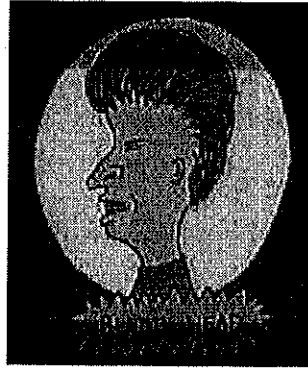


BUTT-HEAD Seminar



III. Linear Operators on Hilbert Spaces: Operators, Norms, Self Adjoint Operators

(From "Introduction to Hilbert Spaces with Applications"
by L. Debnath and R. Mikusiński.)

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3.1 LINEAR OPERATORS ON HILBERT SPACES - LINEAR OPERATORS AND OPERATOR NORMS

Definition. An *operator* is a mapping from one vector space to another (not necessarily different) vector space.

Definition. A *linear operator* L which maps one vector space to another (where the vector spaces have the same scalar field) is an operator satisfying

$$L(\alpha x + \beta y) = \alpha L(x) + \beta L(y)$$

for all scalars α and β and for all vectors x and y .

Note. We will see that in the quantum theory, observables (such as position, momentum and energy) are represented by a certain type of linear operator.

Theorem. Every linear operator on \mathbf{R}^n (or \mathbf{C}^n) is represented by an $n \times n$ real (or complex) matrix.

Proof. Let A be a linear operator and \mathbf{C}^n have “standard” orthonormal basis $\{e_1, e_2, \dots, e_n\}$. Then for $x = \sum_{j=1}^n a_j e_j \in \mathbf{C}^n$, we have

$$Ax = A\left(\sum_{j=1}^n a_j e_j\right) = \sum_{j=1}^n a_j A(e_j).$$

Therefore

$$(Ax, e_i) = \left(\sum_{j=1}^n a_j Ae_j, e_i\right) = \sum_{j=1}^n a_j (Ae_j, e_i) = \sum_{j=1}^n a_j a_{i,j}$$

where $a_{i,j} = (Ae_j, e_i)$. Therefore A can be represented by the $n \times n$ matrix $(a_{i,j})$. ■

Example. Consider the vector space

$$C_1([a, b]) = \{f : [a, b] \rightarrow \mathbf{C} \mid f' \text{ is continuous}\}.$$

Then $C_1([a, b])$ is a subspace of $L^2([a, b])$ and the operator D defined as

$$D(f(t)) = \frac{d}{dt}[f(t)] = f'(t)$$

is a linear operator (in fact, $D : C_1([a, b]) \rightarrow C_0([a, b])$ where $C_0([a, b])$ is the vector space of all continuous functions on $[a, b]$). D is called the *differential operator*.

Example. Let $z \in C_0([a, b])$ and define operator A on $L^2([a, b])$ by

$$A(x(t)) = z(t)x(t).$$

A is called a *multiplication operator*.

Definition. An operator on a vector space V is *bounded* if there exists a nonnegative real K such that $\|Ax\| \leq K\|x\|$ for all $x \in V$. The *norm* of a bounded linear operator is the “smallest” such value K , or equivalently $\|A\| = \sup_{\|x\|=1} \|Ax\|$.

Example. The identity operator \mathcal{I} on a vector space V is defined as $\mathcal{I}(x) = x$ for all $x \in V$. Notice that \mathcal{I} is bounded and $\|\mathcal{I}\| = 1$.

Note. A multiplier operator A is bounded:

$$\begin{aligned}
 \|A\|^2 &= \sup_{\|x\|=1} \|Ax\|^2 = \int_a^b |A(x(t))|^2 dt = \int_a^b |z(t)x(t)|^2 dt \\
 &= \int_a^b |z(t)|^2 |x(t)|^2 dt \leq \max_{t \in [a,b]} |z(t)|^2 \int_a^b |x(t)|^2 dt \\
 &= \left(\max_{t \in [a,b]} |z(t)|^2 \right) \|x\|^2.
 \end{aligned}$$

Notice that if $z(t) = K \in \mathbf{C}$ then $\|A\| = |K|$.

