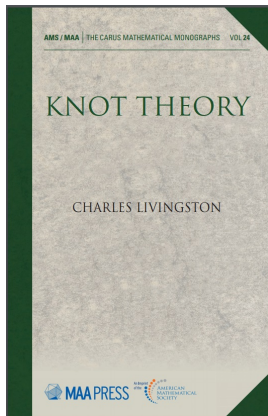


# Introduction to Knot Theory

## Chapter 8. Symmetries of Knots

### 8.4. Periodic Seifert Surfaces and Edmonds' Theorem—Proofs of Theorems



# Table of contents

- 1 Theorem 8.4.4. Riemann-Hurwitz Formula

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$$\text{genus}(F) = q(\text{genus}(G)) + (q - 1)(\Lambda - 1)/2,$$

where  $\Lambda$  is the number of points of intersection of  $F$  (or  $G$ ) with the  $z$ -axis.

**Proof.** Recall from Section 4.2 (“Classification of Surfaces”) that for polyhedral surface  $S$  which is triangulated with  $F$  triangles, with a total of  $E$  edges and  $V$  vertices in the triangulation, then the Euler characteristic is given by  $\chi(S) = F - E + V$ . So we consider triangulations of surfaces  $F$  and  $G$ .

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## Theorem 8.4.4 (continued 1)

**Proof (continued).** Since  $F$  is equivariant and admits a rotation through  $(360/q)^\circ$ , then each triangle in the triangulation of quotient surface  $G$  determines  $q$  triangles in the triangulation of surface  $F$ . Similarly, each edge of quotient surface  $G$  determines  $q$  edges on surface  $F$ . Also, the vertices of quotient  $G$  which are not on the  $z$ -axis lift to  $q$  vertices in  $F$ . But the  $\Lambda$  vertices of quotient  $G$  which are on the  $z$ -axis each lift to a single vertex in the triangulation of surface  $F$ .

Denote the number of triangles, edges, and vertices of the triangulation of surface  $F$  as  $t_F$ ,  $e_F$ , and  $v_F$ , respectively. Similar define  $t_G$ ,  $e_G$ , and  $v_G$  for surface  $G$ . By the argument above, we have  $t_F = q t_G$ ,  $e_F = q e_G$ , and  $v_F = q v_G - (q - 1)\Lambda$ . Now by definition, the genus of a connected orientable surface  $S$  is  $\text{genus}(S) = (2 - \chi(S) - B)/2$  where  $B$  is the number of boundary components of the surface. Hence,

$$\chi(F) = t_F - e_F + v_F = q t_G - q e_G + q v_G - (q - 1)\Lambda$$

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Denote the number of triangles, edges, and vertices of the triangulation of surface  $F$  as  $t_F$ ,  $e_F$ , and  $v_F$ , respectively. Similar define  $t_G$ ,  $e_G$ , and  $v_G$  for surface  $G$ . By the argument above, we have  $t_F = q t_G$ ,  $e_F = q e_G$ , and  $v_F = q v_G - (q - 1)\Lambda$ . Now by definition, the genus of a connected orientable surface  $S$  is  $\text{genus}(S) = (2 - \chi(S) - B)/2$  where  $B$  is the number of boundary components of the surface. Hence,

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## Theorem 8.4.4 (continued 2)

**Proof (continued).** Since surfaces  $F$  and  $G$  both have one boundary component by hypothesis, so

$$\begin{aligned}
 \text{genus}(F) &= \frac{2 - \chi(F) - (1)}{2} = \frac{2 - (qt_G - qe_G + qv_G - (q-1)\Lambda) - 1}{2} \\
 &= \frac{2 - q(t_G - e_G + v_G) + (q-1)\Lambda - 1}{2} \\
 &= \frac{2 - q\chi(G) - (1)}{2} + \frac{(q-1)\Lambda}{2} \\
 &= \frac{1}{2} - \frac{q\chi(G)}{2} + \left(\frac{q}{2} - \frac{q}{2}\right) + \frac{(q-1)\Lambda}{2} \\
 &= \frac{2q - q\chi(G) - q}{2} - \frac{q}{2} + \frac{1}{2} + \frac{(q-1)\Lambda}{2} \\
 &= q \frac{2 - \chi(G) - (1)}{2} + \frac{(q-1)\Lambda - (q-1)}{2} \\
 &= q(\text{genus}(G)) + \frac{(q-1)(\Lambda - 1)}{2}, \text{ as claimed. } \square
 \end{aligned}$$