## Introduction to Knot Theory

Chapter 6. Geometry, Algebra, and the Alexander Polynomial 6.2. Seifert Matrices and the Alexander Polynomial—Proofs of Theorems


## Table of contents

(1) Corollary 6.2.2
(2) Corollary 6.2.4

## Corollary 6.2.2

Corollary 6.2.2. The Alexander polynomial of a knot $K$ satisfies $A_{K}(t)=t^{ \pm i} A_{K}\left(t^{-1}\right)$ for some $i \in \mathbb{Z}$.

Proof. This follows from properties of determinants. We recall some relevant properties from my online Linear Algebra (MATH 2010) notes on 4.2. The Determinant of a Square Matrix (see Theorem 4.2.A. Properties of the Determinant): For square matrix $A$ and $\operatorname{scalar} r, \operatorname{det}(A)=\operatorname{det}\left(A^{t}\right)$ (the Transpose Property) and if a single row of $A$ is multiplied by $r$ to give matrix $B$ then $\operatorname{det}(B)=r \operatorname{det}(A)$ (The Scalar Multiplication Property). Notice that the second property implies that $\operatorname{det}(r A)=r^{n} \operatorname{det}(A)$ where $A$ is $n \times n$.

## Corollary 6.2.2

Corollary 6.2.2. The Alexander polynomial of a knot $K$ satisfies $A_{K}(t)=t^{ \pm i} A_{K}\left(t^{-1}\right)$ for some $i \in \mathbb{Z}$.

Proof. This follows from properties of determinants. We recall some relevant properties from my online Linear Algebra (MATH 2010) notes on 4.2. The Determinant of a Square Matrix (see Theorem 4.2.A. Properties of the Determinant): For square matrix $A$ and $\operatorname{scalar} r, \operatorname{det}(A)=\operatorname{det}\left(A^{t}\right)$ (the Transpose Property) and if a single row of $A$ is multiplied by $r$ to give matrix $B$ then $\operatorname{det}(B)=r \operatorname{det}(A)$ (The Scalar Multiplication Property). Notice that the second property implies that $\operatorname{det}(r A)=r^{n} \operatorname{det}(A)$ where $A$ is $n \times n$.

## Corollary 6.2.2 (continued)

Corollary 6.2.2. The Alexander polynomial of a knot $K$ satisfies $A_{K}(t)=t^{ \pm i} A_{K}\left(t^{-1}\right)$ for some $i \in \mathbb{Z}$.

Proof. We have that the Alexander polynomial satisfies

$$
\begin{aligned}
A_{K}(t)= & \operatorname{det}\left(V-t V^{t}\right)=\operatorname{det}\left(\left(V-t V^{t}\right)^{t}\right) \text { by the Transpose Property } \\
= & \operatorname{det}\left(V^{t}-t V\right)=\operatorname{det}\left(t V-V^{t}\right) \text { by the Scalar Multiplication } \\
& \quad \operatorname{Property} \text { with } r=-1 \text { and } n=2 g \\
= & \operatorname{det}\left(t\left(V-t^{-1} V^{t}\right)=t^{2 g} \operatorname{det}\left(V-v^{-1} V^{t}\right)\right. \text { by the Scalar } \\
& \text { Multiplication Property with } r=t \text { and } n=2 g \\
= & t^{2 g} A+K\left(t^{-1}\right) .
\end{aligned}
$$

as claimed.

## Corollary 6.2.4

Corollary 6.2.4. If $V_{1}$ and $V_{2}$ are Seifert matrices associated with the same knot, then the polynomials $\operatorname{det}\left(V_{1}-t V_{1}^{t}\right)$ and $\operatorname{det}\left(V_{2}-t V_{2}^{t}\right) \operatorname{differ}$ by a multiple of $\pm t^{k}$.

Proof. We know that the $V_{1}$ and $V_{2}$ are $S$-equivalent by Theorem 6.2.3 So we consider the effect on $\operatorname{det}\left(V_{1}-t V_{1}^{t}\right)$ and $\operatorname{det}\left(V_{2}-t V_{2}^{t}\right)$ by the multiplication on the left by matrix $M$ and on the right by matrix $M^{t}$, where $M$ is as described in Note 6.2.A. Now $M$ is a product of elementary matrices which correspond to adding a multiple of one row to another. The determinant of such an elementary matrix is the same as the identity matrix (by, say, The Row-Addition Property of "Theorem 4.2.A. Properties of the Determinant" in my Linear Algebra [MATH 2010] notes on 4.2. The Determinant of a Square Matrix) and so is 1.

## Corollary 6.2.4

Corollary 6.2.4. If $V_{1}$ and $V_{2}$ are Seifert matrices associated with the same knot, then the polynomials $\operatorname{det}\left(V_{1}-t V_{1}^{t}\right)$ and $\operatorname{det}\left(V_{2}-t V_{2}^{t}\right) \operatorname{differ}$ by a multiple of $\pm t^{k}$.