Note. The differential operator D is not bounded. Consider the sequence of functions $f_n(t) = \sin(nt)$ for $n = 1, 2, 3, \dots$, as elements of $L^2([-\pi, \pi])$. Then

$$\|f_n\| = \sqrt{\int_{-\pi}^{\pi} (\sin(nt))^2 dt} = \sqrt{\pi}$$

and

$$\|D(f_n)\| = \sqrt{\int_{-\pi}^{\pi} (n \cos(nt))^2 dt} = n\sqrt{\pi}.$$

Therefore $\|D(f_n)\| = n\|f_n\|$ and we see that $\sup_{\|x\|=1} \|D(x)\|$

can be made arbitrarily large by taking $x_n = \frac{f_n}{\sqrt{\pi}} =$

$\frac{\sin(nt)}{\sqrt{\pi}}$ (then $\|x_n\| = 1$ and $\|D(x_n)\| = n$, therefore

$\sup_{\|x_n\|=1} \|D(x)\| = \infty$).

Definition. The *product* of operators A and B on vector space V is defined as $AB(x) = A(Bx)$ for all $x \in V$. If $AB = BA$ then A and B are *commuting operators*.

Example. The differential operator $D = \frac{d}{dt}$ and the multiplier operator $A(x(t)) = tx(t)$ do not commute.

Example. The identity operator commutes with all operators.

Theorem. The product AB of bounded linear operators A and B is a bounded linear operator and $\|AB\| \leq \|A\| \|B\|$.

Theorem. A bounded linear operator on a separable infinite dimensional Hilbert space can be represented by an infinite matrix.

Example. The operator $Ax = \alpha x$ where α is a fixed scalar and $x \in l^2$ is represented by the infinite matrix

$$\begin{bmatrix} \alpha & 0 & 0 & \dots \\ 0 & \alpha & 0 & \dots \\ 0 & 0 & \alpha & \dots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix}.$$

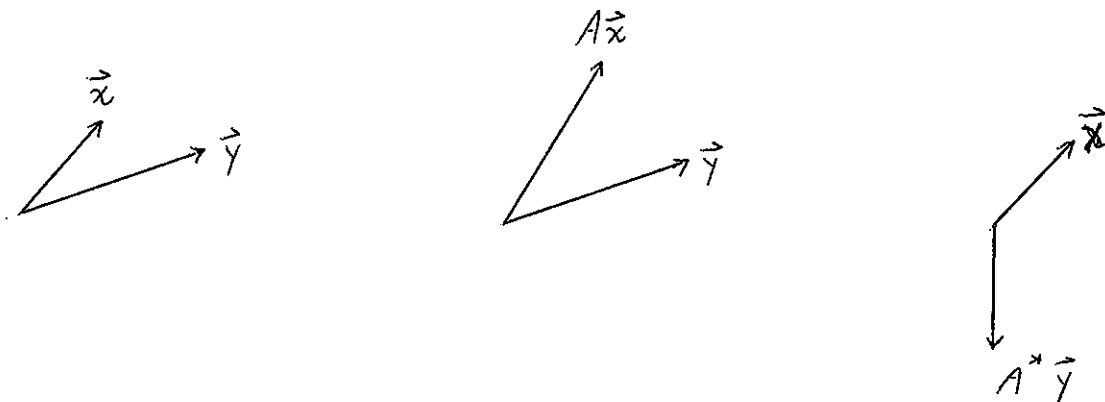
3.2 LINEAR OPERATORS ON HILBERT SPACES - ADJOINT AND SELF-ADJOINT OPERATORS

Definition. Let A be a bounded linear operator on a Hilbert space H . The operator $A^* : H \rightarrow H$ defined by

$$(Ax, y) = (x, A^*y) \text{ for all } x, y \in H$$

is the *adjoint operator* of A .

Note. In \mathbf{R}^2 , this implies:



$$Ax \cdot y = x \cdot A^*y$$

Theorem. Properties of Adjoint.

1. $(A + B)^* = A^* + B^*$

2. $(\alpha A)^* = \bar{\alpha}A^*$

3. $(A^*)^* = A$

4. $\mathcal{I}^* = \mathcal{I}$

5. $(AB)^* = B^*A^*$

Theorem. Suppose A is a bounded linear operator.

Then A^* is bounded and $\|A\| = \|A^*\|$ and $\|A^*A\| = \|A\|^2$. (Notice that in general $\|AB\| \leq \|A\|\|B\|$.)

Definition. If $A = A^*$ then A is a *self adjoint* (or *Hermetian*) operator.

Example. Let A be the operator on $L^2([a, b])$ defined by

$$A(x(t)) = tx(t).$$

Then A is self-adjoint since

$$(Ax, y) = \int_a^b tx(t)\overline{y(t)} dt = \int_a^b x(t)\overline{ty(t)} dt = (x, Ay).$$

Example/Theorem. If A is an operator on \mathbf{C}^n , then A is represented by an $n \times n$ matrix $A = (a_{i,j})$ (as above) and A^* is represented by the matrix $A^* = (\overline{a_{j,i}})$.

