

## Section 42. Isometries

**Note.** We now consider mappings which preserve distances.

**Definition.** An *isometry* (or “congruent transformation” or “rigid motion”) of the Gauss plane (i.e.,  $\mathbb{C}$ ) is a one to one mapping of the plane onto itself such that if  $P$  is mapped to  $P'$  and  $Q$  is mapped to  $Q'$ , the distance  $PQ$  equals the distance  $P'Q'$ , whatever the points  $P$  and  $Q$ .

**Note.** In fact, translations, rotations, and reflections are isometries. For a translation by  $b \in \mathbb{C}$ , we have the distances  $|z' - w'| = |(z + b) - (w + b)| = |z - w|$ . For rotations about the origin we have the distances

$$\begin{aligned} |z' - w'| &= |(\cos \varphi + i \sin \varphi)z - (\cos \varphi + i \sin \varphi)w| = |(\cos \varphi + i \sin \varphi)(z - w)| \\ &= |\cos \varphi + i \sin \varphi| |z - w| = |z - w|. \end{aligned}$$

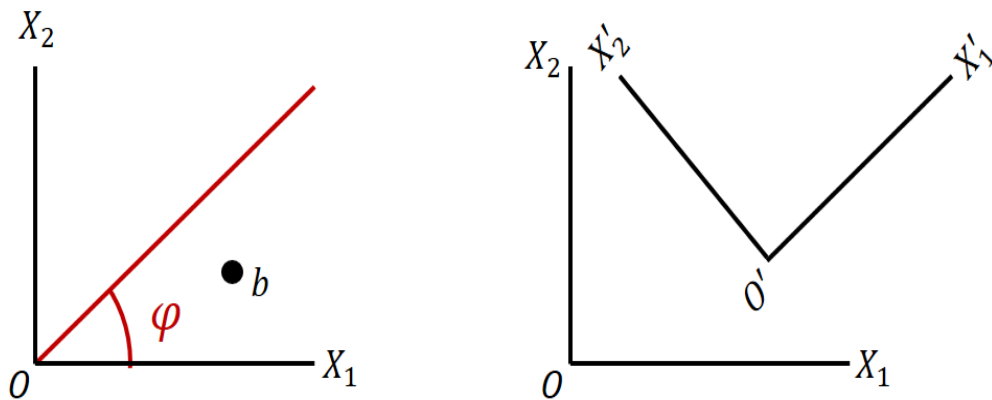
For reflection about a line through the origin, we have the distances

$$\begin{aligned} |z' - w'| &= |(\cos(2\alpha) + i \sin(2\alpha))\bar{z} - (\cos(2\alpha) + i \sin(2\alpha))\bar{w}| \\ &= |(\cos(2\alpha) + i \sin(2\alpha))(\bar{z} - \bar{w})| = |\cos(2\alpha) + i \sin(2\alpha)| |\bar{z} - \bar{w}| \\ &= |\bar{z} - \bar{w}| = \left| \overline{(\bar{z} - \bar{w})} \right| = |z - w| \end{aligned}$$

since  $|z| = |\bar{z}|$ .

**Note.** We now introduce axes to the plane. We take the  $X_1$ -axis to coincide with the real axis and the  $X_2$ -axis to coincide with the imaginary axis. We can perform a rotation and translation of these axes to get new axes,  $X'_1$  and  $X'_2$ , respectively. A given point in the plane will then have coordinates with respect to both sets of axes.

**Note.** First we rotate the axes through an angle  $\varphi$  about the origin. We then translate the rotated axes by complex number  $b$ .



Consider point  $z$  in the  $X_1X_2$ -plane (that is, we represent the point in the  $X_1, X_2$  coordinate system as  $z$ ). The representation of  $z$  with respect to the rotated axes is then given by  $z(\cos(-\varphi) + i \sin(-\varphi))$ . So point  $b$  (in the  $X_1X_2$ -plane) has become  $b(\cos(-\varphi) + i \sin(-\varphi))$ . The origin of the  $X_1X_2$ -plane is transformed to point  $b$  under the rotation and translation. So with  $O'$  as the origin of the  $X'_1X'_2$ -plane, point  $z$  has the representation  $Z'$  in the  $X'_1X'_2$  coordinate system as

$$Z' = z(\cos(-\varphi) + i \sin(-\varphi)) - b(\cos(-\varphi) + i \sin(-\varphi)).$$

If we set  $a = \cos(-\varphi) + i \sin(-\varphi)$  and  $c = -b(\cos(-\varphi) + i \sin(-\varphi))$  then  $|a| = 1$  and  $Z' = az + c$ .

**Note 42.A.** We now consider a transformation of the form  $Z' = az + c$  where  $|z| = 1$  (so here we do not concern ourselves with coordinates and new axes). This transformation is an isometry:  $|Z' - W'| = |(az + c) - (aw + c)| = |a||z - w| = |z - w|$ .

**Note 42.B.** Another transformation of interest (we give a geometric interpretation in terms of axes below) is  $Z' = a\bar{z} + c$  where  $|z| = 1$ . This is also an isometry:

$$|Z' - W'| = |(a\bar{z} + c) - (a\bar{w} + c)| = |a||\bar{z} - \bar{w}| = |a||\overline{z - w}| = |a||z - w| = |z - w|.$$

**Note.** The transformation  $Z' = az + c$  where  $|a| = 1$  “preserves the orientation” of the axes. That is, the angle from the positive  $X_1$ -axis to the positive  $X_2$ -axis is the same as the angle from the positive  $X'_1$ -axis to the positive  $X'_2$ -axis. Both angles are  $90^\circ$ . The transformation  $Z' = a\bar{z} + c$  where  $|z| = 1$  “reverses the orientation” of the axes. Under this transformation, the angle from the positive  $X'_1$ -axis to the positive  $X'_2$ -axis is  $-90^\circ$ . We’ll see in the next section that these two transformations are fundamental isometries of the (Gauss) plane.