Proof. We know that the $V_{1}$ and $V_{2}$ are $S$-equivalent by Theorem 6.2.3 So we consider the effect on $\operatorname{det}\left(V_{1}-t V_{1}^{t}\right)$ and $\operatorname{det}\left(V_{2}-t V_{2}^{t}\right)$ by the multiplication on the left by matrix $M$ and on the right by matrix $M^{t}$, where $M$ is as described in Note 6.2.A. Now $M$ is a product of elementary matrices which correspond to adding a multiple of one row to another.
The determinant of such an elementary matrix is the same as the identity matrix (by, say, The Row-Addition Property of "Theorem 4.2.A. Properties of the Determinant" in my Linear Algebra [MATH 2010] notes on 4.2. The Determinant of a Square Matrix) and so is 1.

## Corollary 6.2.4 (continued 1 )

Proof (continued). Since the determinant of a product of matrices is the product of the determinants (by "Theorem 4.4. The Multiplicative Property" in the same online notes), then $\operatorname{det}(M)=1$ and $\operatorname{det}\left(M^{t}\right)=1$ (by The Transpose Property of Theorem 4.2.A in the online notes). So the band moves has the effect:

$$
\operatorname{det}\left(M\left(V_{1}-t V_{1}^{t}\right) M^{t}\right)=\operatorname{det}(M) \operatorname{det}\left(V_{1}-t V_{1}^{t}\right) \operatorname{det}\left(M^{t}\right)=\operatorname{det}\left(V_{1}-t V_{1}^{t}\right)
$$

Now for stabilization. One step of stabilization changes Seifert matrix $V_{1}$ to


## Corollary 6.2.4 (continued 1 )

Proof (continued). Since the determinant of a product of matrices is the product of the determinants (by "Theorem 4.4. The Multiplicative Property" in the same online notes), then $\operatorname{det}(M)=1$ and $\operatorname{det}\left(M^{t}\right)=1$ (by The Transpose Property of Theorem 4.2.A in the online notes). So the band moves has the effect:

$$
\operatorname{det}\left(M\left(V_{1}-t V_{1}^{t}\right) M^{t}\right)=\operatorname{det}(M) \operatorname{det}\left(V_{1}-t V_{1}^{t}\right) \operatorname{det}\left(M^{t}\right)=\operatorname{det}\left(V_{1}-t V_{1}^{t}\right)
$$

Now for stabilization. One step of stabilization changes Seifert matrix $V_{1}$ to

$$
V_{1}^{\prime}=\left(\begin{array}{ccccc} 
& & & * & 0 \\
& V_{1} & & \vdots & \vdots \\
& & & * & 0 \\
* & \cdots & * & * & 1 \\
0 & \cdots & 0 & 0 & 0
\end{array}\right) .
$$

## Corollary 6.2.4 (continued 2)

Proof (continued). So we have


We expand along the last column (and observe that we have a $(2 g+2) \times(2 g+2)$ matrix $)$.

## Corollary 6.2.4 (continued 3 )

## Proof (continued).

$$
\operatorname{det}\left(V_{1}^{\prime}-t\left(V_{1}^{\prime}\right)^{t}\right)=(-1)^{(2 g+1)+(2 g+2)} \operatorname{det}\left(\begin{array}{cccc} 
& & & * \\
& V_{1}-t V_{1}^{t} & & \vdots \\
& & & * \\
0 & \cdots & 0 & -t
\end{array}\right)
$$

$=(-1)(-t)(-1)^{(2 g+1)+(2 g+1)} \operatorname{det}\left(V_{1}-t V_{1}^{t}\right)$ expanding along the last row $=t \operatorname{det}\left(V_{1}-t V_{1}^{t}\right)$.

So one step of stabilization affects $\operatorname{det}\left(V_{1}-t V_{1}^{t}\right)$ by a multiple of $t$.
So a sequence of band moves and stabilization will affect the determinant of $V_{1}-t V_{1}^{t}$ by some power of $t$. The claim not follows.

## Corollary 6.2.4 (continued 3 )

## Proof (continued).

$$
\begin{aligned}
& \quad \operatorname{det}\left(V_{1}^{\prime}-t\left(V_{1}^{\prime}\right)^{t}\right)=(-1)^{(2 g+1)+(2 g+2)} \operatorname{det}\left(\begin{array}{ccc} 
& & \\
& V_{1}-t V_{1}^{t} & \vdots \\
& \ldots & 0 \\
0 & \cdots & -t
\end{array}\right) \\
& =(-1)(-t)(-1)^{(2 g+1)+(2 g+1)} \operatorname{det}\left(V_{1}-t V_{1}^{t}\right) \text { expanding along the last row } \\
& =t \operatorname{det}\left(V_{1}-t V_{1}^{t}\right) .
\end{aligned}
$$

So one step of stabilization affects $\operatorname{det}\left(V_{1}-t V_{1}^{t}\right)$ by a multiple of $t$.
So a sequence of band moves and stabilization will affect the determinant of $V_{1}-t V_{1}^{t}$ by some power of $t$. The claim not follows.