Proof. Let $\{e_1, e_2, \dots, e_n\}$ be the standard orthonormal basis for \mathbf{C}^n (i.e., e_i has i th entry 1 and all other entries 0). Suppose A^* is represented by $(b_{i,j})$. Then we have

$$a_{i,j} = (Ae_j, e_i) = (e_j, A^*e_i) = \overline{(A^*e_j, e_i)} = \overline{b_{j,i}}.$$

Therefore $A^* = (b_{i,j}) = (\overline{a_{j,i}})$. ■

Note. If A is a self-adjoint operator on \mathbf{C}^n and A is represented by the $n \times n$ matrix $A = (a_{i,j})$, then A^* is represented by an $n \times n$ matrix, the (i, j) entry of which is $\overline{a_{j,i}}$. So $a_{i,j} = \overline{a_{j,i}}$ and A equals its “conjugate transpose.”

Note. The previous result holds in separable Hilbert spaces as well. That is, if A is a bounded self-adjoint operator on a separable (infinite dimensional) Hilbert space and A is represented by the infinite matrix $(a_{i,j})$, then A^* is represented by $(\overline{a_{j,i}})$ and we have $a_{i,j} = \overline{a_{j,i}}$.

Theorem. Let A be a bounded operator on a Hilbert space. Then A^*A and $A + A^*$ are self-adjoint.

Theorem. The product of two self-adjoint operators is self-adjoint if and only if the operators commute.

Proof. Let A and B be self-adjoint. Then

$$(ABx, y) = (Bx, A^*y) = (x, B^*A^*y) = (x, B Ay).$$

So if $AB = BA$ then AB is self-adjoint. Conversely, if AB is self-adjoint, then $(AB)^* = AB$ and from the above, $(AB)^* = BA$, therefore $AB = BA$. ■

3.3 LINEAR OPERATORS ON HILBERT SPACES - INVERSES AND UNITARY OPERATORS

Definition. Let A be an operator with range $\mathcal{R}(A)$. An operator B is the *inverse* of A if $ABx = x$ for all $x \in \mathcal{R}(A)$ and $BAx = x$ for all $x \in \mathcal{D}(A)$ where $\mathcal{D}(A)$ is the domain of A . Operator A is said to be invertible and B is denoted as A^{-1} .

Some Properties of A^{-1}

1. If A is linear, then A^{-1} is linear.
2. A is invertible if and only if $Ax = 0$ implies $x = 0$.
3. If A is invertible and x_1, x_2, \dots, x_n are linearly independent, then Ax_1, Ax_2, \dots, Ax_n are linearly independent.
4. If A and B are invertible, then AB is invertible and $(AB)^{-1} = B^{-1}A^{-1}$.

Definition. A bounded operator T on a Hilbert space is *unitary* if $T^*T = TT^* = \mathcal{I}$. That is, T is unitary if and only if $T^{-1} = T^*$.

Example. Define T on $L^2([0, 1])$ as

$$T(x(t)) = x(1 - t).$$

Then

$$T(T(x(t))) = T(x(1 - t)) = x(1 - (1 - t)) = x(t)$$

and $T = T^{-1}$. Also

$$\begin{aligned}(Tx, y) &= \int_0^1 x(1 - t)y(t) dt = - \int_1^0 x(u)y(1 - u) du \\ &= \int_0^1 x(u)y(1 - u) du = (x, Ty)\end{aligned}$$

and so $T = T^*$. Therefore, $T^* = T^{-1}$ and T is unitary.

Definition. Let S be a non-empty subspace of a Hilbert space H . An element $x \in H$ is *orthogonal* to S , denoted $x \perp S$, if $(x, y) = 0$ for every $y \in S$. The set of all elements of H orthogonal to S , denoted S^\perp , is the *orthogonal complement* of S .

Example. In \mathbf{C}^3 , with $S = \{(z, 0, 0) \mid z \in \mathbf{C}\}$ (clearly a subspace), $S^\perp = \{(0, z_1, z_2) \mid z_1, z_2 \in \mathbf{C}\}$.

Definition. Let S be (topologically) closed subspace of a Hilbert space H . The operator P defined as

$$P(x) = y \text{ for } x = y + z, y \in S \text{ and } z \in S^\perp$$

is the *projection operator* onto S . The vector y is the *projection of x onto S* .

