are two directions tangent to  $\mathcal{C}_B$  at  $B$  then for a given direction tangent to  $\mathcal{C}_A$  at  $A$  there are two such  $M$ -transformations (reversing the direction of the tangent to  $\mathcal{C}_A$  at  $A$  results in the same two  $M$ -transformations). Therefore, there are two such  $M$ -transformations, as claimed.  $\square$

## Theorem 55.3

**Theorem 55.3.** There exists a unique  $M$ -transformation which interchanges two given points  $A$  and  $B$  of  $\Omega$ .

**Proof.** Let  $\mathcal{C}$  be the unique circle through  $A$  and  $B$  that is orthogonal to  $\omega$  (as given by Theorem 55.2). Any  $M$ -transformation which maps point  $A$  to point  $B$  and maps point  $B$  to point  $A$  must map the circle  $\mathcal{C}$  to itself (since two points in  $\Omega$  uniquely determine a hyperbolic line; if the points are collinear with the center of  $\Omega$  then the hyperbolic line is a diameter of the unit circle, otherwise it is a segment of a circle that intersects  $\omega$  at right angles). By Corollary 55.A, by taking  $\mathcal{C} = \mathcal{C}_A = \mathcal{C}_B$ , we have that there are only two  $M$ -transformations which map  $A$  to  $B$  and  $\mathcal{C}$  to itself. The proof of Corollary 55.A shows that one of the  $M$ -transformations preserves the orientation on  $\mathcal{C}$  and the other reverses the orientation. However, the  $M$ -transformation which preserves the orientation on  $\mathcal{C}$  cannot map  $A$  to  $B$  (since the orientation of  $\mathcal{C}$  from  $A$  to  $B$  is opposite that from  $B$  to  $A$ ).

## Theorem 55.3 (continued 1)

**Theorem 55.3.** There exists a unique  $M$ -transformation which interchanges two given points  $A$  and  $B$  of  $\Omega$ .

**Proof (continued).** So the only possible  $M$ -transformation which interchanges points  $A$  and  $B$  is the one which reverses the orientation of  $\mathcal{C}$ . Let  $M'$  be the  $M$ -transformation which maps  $A$  to  $B$  and reverses the orientation of  $\mathcal{C}$ . We next show that  $M'$  maps  $B$  to  $A$ , completing the proof.

Let  $X_1$  and  $X_2$  be the points of intersection of  $\mathcal{C}$  with  $\omega$ . Let the transform of  $B$  under  $M'$  be  $A'$  (we will show that  $A' = B$ , as desired). Since  $\mathcal{C}$  and  $\omega$  are mapped by  $M'$  onto themselves, the set of two intersections  $X_1$  and  $X_2$  of  $\mathcal{C}$  and  $\omega$  is mapped onto itself. Hence either  $X_1$  is mapped to  $X_1$  and  $X_2$  is mapped to  $X_2$ , or  $X_1$  is mapped to  $X_2$  and  $X_2$  is mapped to  $X_1$ . Since  $M'$  reverses the orientation of  $\mathcal{C}$ , then we cannot have  $M'$  fixing  $X_1$  and  $X_2$ . So we must have  $X_1$  and  $X_2$  interchanged by  $M'$ .

## Theorem 55.3 (continued 2)

**Theorem 55.3.** There exists a unique  $M$ -transformation which interchanges two given points  $A$  and  $B$  of  $\Omega$ .

**Proof (continued).** Since the cross-ratio is invariant under a Möbius transformation by Theorem 53.4, then

$$(X_1, X_2; A, B) = (M'(X_1), M'(X_2); M'(A), M'(B)) = (X_2, X_1; B, A').$$

For any cross-ratio we have by Theorem 53.3 that  $(X_1, X_2; A, B) = (X_2, X_1; B, A)$ , so that we must have  $(X_2, X_1; B, A) = (X_2, X_1; B, A')$ . So, by the definition of cross-ratio, we have  $A = A'$ , as desired.  $\square$