Example. Let S be a closed subspace of a Hilbert space H and let $\{e_1, e_2, \dots\}$ be an orthonormal basis of S . Then the projection operator P onto S is defined by

$$P(x) = \sum_{n=1}^{\infty} (x, e_n) e_n.$$

In particular, if S is of dimension 1 (of special interest in quantum mechanics), then for $v \in S$ where $\|v\| = 1$, we have $P(x) = (x, v)v$.

3.4
~~3.3~~ LINEAR OPERATORS ON HILBERT
SPACES - EIGENVALUES AND
EIGENVECTORS

Definition. Let A be an operator on a complex vector space E . A complex number λ is an *eigenvalue* of A if there is a non-zero vector $u \in E$ such that $Au = \lambda u$. A vector satisfying this condition is an *eigenvector* of A corresponding to eigenvalue λ (in a function space, an eigenvector is also called an *eigenfunction*).

Definition. Let A be an operator on a normed space E . The operator

$$A_\lambda = (A - \lambda I)^{-1}$$

is called the *resolvent* of A . The values of λ for which A_λ is defined on the whole space E and is bounded are called the *regular points* of A . The set of all λ s which are not regular is called the *spectrum* of A .

The set of all eigenvalues (which are a subset of the spectrum) is called the *point spectrum*. The remaining part of the spectrum (that is, that set of all λ s for which A_λ exists but is unbounded) is called the *continuous spectrum*.

Theorem. The collection of all eigenvectors corresponding to one particular eigenvalue of an operator is a vector space.

Definition. The set of all eigenvectors corresponding to one particular eigenvalue λ is called the *eigenspace* of λ . The dimension of that space is called the *multiplicity* of λ (this is consistent with the finite dimensional idea where the multiplicity of an eigenvalue of a matrix corresponds to its multiplicity as a zero of the equation $A - \lambda I = 0$).

Theorem. All eigenvalues of a self-adjoint operator on a Hilbert space are real.

Proof. Let λ be an eigenvalue of a self-adjoint operator A , and let u be an eigenvector of λ , $u \neq 0$. Then

$$\begin{aligned}\lambda(u, u) &= (\lambda u, u) = (Au, u) \\ &= (u, Au) = (u, \lambda u) = \bar{\lambda}(u, u).\end{aligned}$$

Since $(u, u) \geq 0$, we have $\lambda = \bar{\lambda}$, and therefore, λ is real. ■

Theorem. Eigenvectors corresponding to distinct eigenvalues of a self-adjoint or unitary operator on a Hilbert space are orthogonal.

Definition. An operator A in a Hilbert space H is *compact* (or sometimes called *completely continuous*) if for every bounded sequence $\{x_n\}$ in H , the sequence $\{Ax_n\}$ contains a convergent subsequence.

Note. Every compact operator is bounded, but not every bounded operator is compact (the identity operator \mathcal{I} is bounded, but not compact... consider the standard orthonormal basis in l^2).

Theorem. The Spectral Theorem for Self-Adjoint Compact Operators.

Let A be a self-adjoint compact operator on an infinite dimensional Hilbert space H . Then there exists an orthonormal basis of H , $\{v_n\}$, consisting of eigenvectors of A . Moreover, for every $x \in H$,

$$Ax = \sum_{n=1}^{\infty} \lambda_n(x, v_n)v_n,$$

where λ_n is the eigenvalue corresponding to v_n .

Theorem. For any two commuting self-adjoint compact operators A and B on a Hilbert space H , there exists an orthonormal basis of H consisting of vectors which are eigenvalues of both A and B .

NOW THAT WE HAVE DEVELOPED THE
MATHEMATICAL BACKGROUND, WE
ARE READY FOR THE REAL REASON
WE ARE ALL HERE...

THE APPLICATIONS OF THIS STUFF
TO QUANTUM MECHANICS!!!

[Gardner exit stage right. Shanks enter stage left.]

APPENDIX A - Unitary Operators

Recall. A bounded operator T is *unitary* if and only if T is invertible and $T^{-1} = T^*$.

Definition. A bounded operator T is *isometric* if it preserves lengths: $\|Tx\| = \|x\|$ for all x .

Theorem. A unitary operator is isometric.

Proof.

$$\begin{aligned}\|Tx\| &= (Tx, Tx) = (x, T^*Tx) \\ &= (x, T^{-1}Tx) = (x, x) = \|x\|.\end{aligned}$$

■

Theorem. A unitary operator “preserves angles.”

That is, $(x, y) = (Tx, Ty)$.

Proof.

$$(x, y) = (x, \mathcal{I}y) = (x, T^*Ty) = (Tx, Ty).$$

■